

Neuromechanics and Spinal Cord: Muscle and Motor Unit Redundancy

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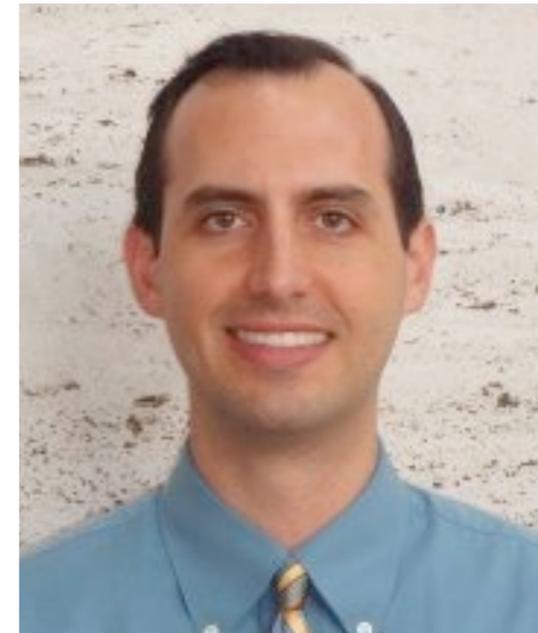


AMPL

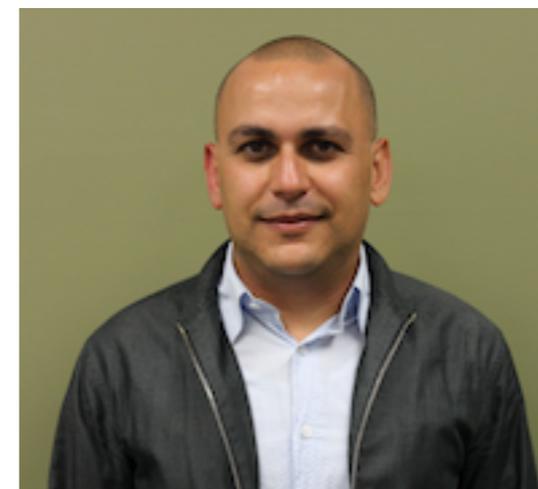
**University of Southern California
Division of Biokinesiology & Physical Therapy**



Louise Cosand



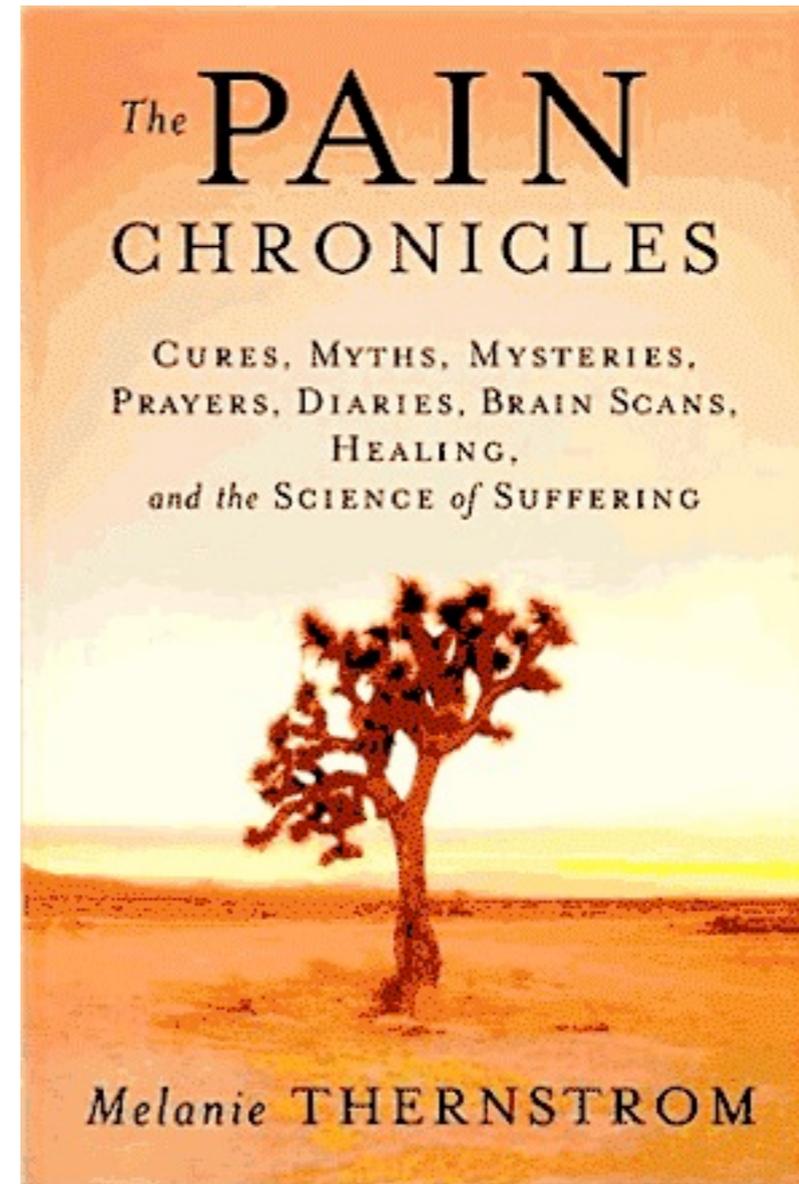
Dan Kirages, DPT



Moheb Yani

- **Biomechanics to Brain Pain**
- **Muscle Redundancy**
- **Motor Unit Redundancy**
- **Think computation, act experimentation**

Biomechanics to Brain Pain



© Farrar, Straus and Giroux

Chronic pain: pain that extends beyond the expected period of healing¹

¹Turk and Okifuji, 2001

My Ph.D. training was interdisciplinary



Tony Bloch, Ph.D.
Applied Mathematics



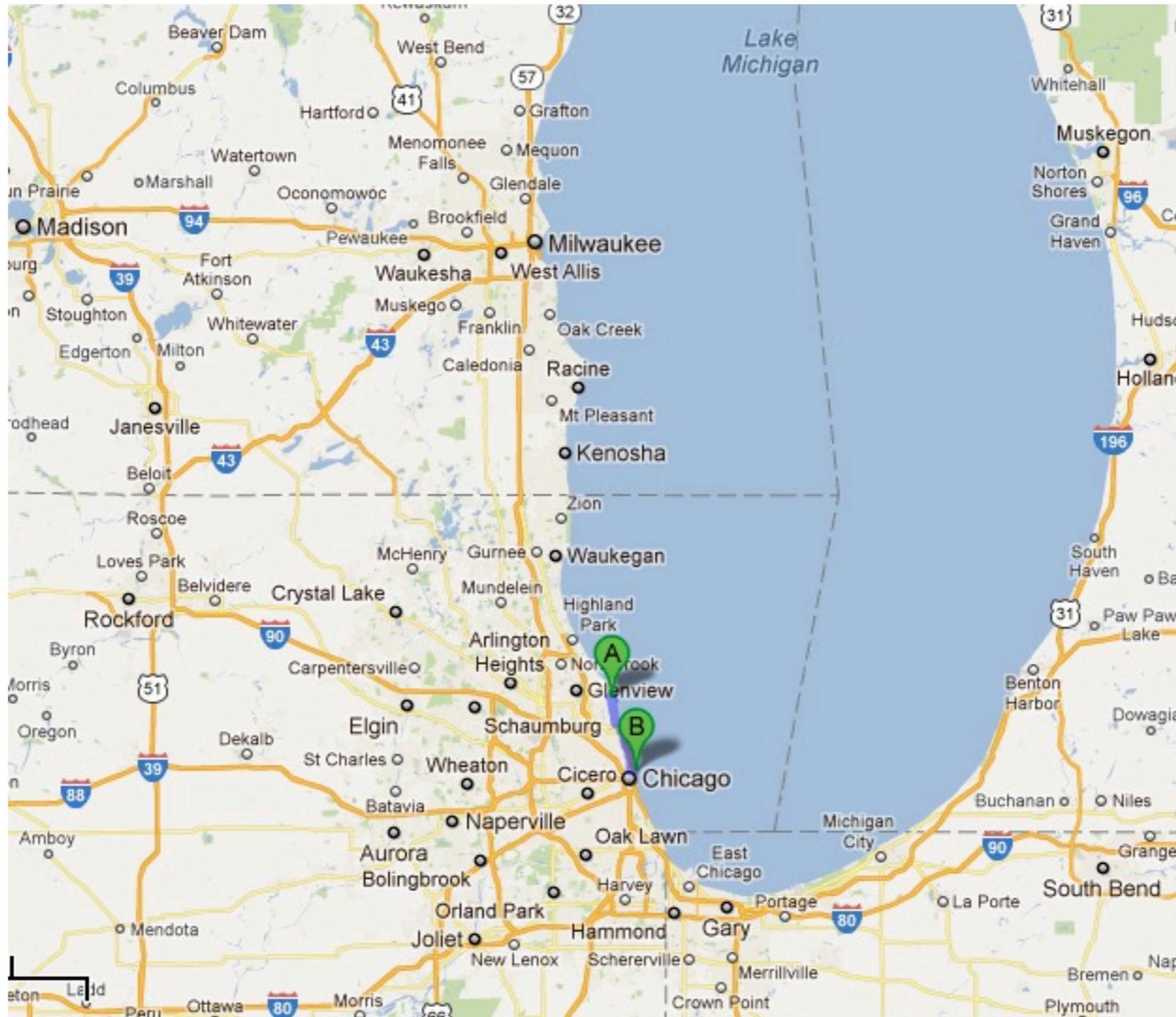
Art Kuo, Ph.D.
Biomechanics



Zev Rymer, M.D. Ph.D.
Neurophysiology

Biomechanics to Brain Pain

Cycling + Stress = CP/CPPS?



Chronic prostatitis/chronic pelvic pain syndrome (CP/CPPS) is a clinical condition presenting as **chronic pelvic pain for 3 months** within a 6-month period, with a variable degree of **urinary and sexual dysfunction** in the **absence of any identifiable pathology**.¹

- Prevalence: 6 - 12% (Most frequent urological diagnosis for men under 50).²
- Virulence: Accounts for 8% of urological visits and 1% of all primary care visits. QOL scores lower than CHF, diabetes, and Crohn's disease.²
- Cost: \$6,500 per patient per year.²

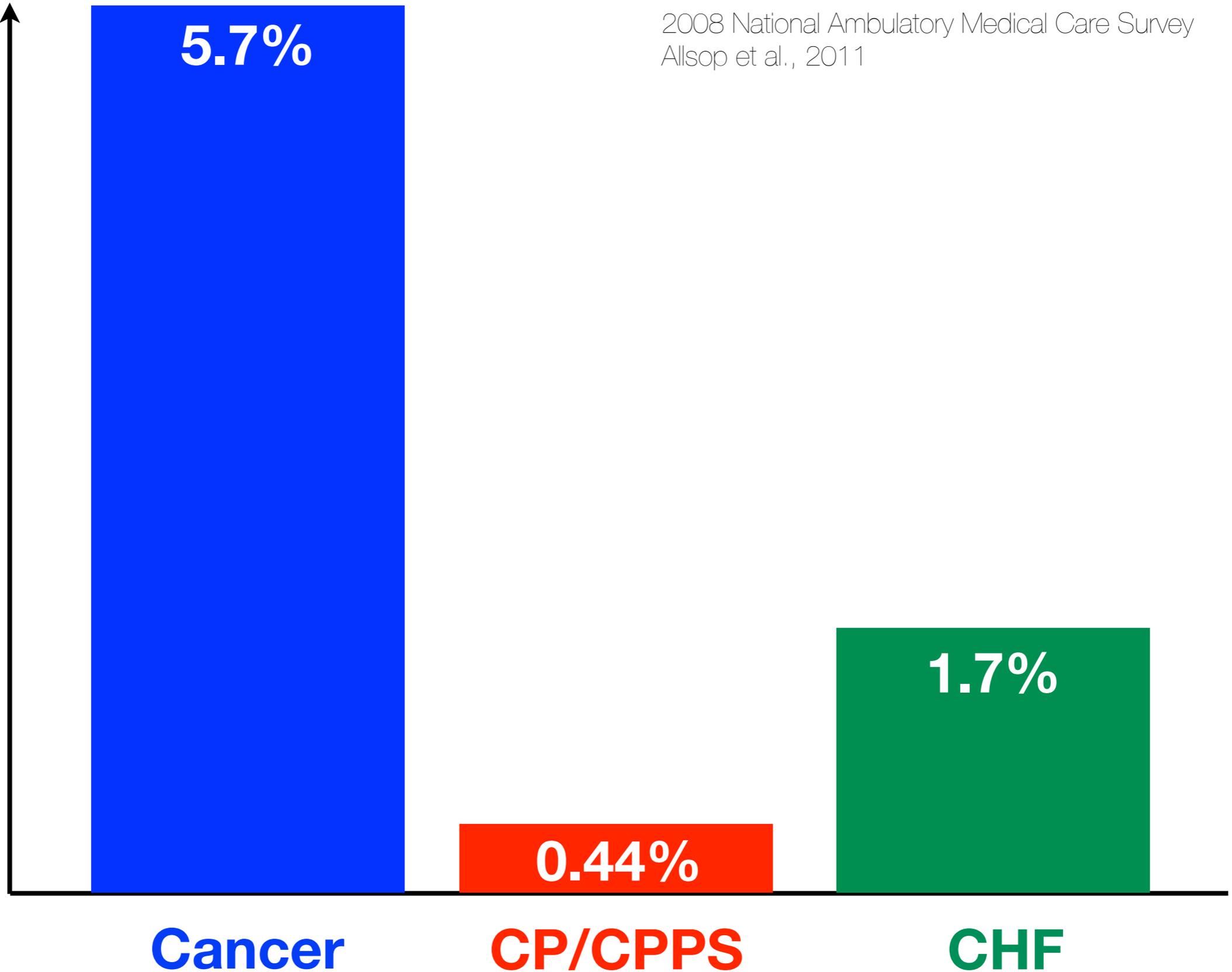
1. Krieger et al., 1999

2. Allsop et al., 2011

Biomechanics to Brain Pain

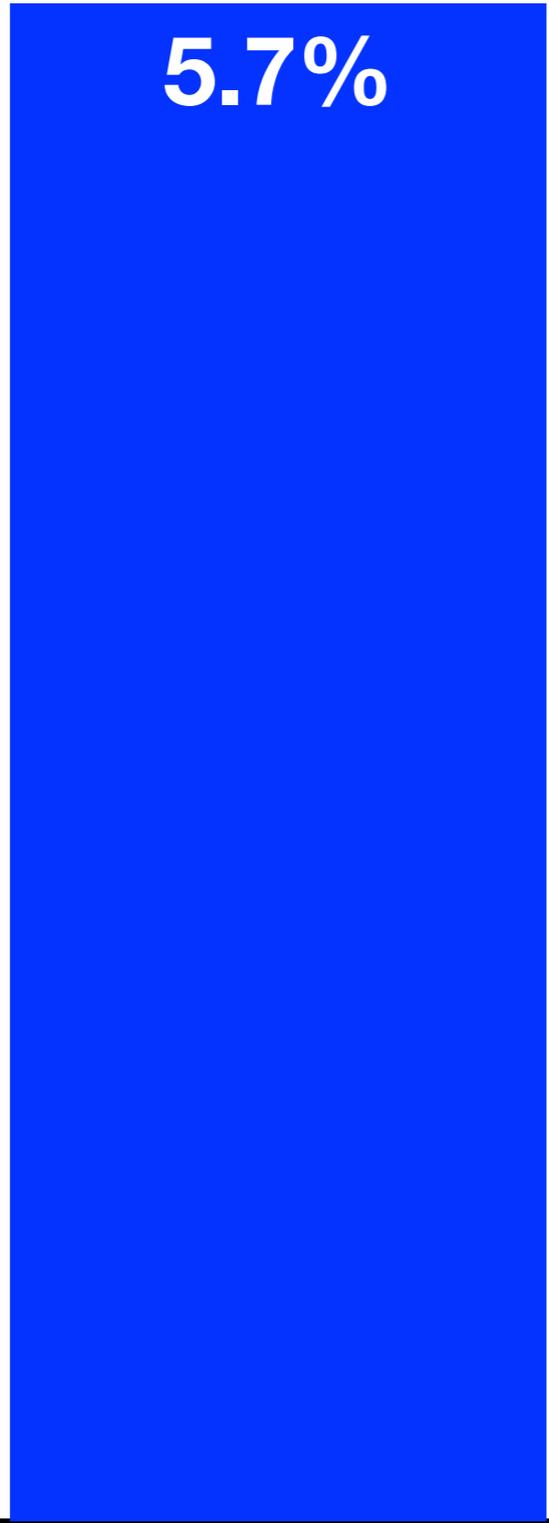
**% office visits
with condition
present**

2008 National Ambulatory Medical Care Survey
Allsop et al., 2011

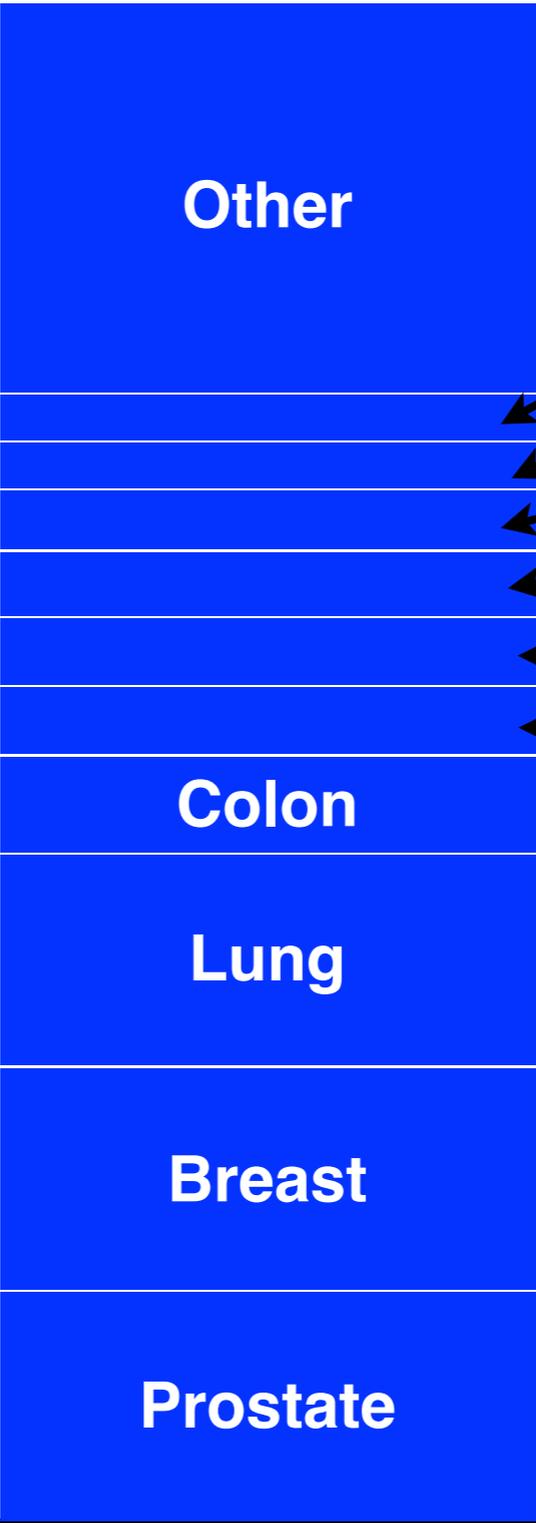


Biomechanics to Brain Pain

% office visits with condition present



Cancer



By type



CP/CPSPS

- Uterine corpus
- Thyroid
- Kidney & renal pelvis
- Non-Hodgkin lymphoma
- Urinary bladder
- Melanoma-skin

Current (conservative) Treatment Options

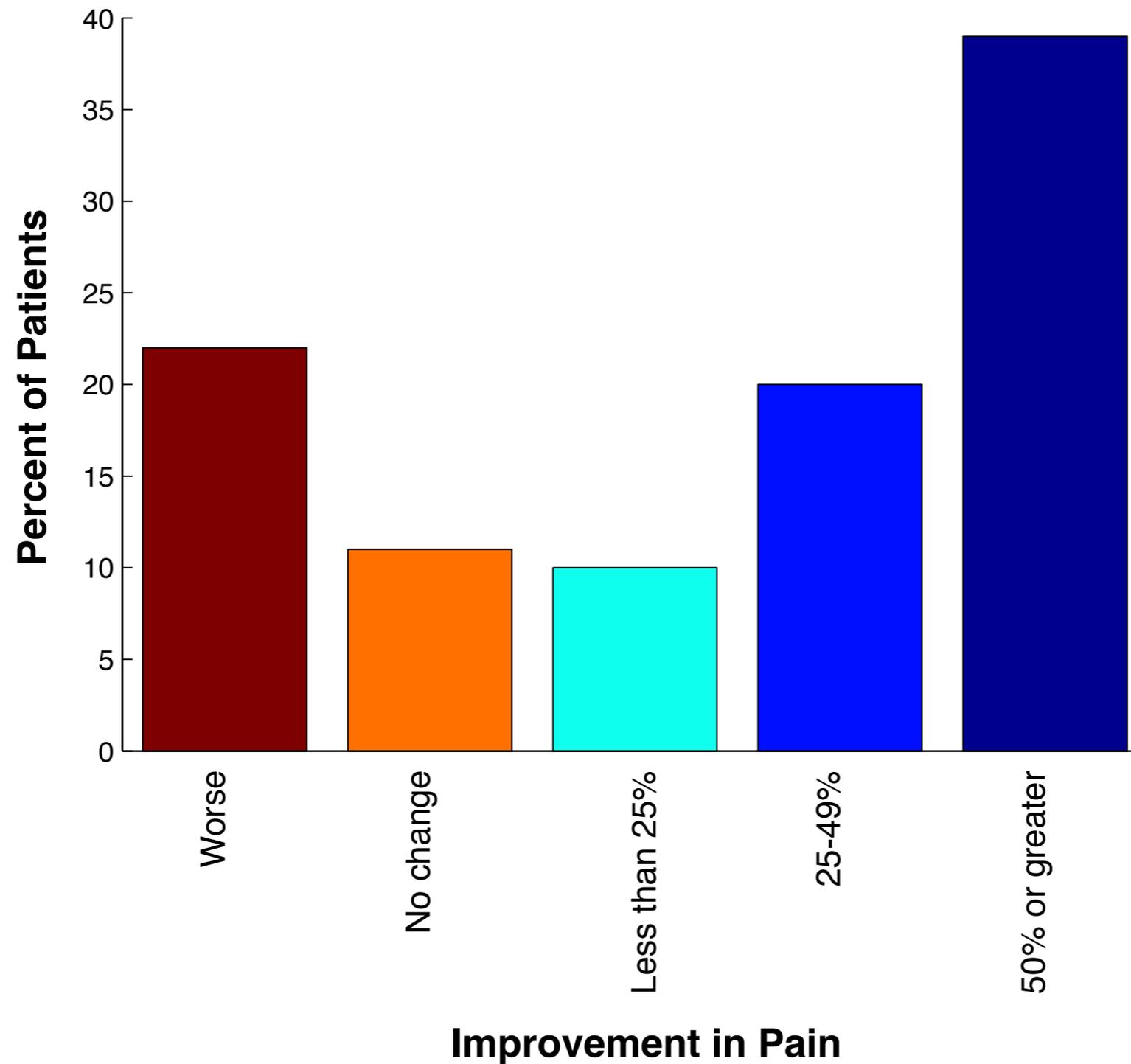
- Long (3 months+) course of antibiotics.¹
- Combination of physical therapy and relaxation techniques.²
- Aerobic exercise.³

1. Allsop et al., 2011

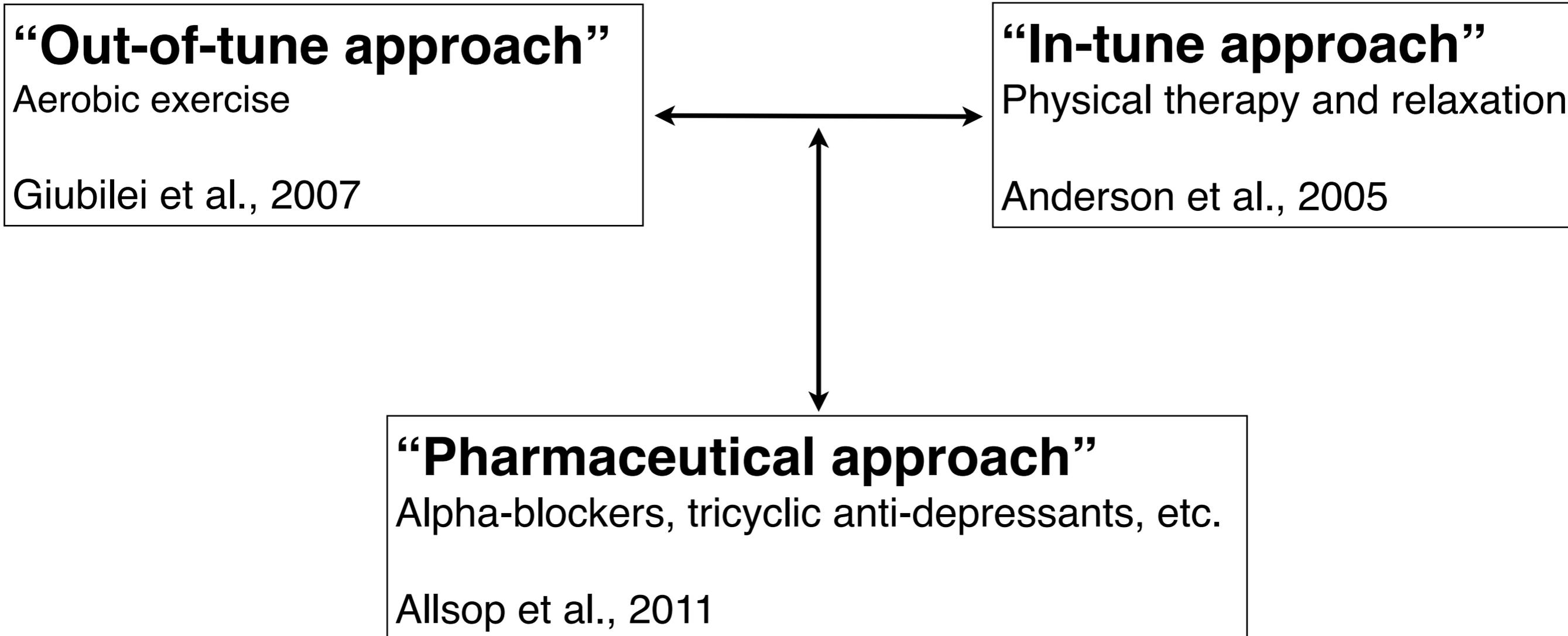
2. Anderson et al., 2005

3. Giubilei 2007

Problem with current treatments



Several approaches, little objective plan



Biomechanics to Brain Pain



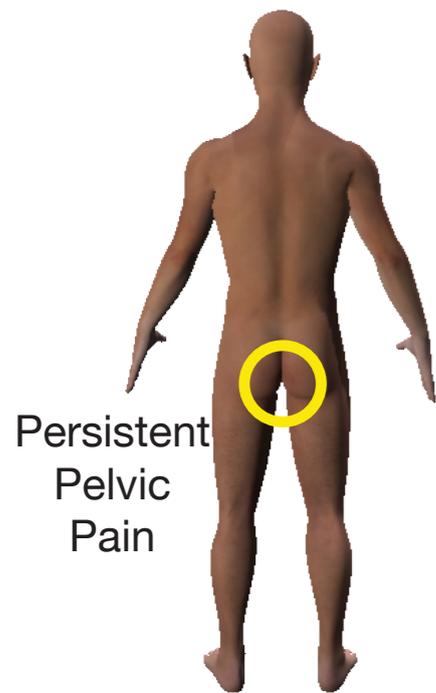
Biomechanics to Brain Pain



Central question in CP/CPPS research

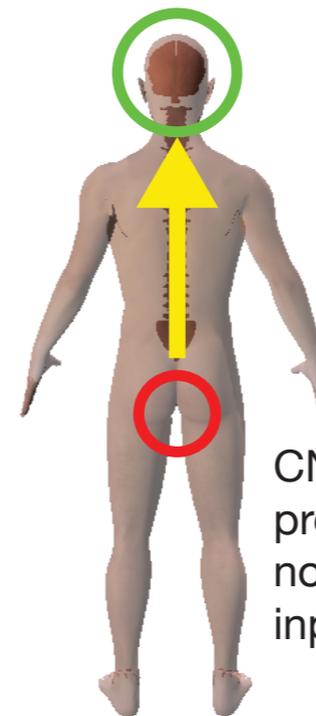
A

CP/CPPS
Phenotype

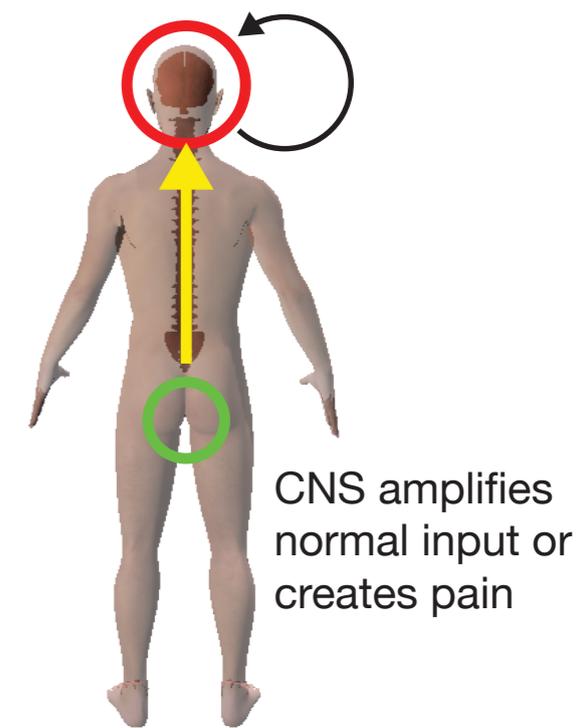


End-organ disease
and/or
Central pain syndrome?

End-organ disease

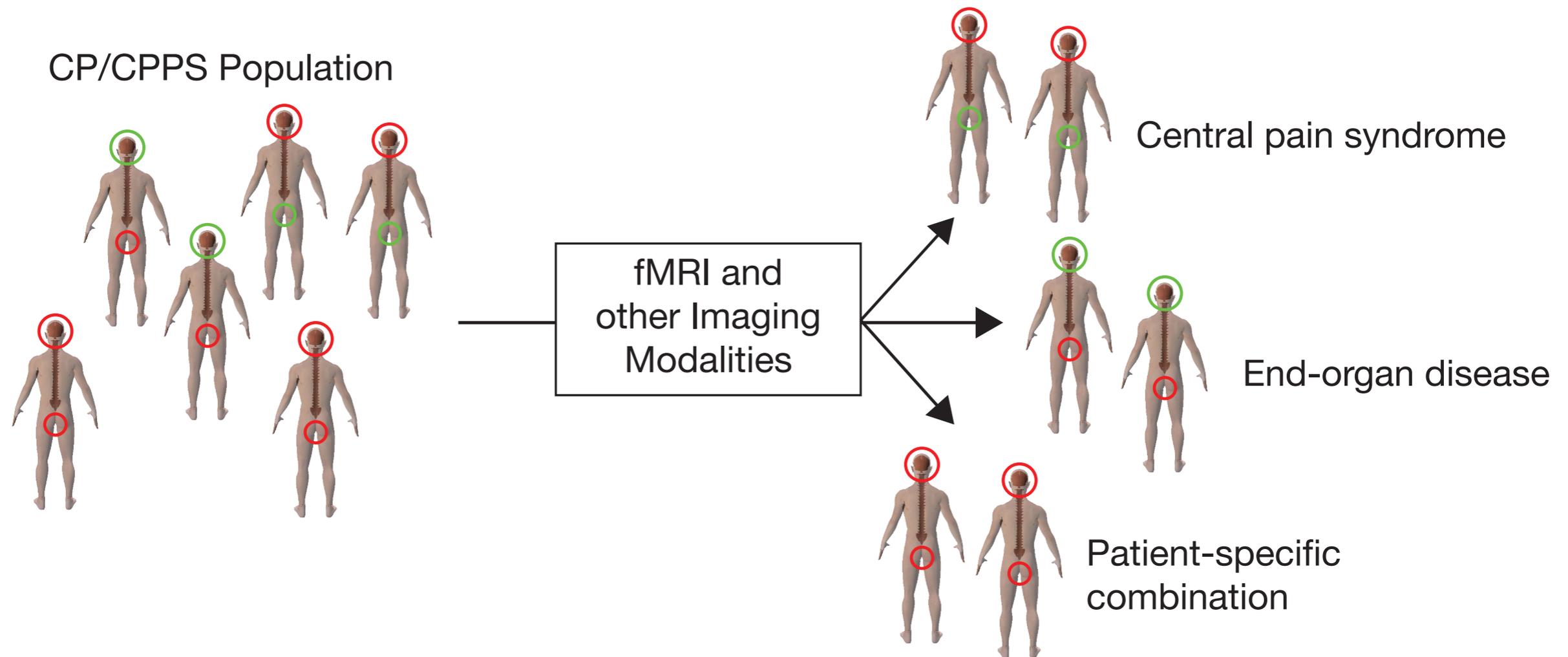


Central pain syndrome



Potential CP/CPPS patient stratification

B



PT targets soft tissues, nerves, and muscles, including neuromuscular education



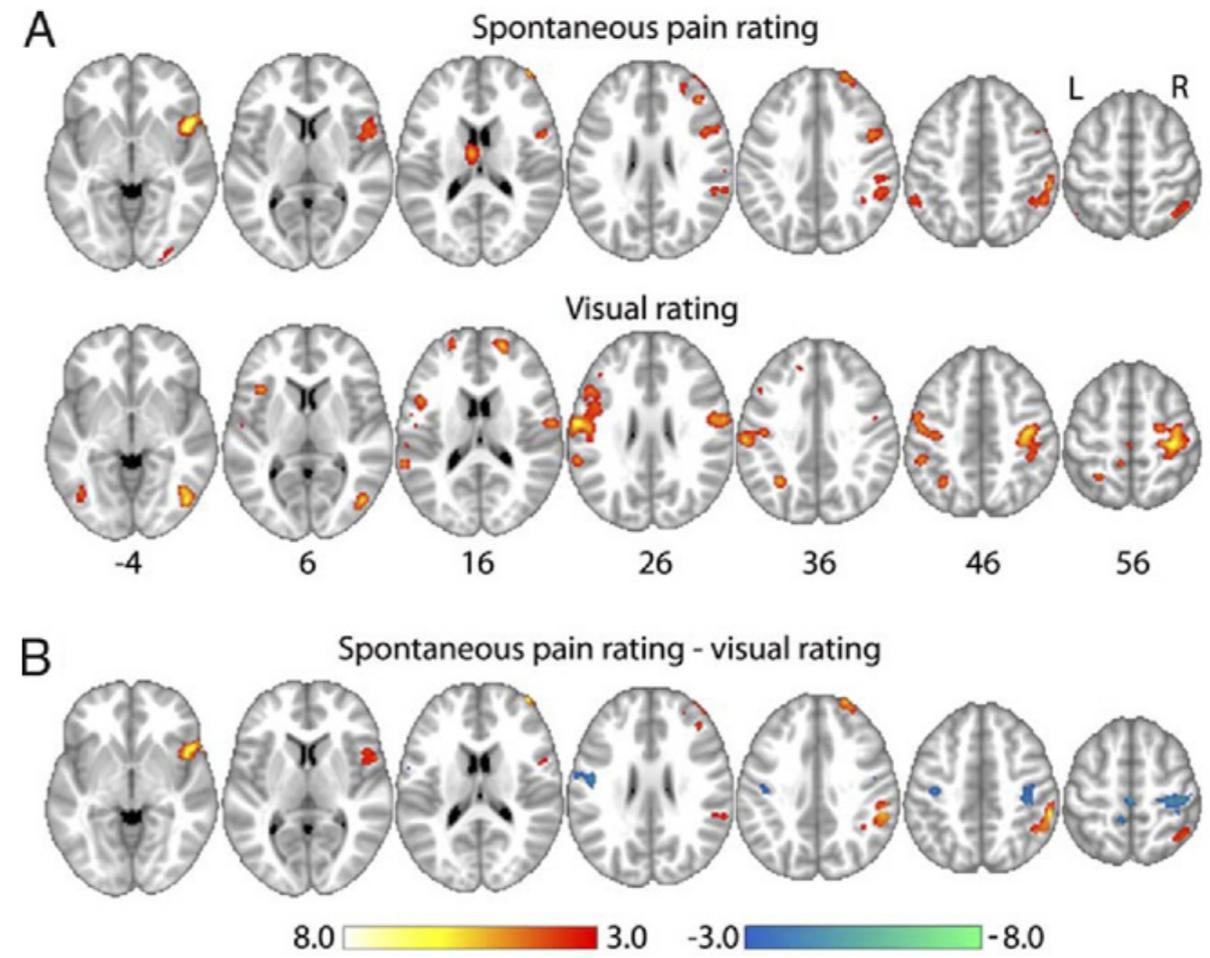
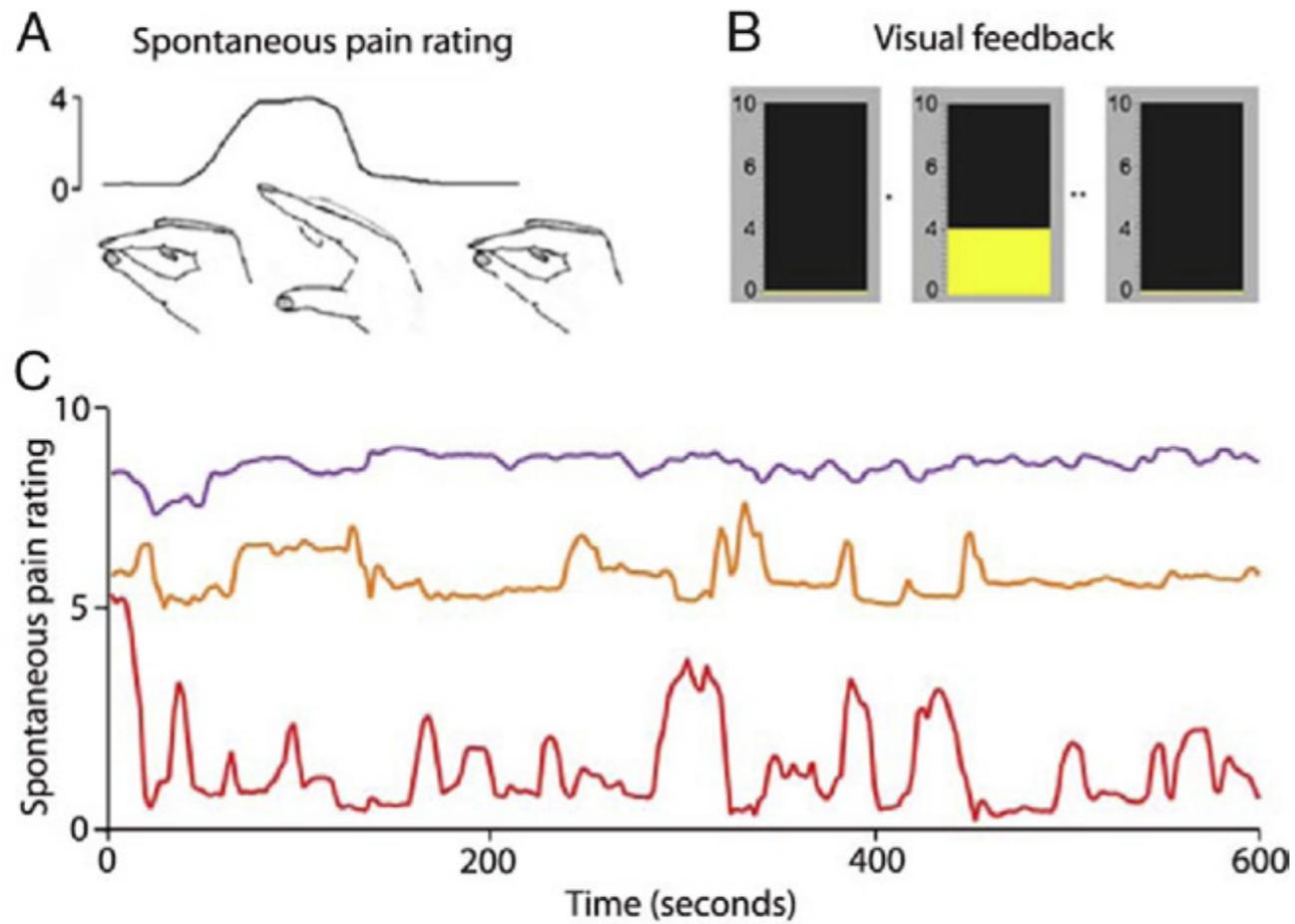
Our fMRI/PT approach



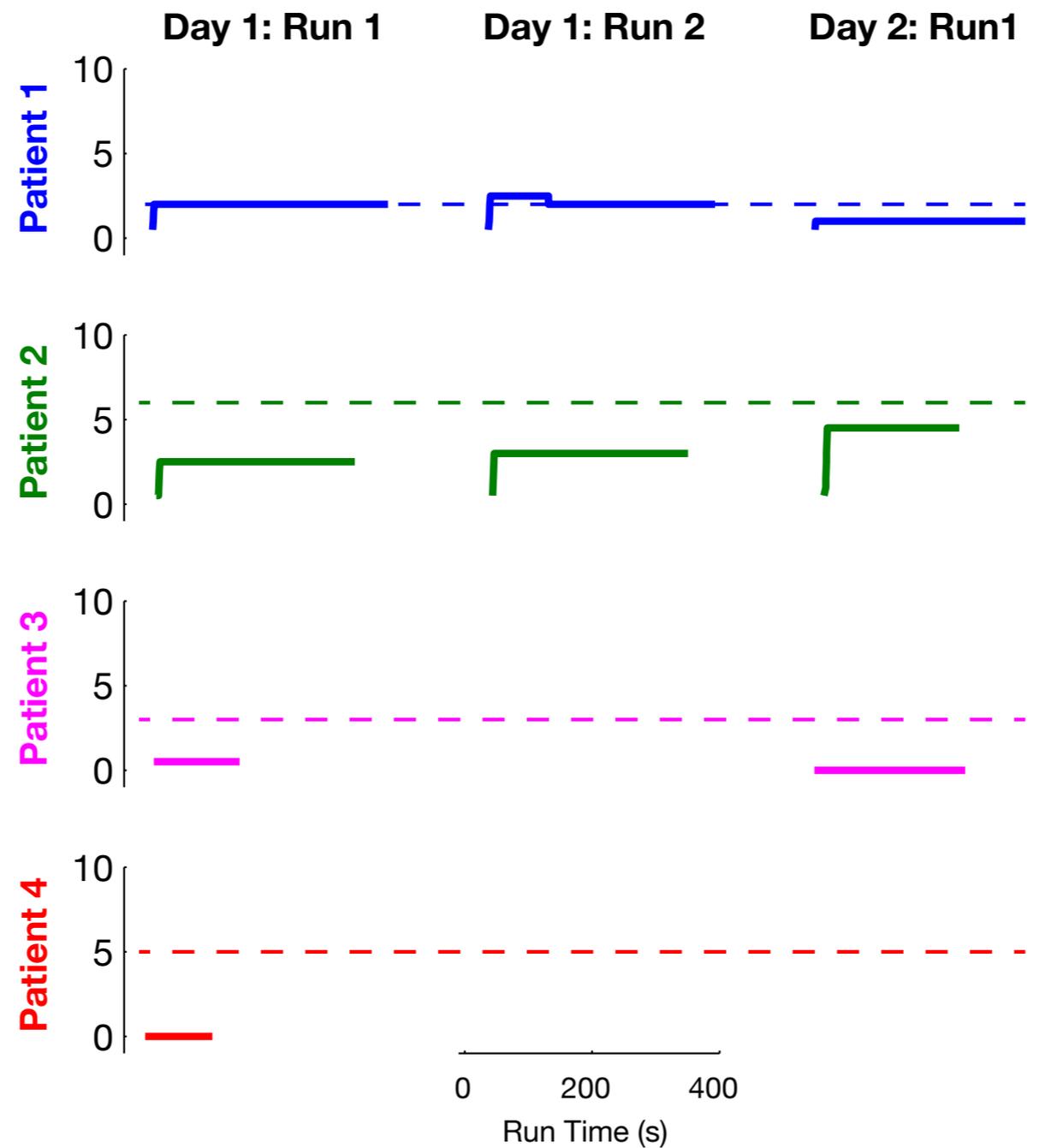
Our fMRI/PT approach



Biomechanics to Brain Pain

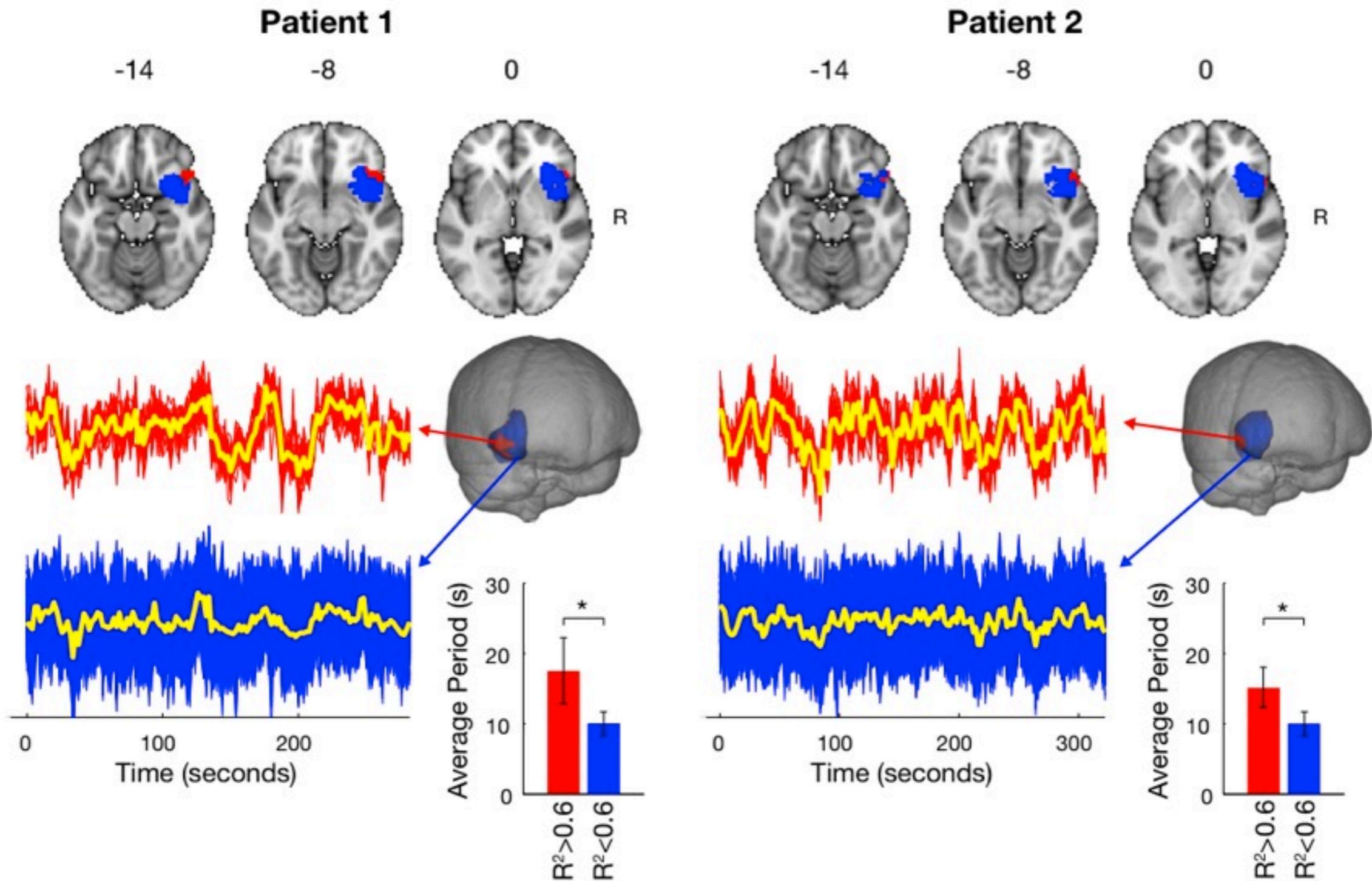


No fluctuations in conscious pain



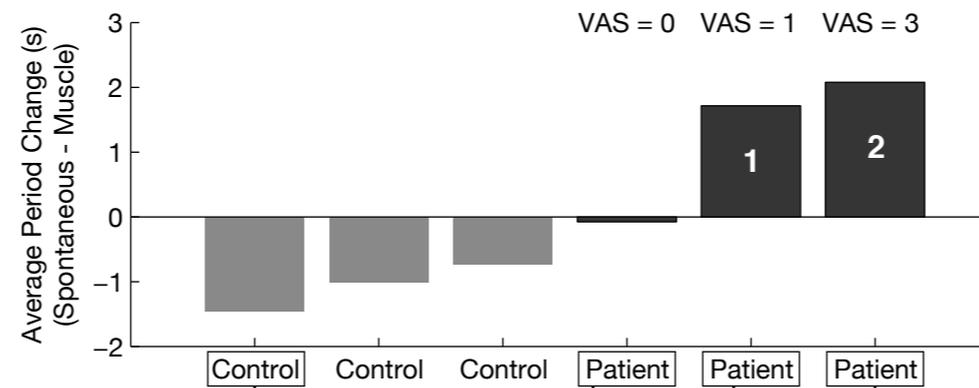
- - - - NIH-CPSI Q4: Which number best describes your AVERAGE pain or discomfort on the days you had it, over the last week?

Spontaneous low-frequency BOLD fluctuations

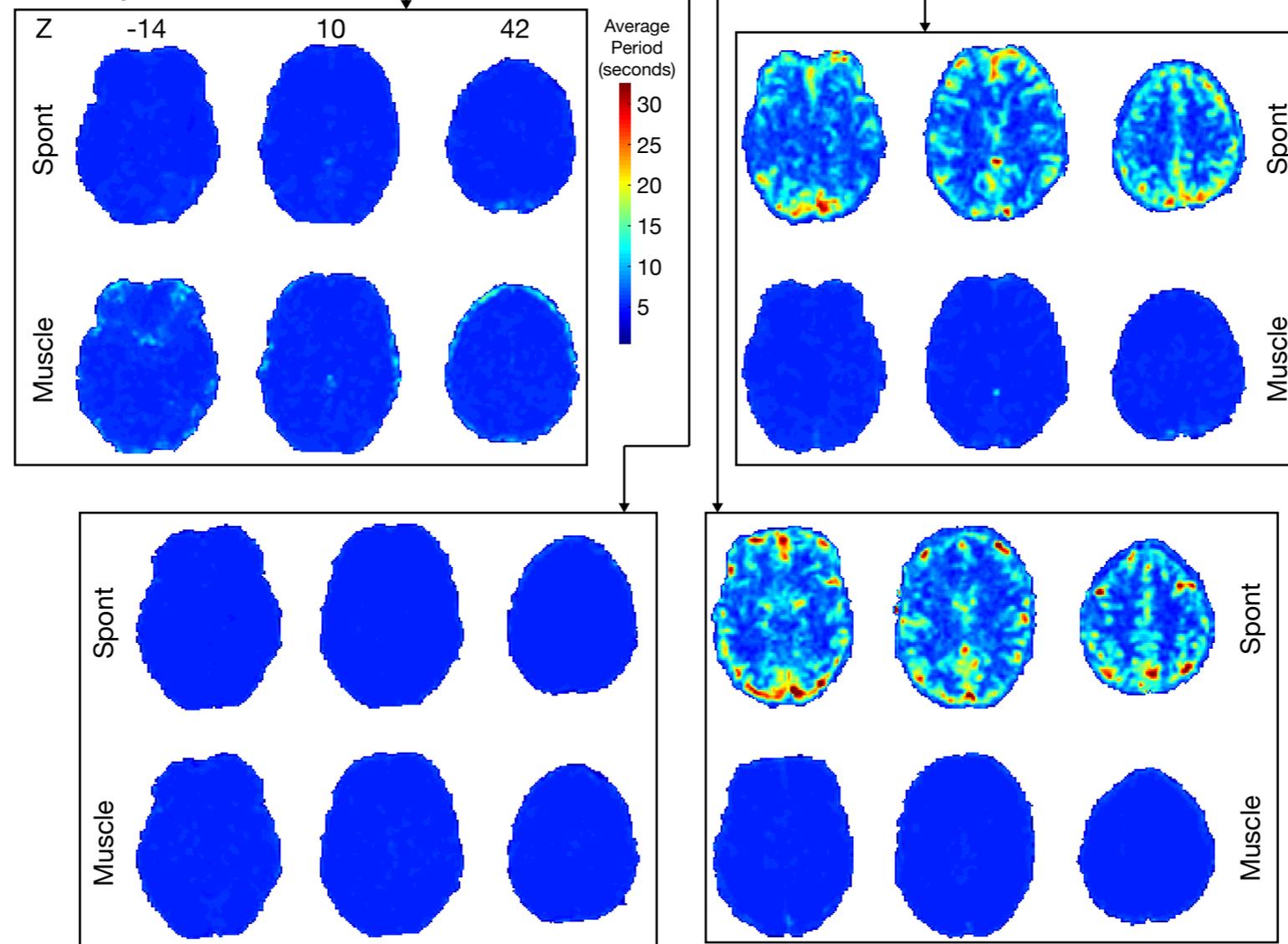


Fluctuations are patient- and task-specific

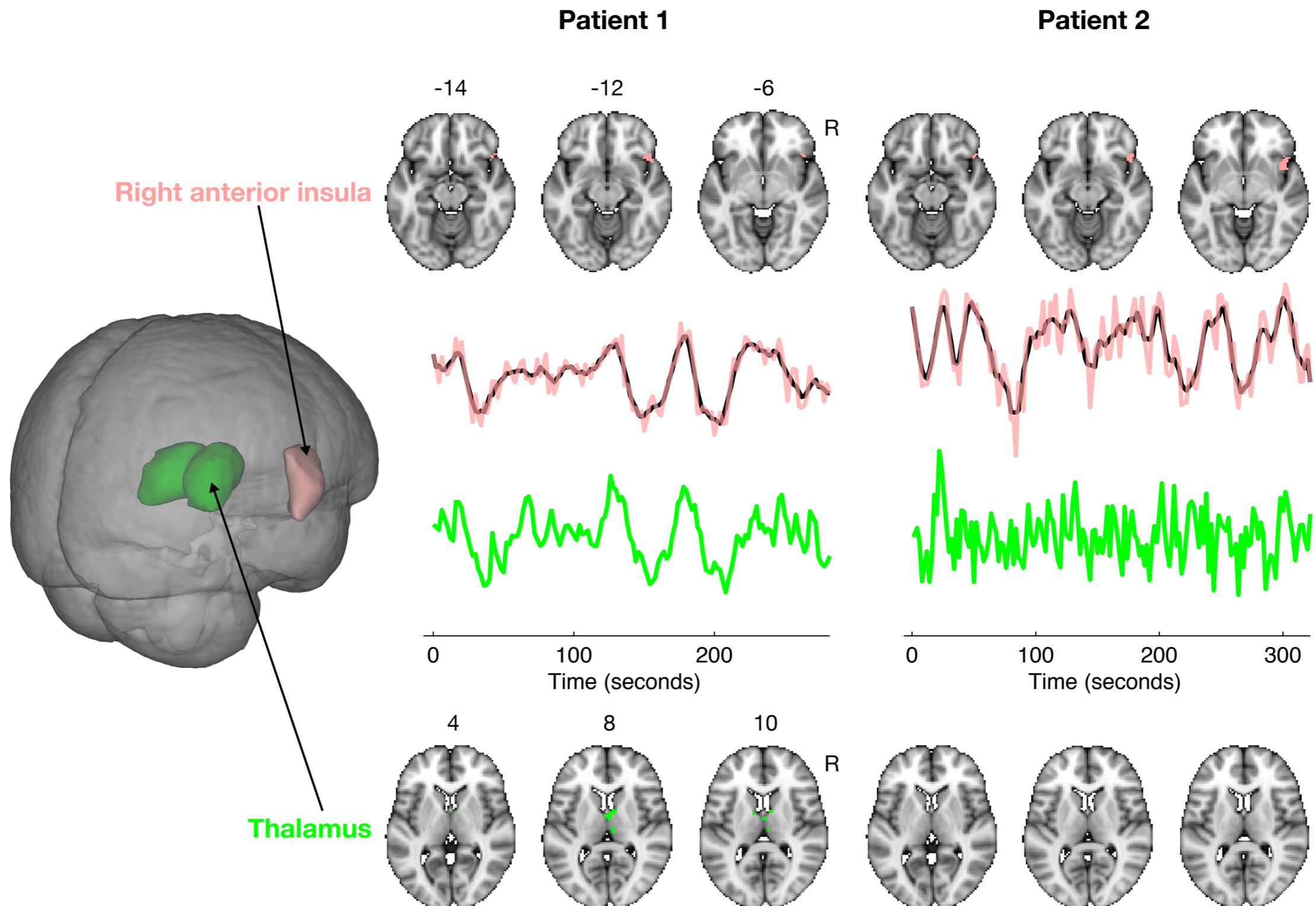
A. Summary



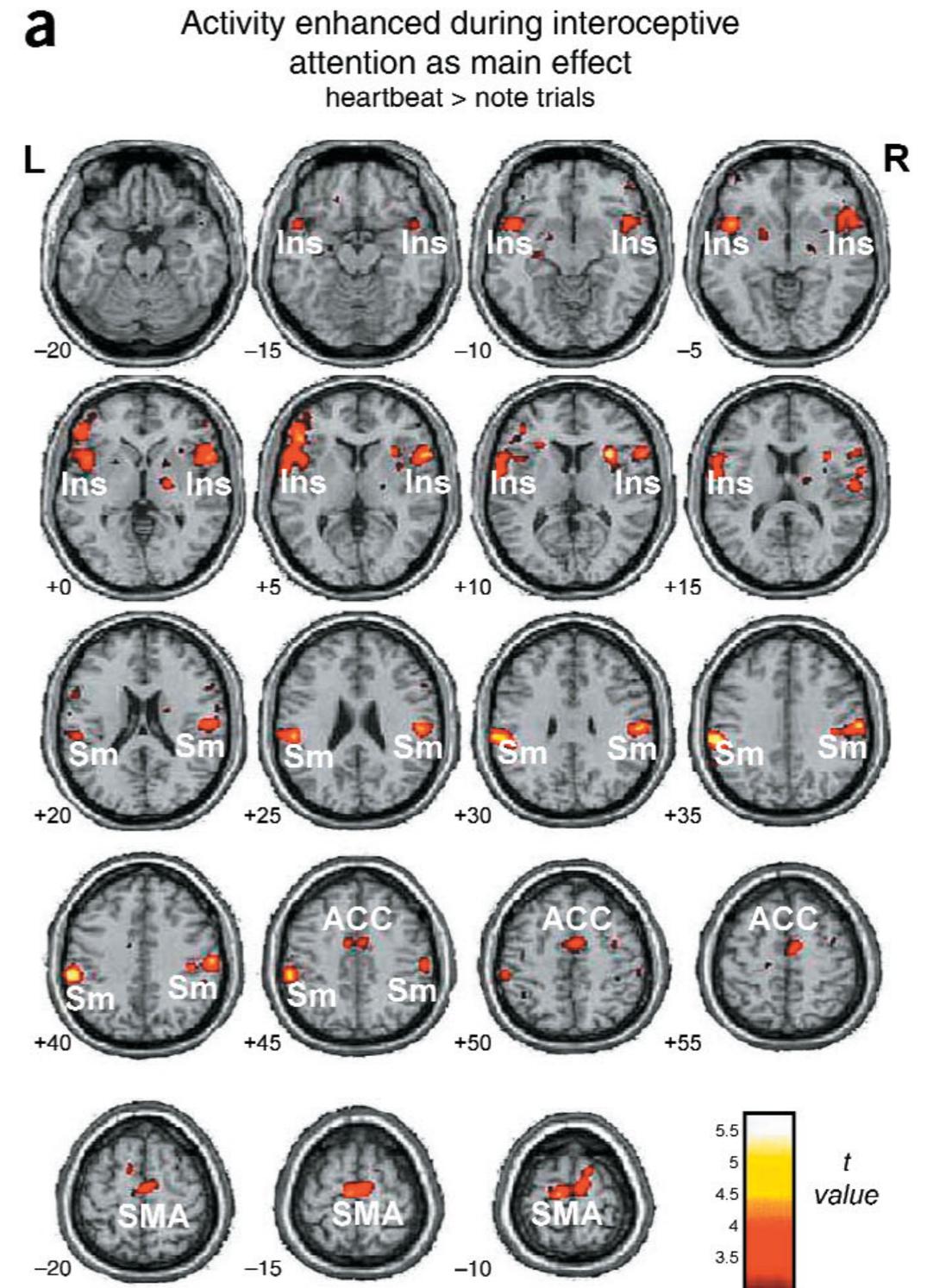
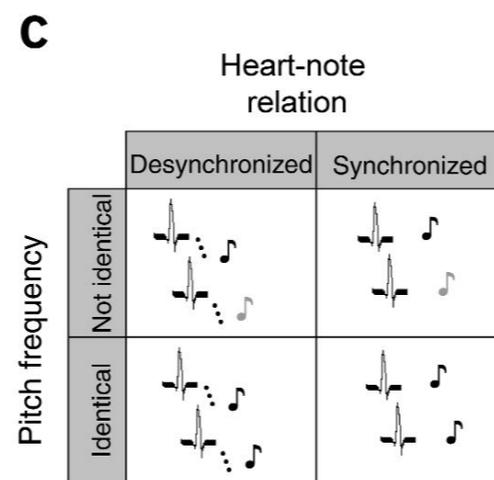
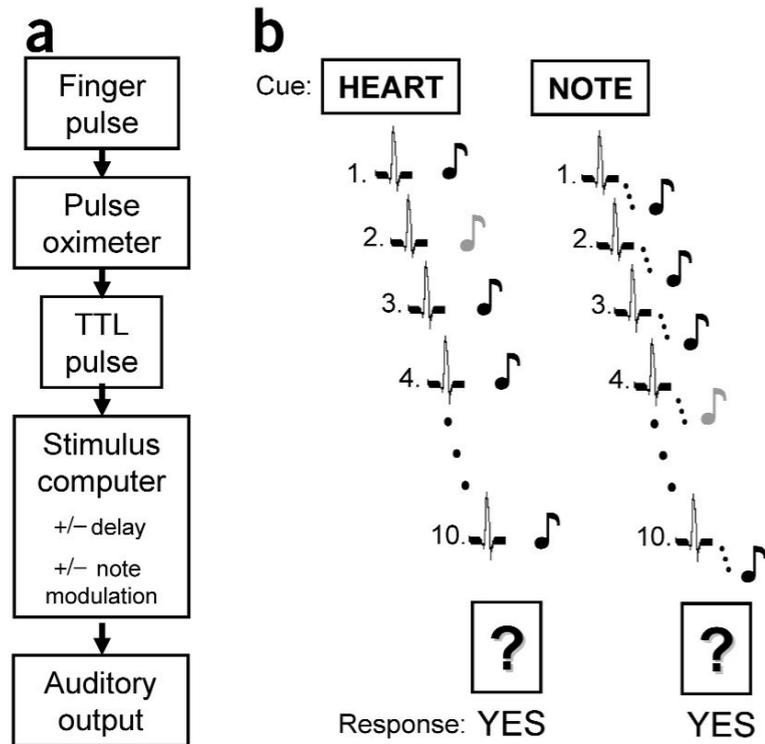
B. Examples



Network differences among patients

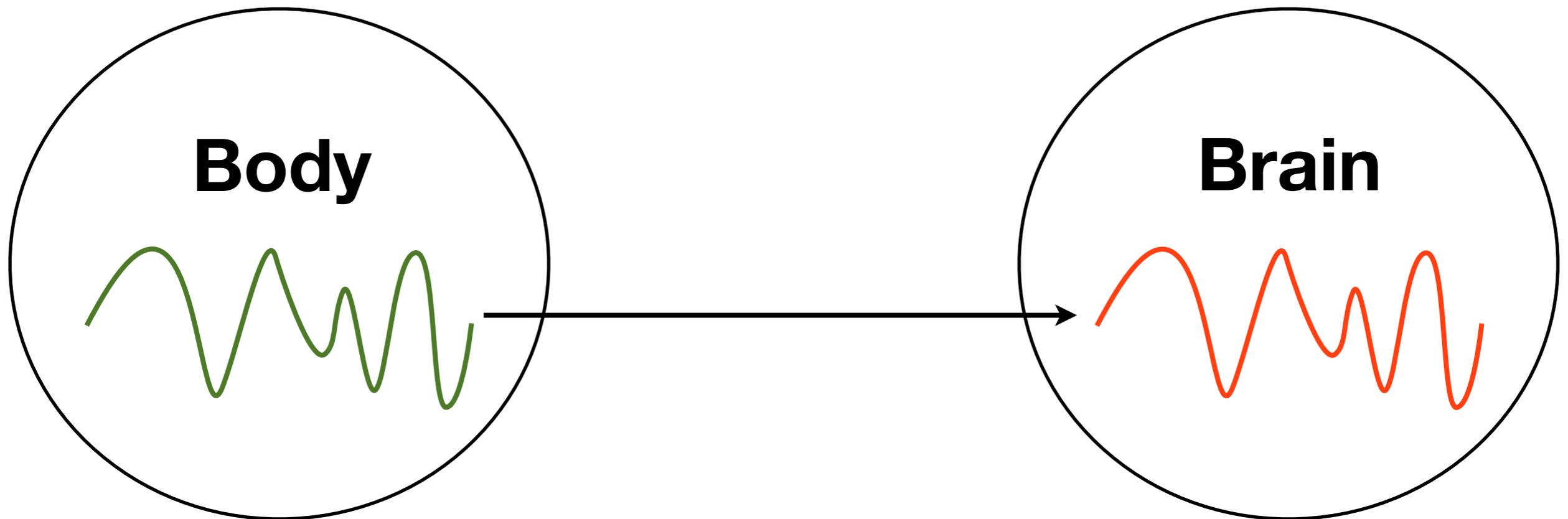


One ignorable peripheral oscillation (heartbeat)



Importance of neuromechanical thinking

without neuromech.: first thought is pathological brain



with neuromech.: first thought is driving peripheral oscillations

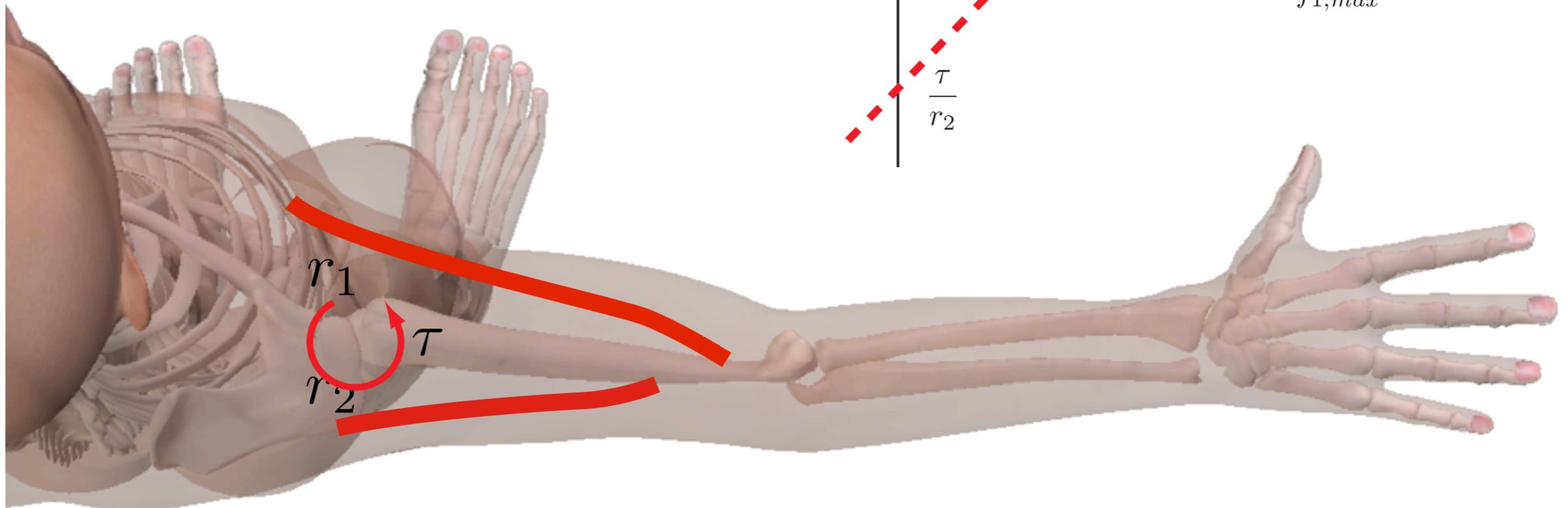
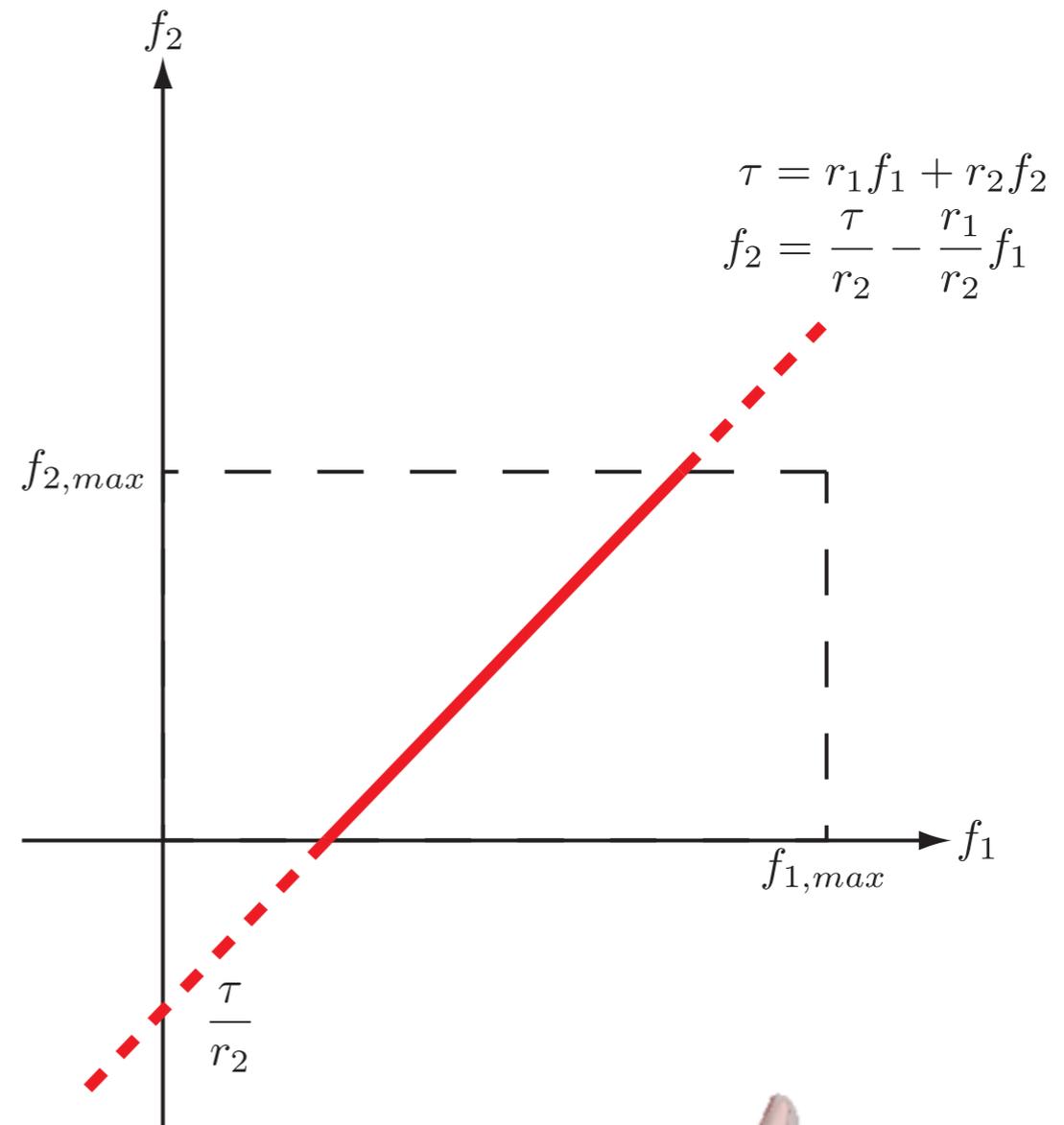
Part 1:
**Peripheral fluctuations from
muscle redundancy**

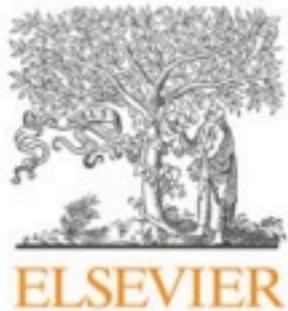
Muscle redundancy



Muscle redundancy

Muscle redundancy can be viewed geometrically as the intersection of hyperplanes and hypercubes





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Muscle redundancy does not imply robustness to muscle dysfunction

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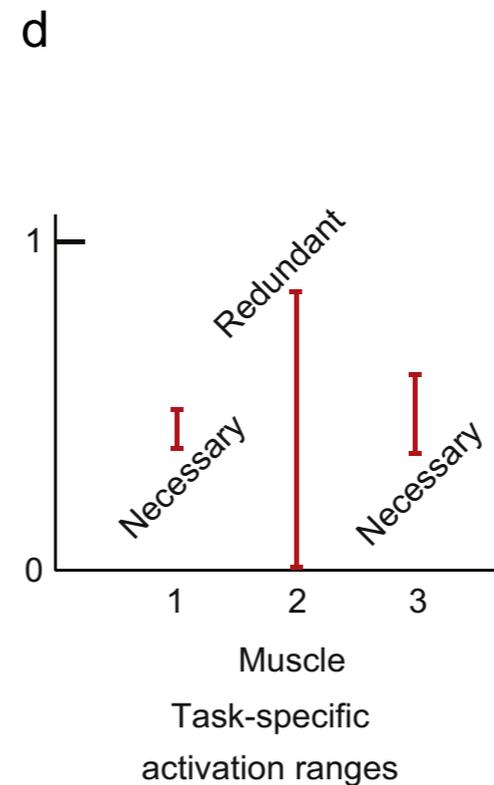
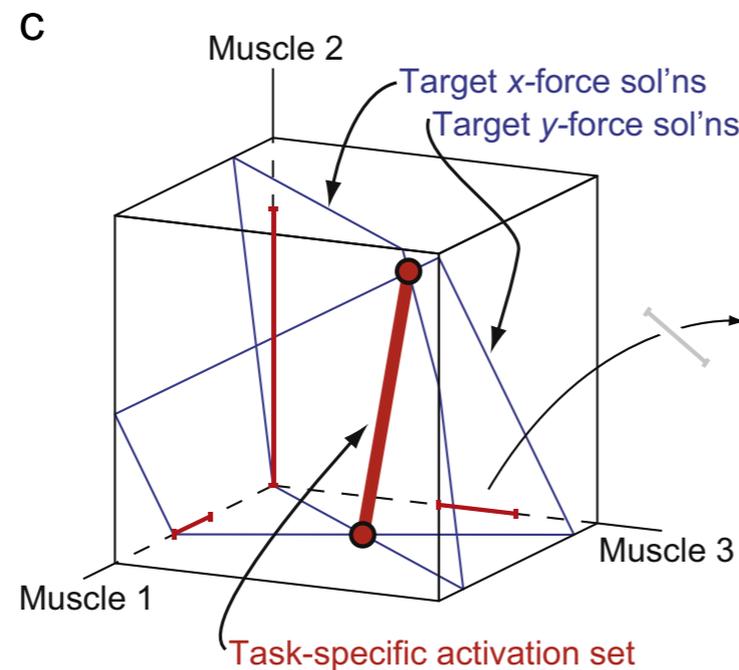
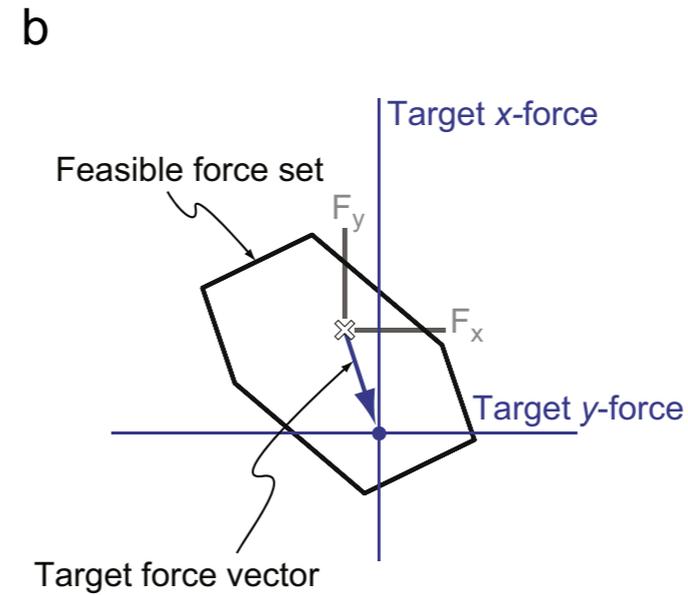
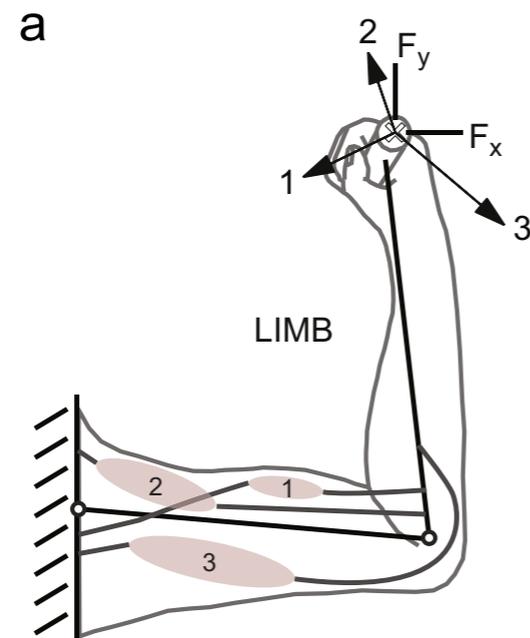
ABSTRACT

It is well-known that muscle redundancy grants the CNS numerous options to perform a task. Does muscle redundancy, however, allow sufficient robustness to compensate for loss or dysfunction of even a single muscle? Are all muscles equally redundant? We combined experimental and computational approaches to establish the limits of motor robustness for static force production. In computer-controlled cadaveric index fingers, we find that only a small subset (< 5%) of feasible forces is robust to loss of any one muscle. Importantly, the loss of certain muscles compromises force production significantly more than others. Further computational modeling of a multi-joint, multi-muscle leg demonstrates that this severe lack of robustness generalizes to whole limbs. These results provide a biomechanical basis to begin to explain why redundant motor systems can be vulnerable to even mild neuromuscular pathology.

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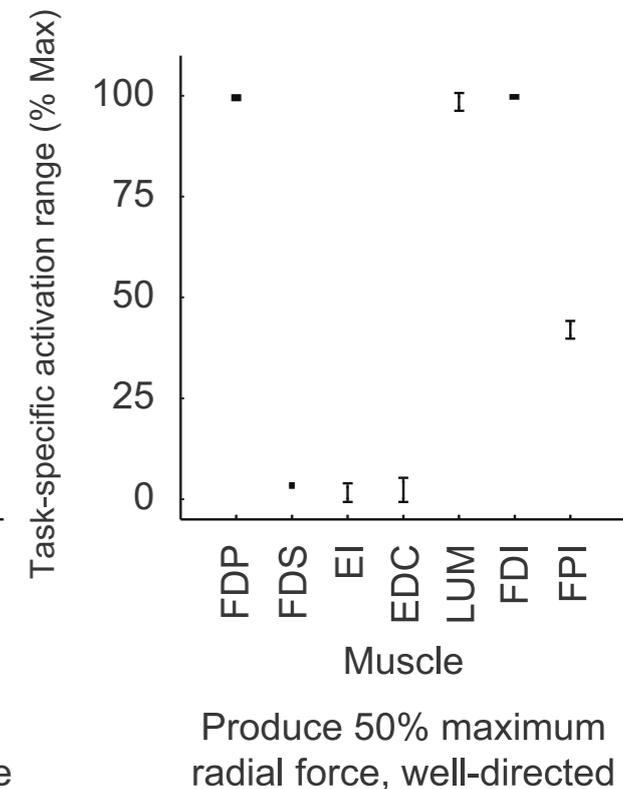
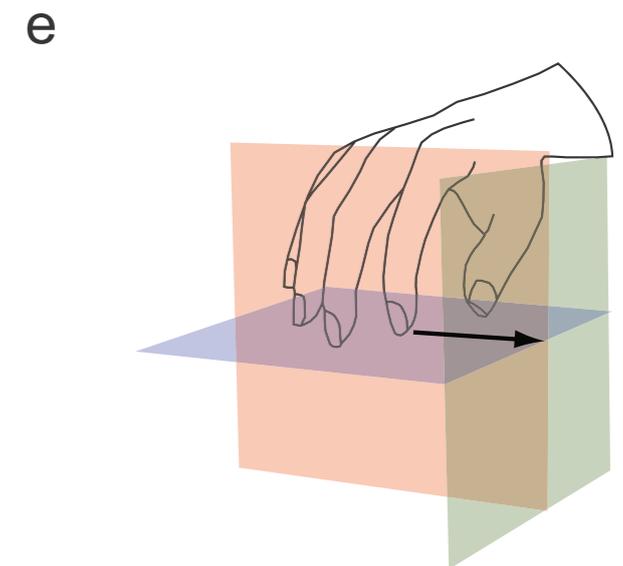
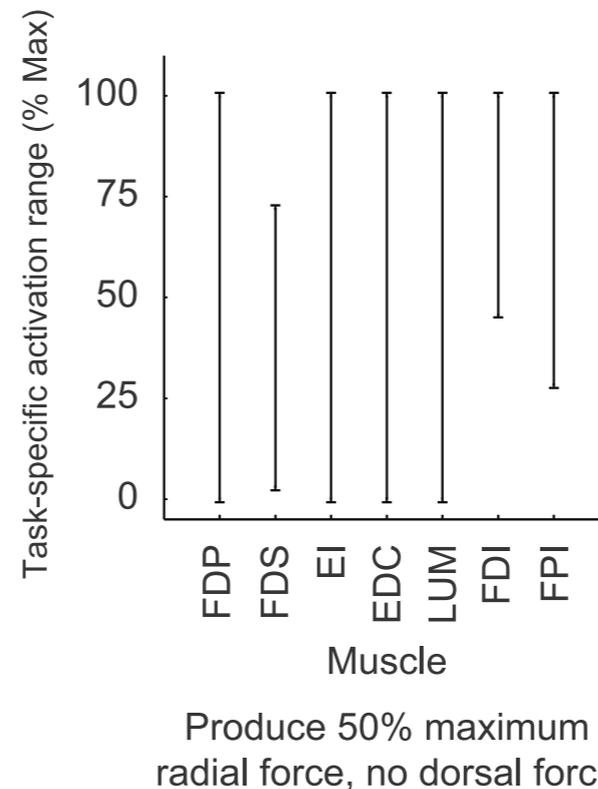
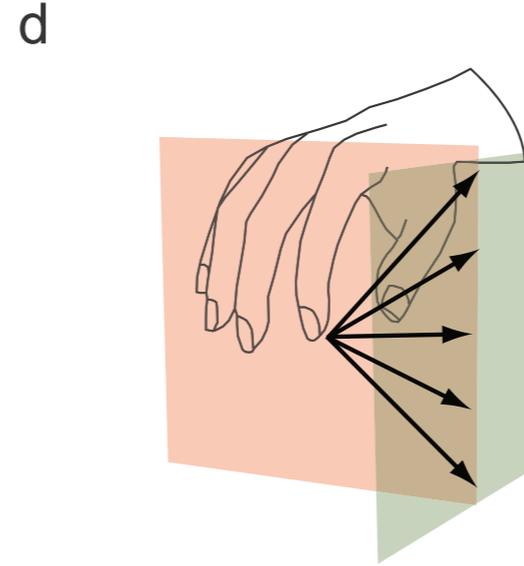
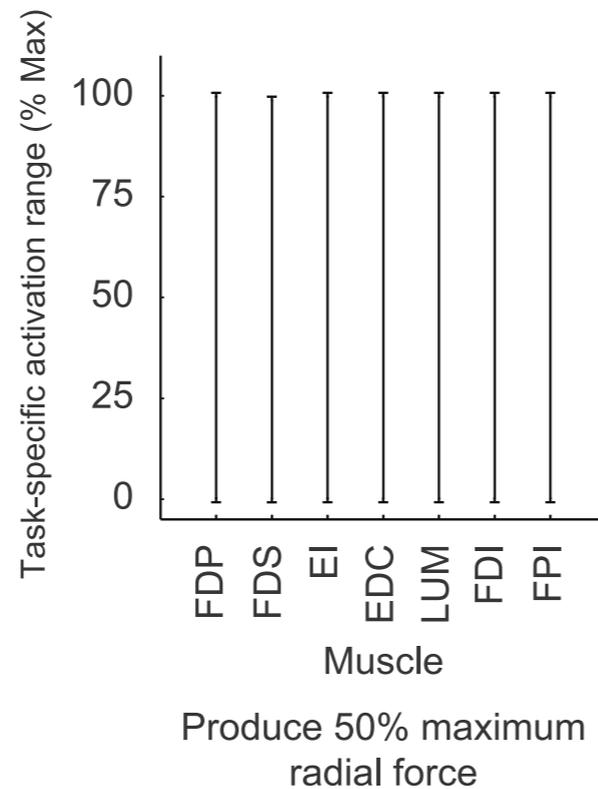
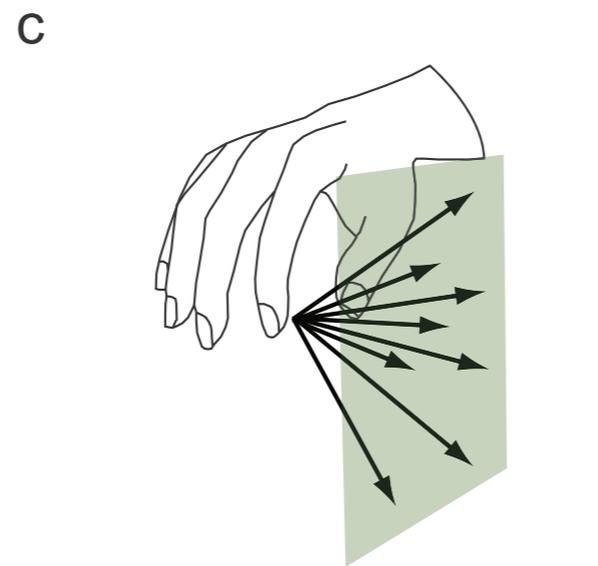
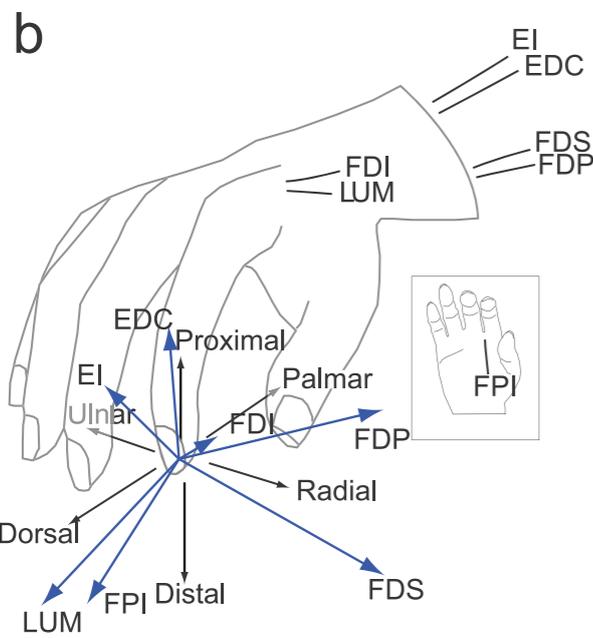
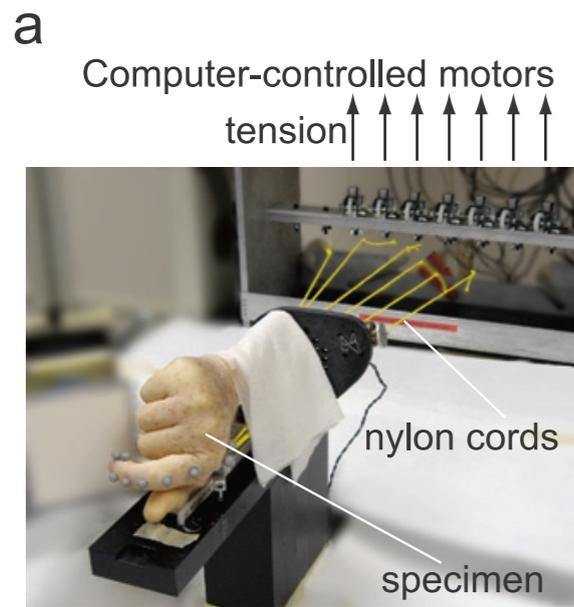
Muscle redundancy

Geometric view of muscle redundancy generalizes.

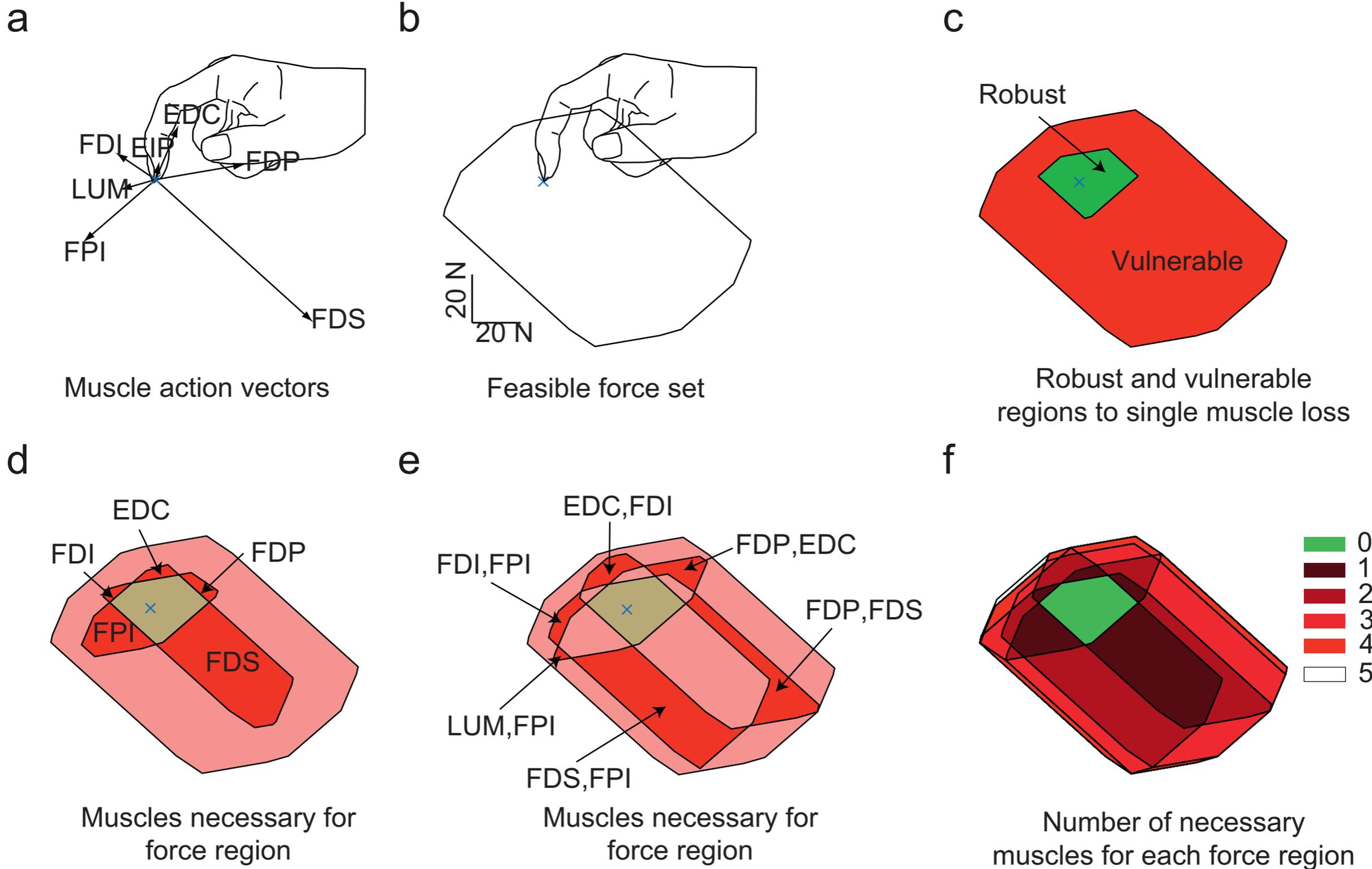


Muscle redundancy

Predictions can be made from cadaveric data.



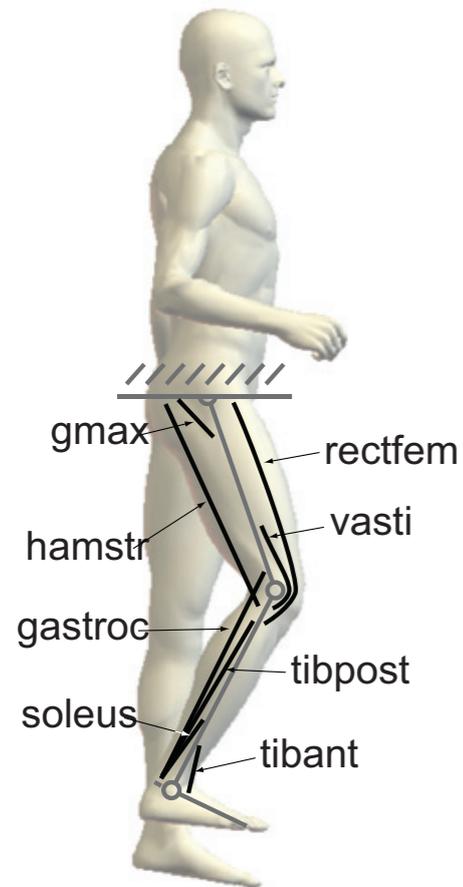
Robust regions - an one muscle can turn off.



Muscle redundancy

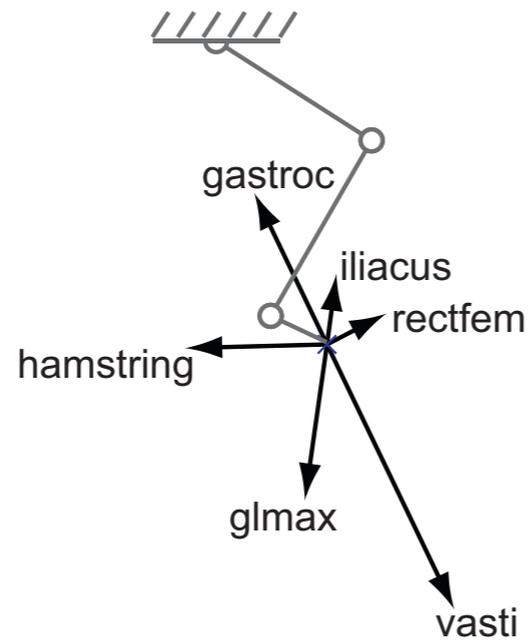
Predictions can also be made from biomechanical models.

a



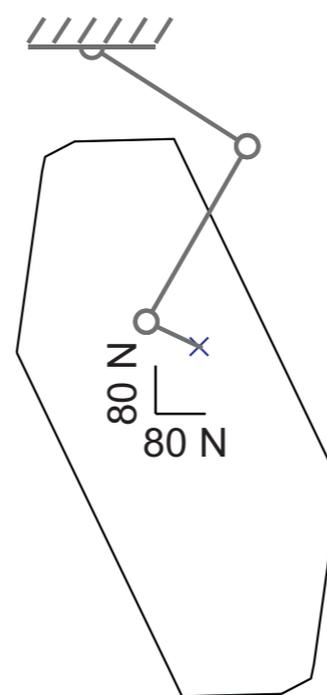
Sagittal Plane Leg Model

b



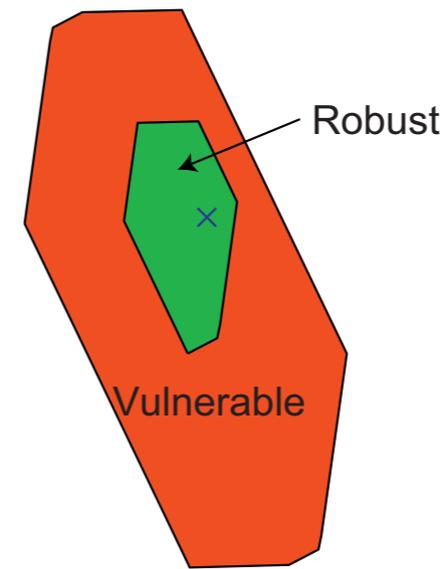
Sample muscle action vectors

c



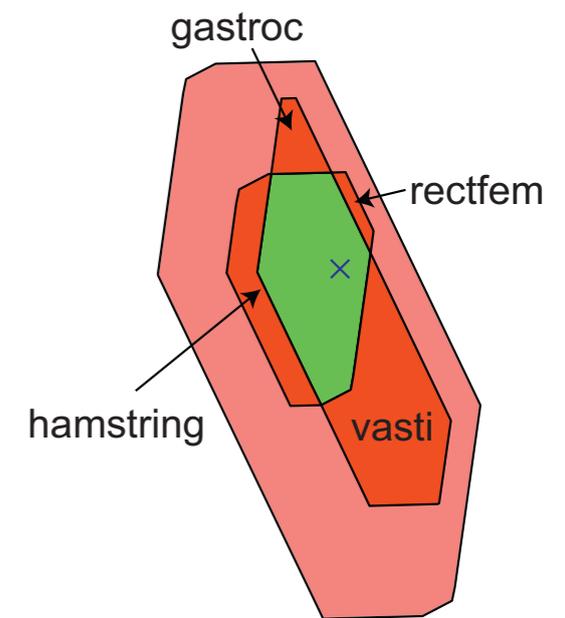
Feasible force set

d



Robust and vulnerable regions to single muscle loss

e



Muscle necessary for force region

Databaser

User Experiment Session Helper Functions Help

Active Experiment:
Active Session:
Current Config:

Databaser
by Jason J. Kutch, PhD

LabWiki

CoSMo2012_MatlabExercise1
DatabaserProject

+ - Edit Open

Collect Data

Methods

+ - Choose Class

Notebook
New Open Add Entry

Run Collection Method

Build Database

Set Path for Add Trial(s)

Set to FTP? FTP address

File(s) of Type 1

Append? ... into Trial Using Reader

+ + Folder - Clear + - Clear + - Choose Class

Search And Select

Build

Analyze

You need to open a session before analyzing
Trial(s) to Analyze Load Save

... Using Function

+ - Clear up down + - Choose Class

Analyze

Refine Results, Model, Publish!

Set Path for Result(s)

Result(s) and/or Model(s) Load Save

... Using Function

+ + Folder - Clear All up down + - Choose Class

GCA Position Export Rough PDF

Publish!

Program Status

Computational Geometry

Monte-Carlo Methods

Optimization focuses on a solution

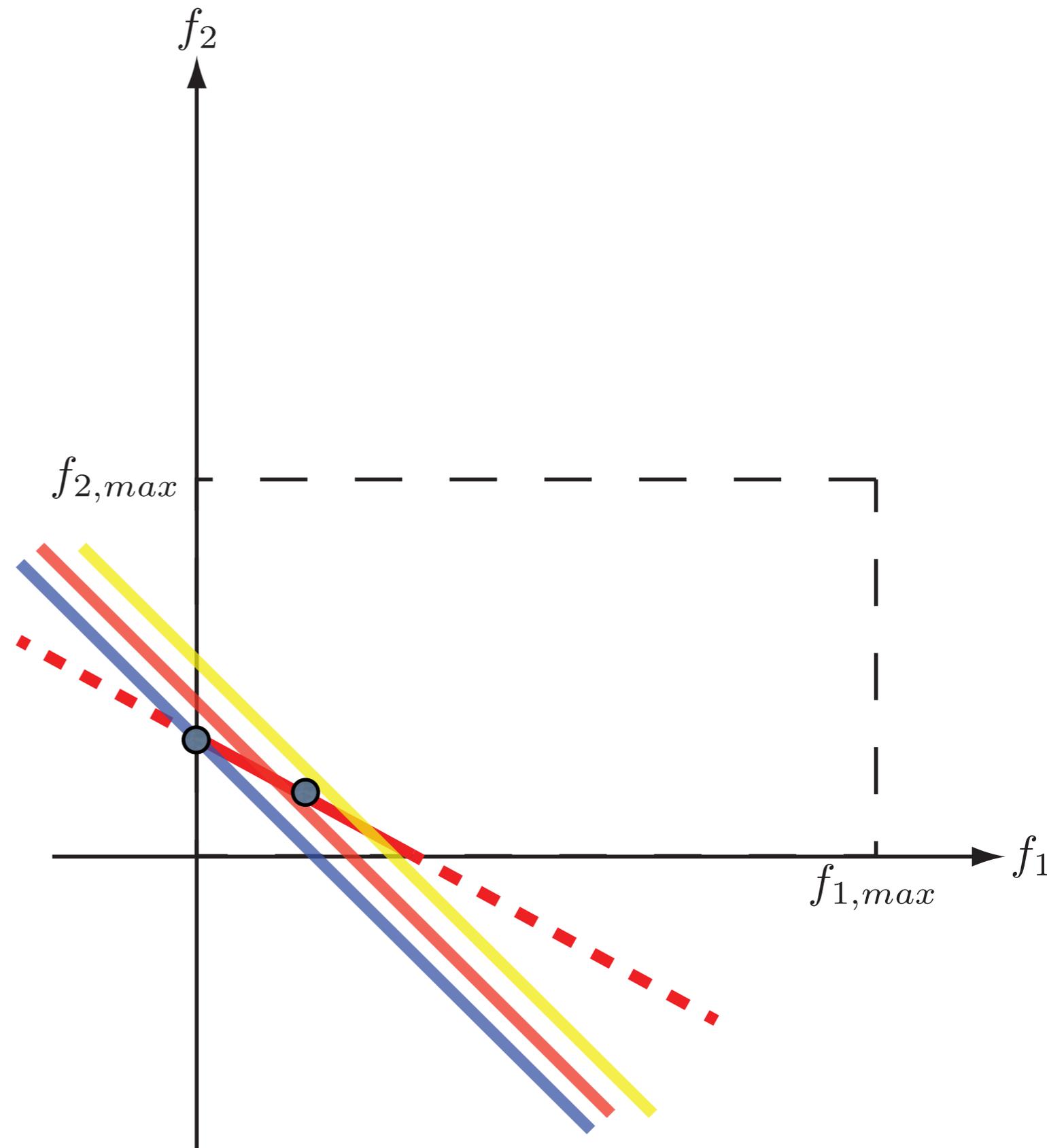
Example 1: Linear cost function

$$J(f) = \sum_{i=1}^n f_i$$

$$\min_f f_1 + f_2$$

such that $Rf = \tau_d$

linprog in MATLAB



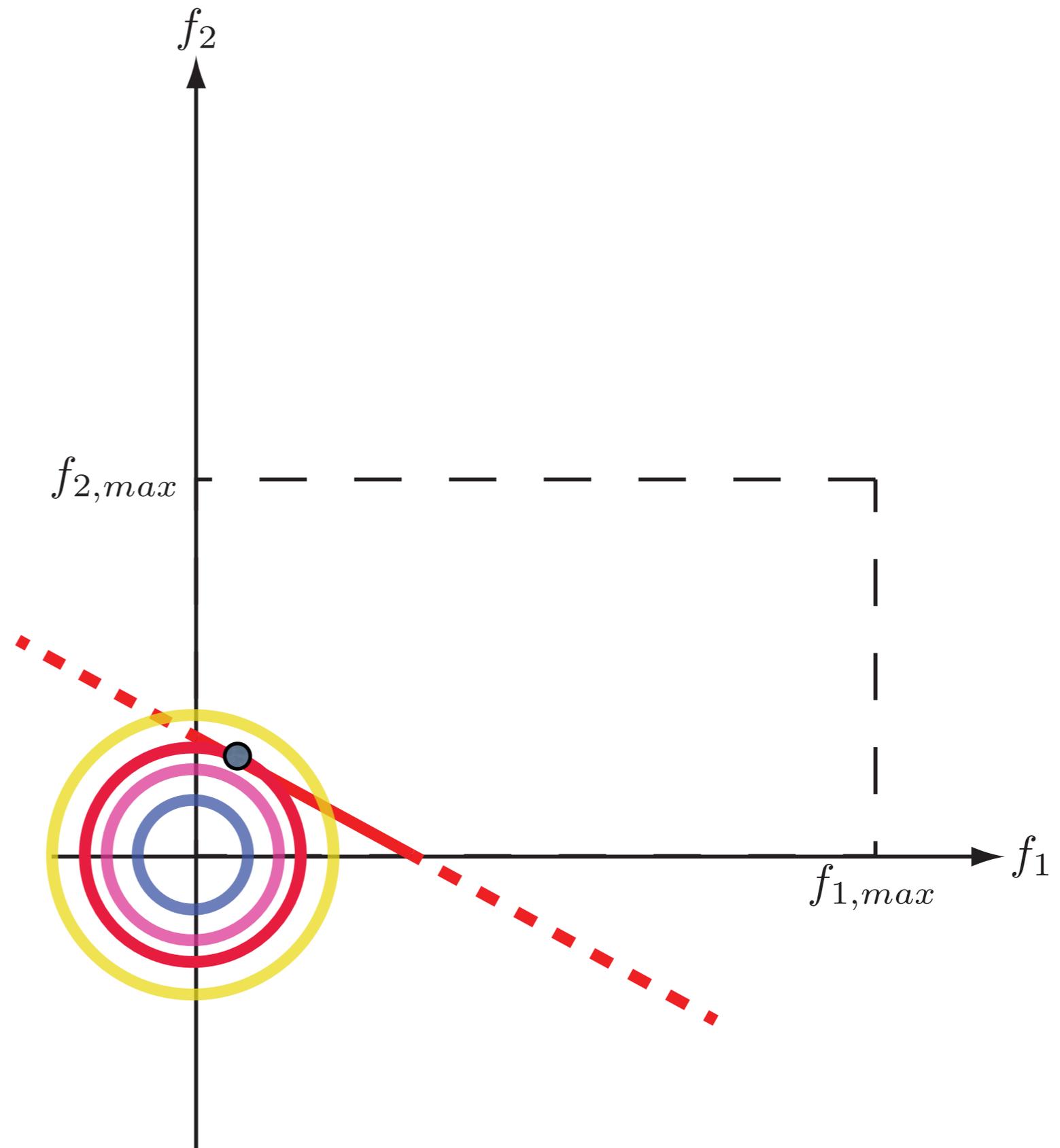
Example 2: Quadratic cost function

$$J(f) = \sum_{i=1}^n f_i^2$$

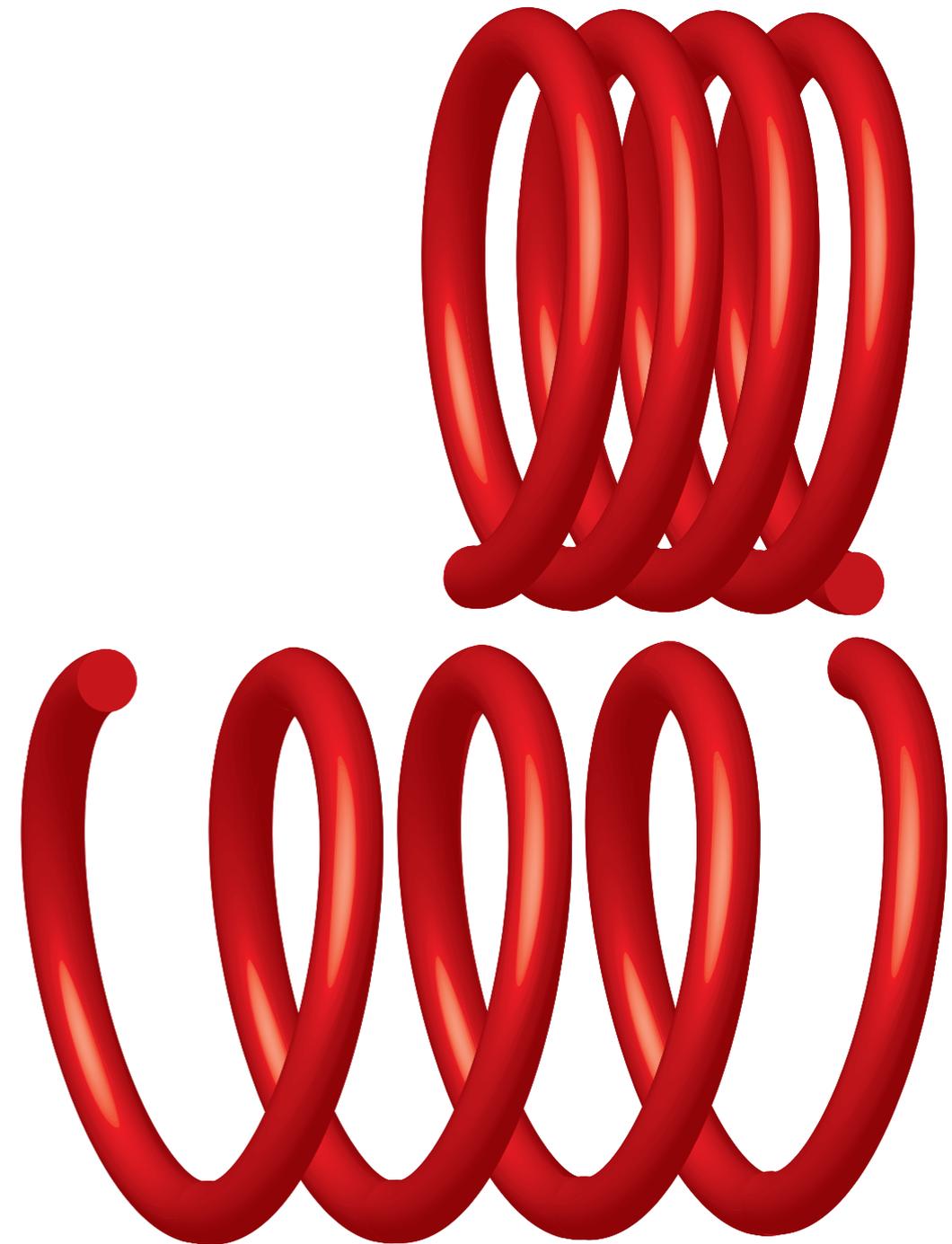
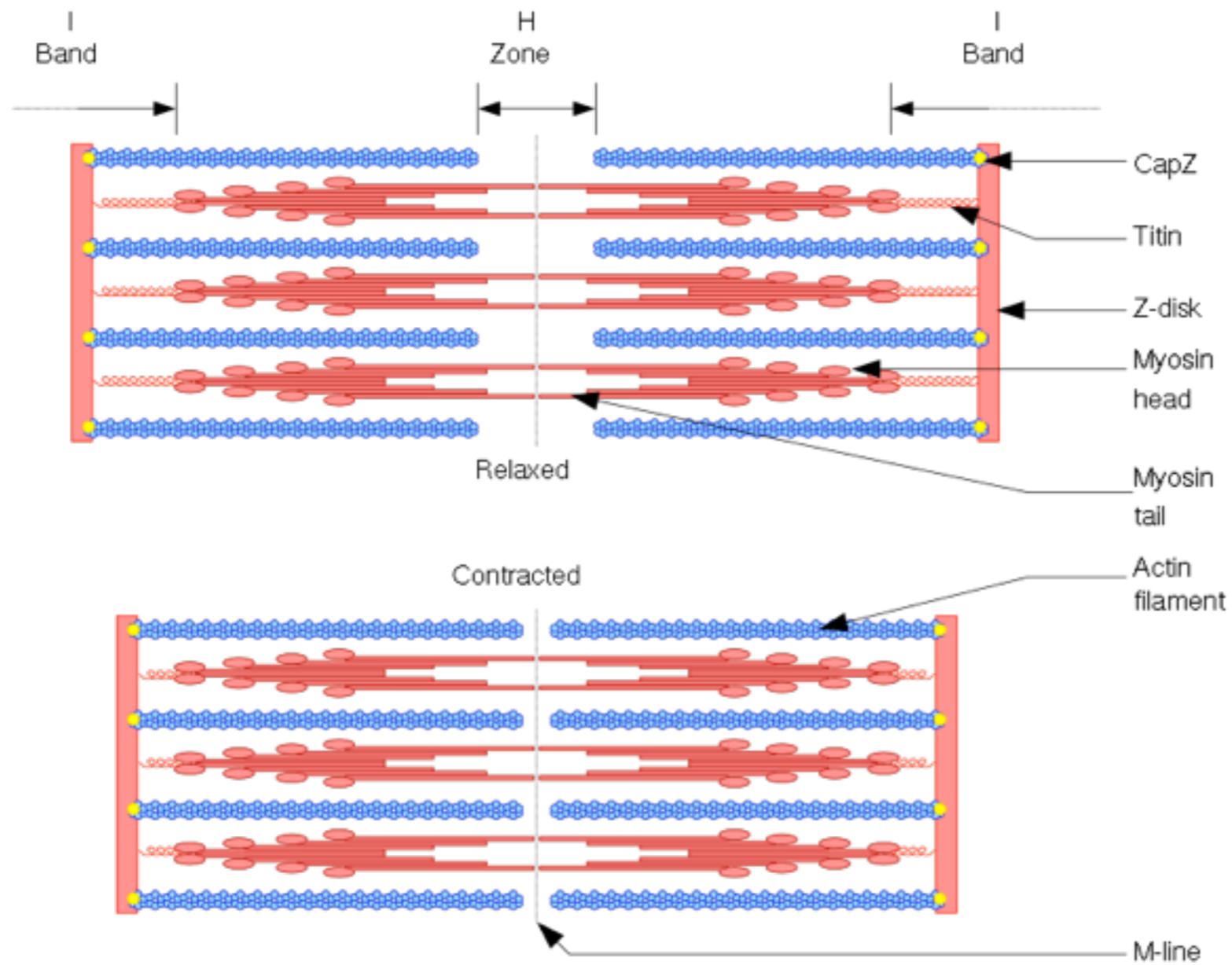
$$\min_f f_1^2 + f_2^2$$

such that $Rf = \tau_d$

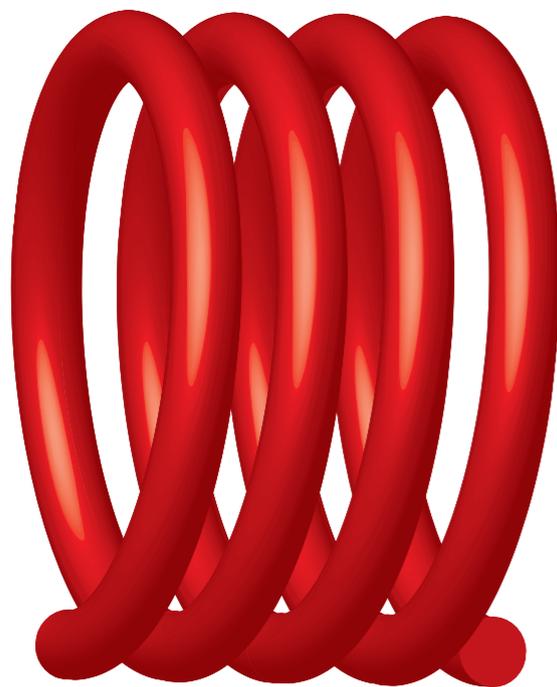
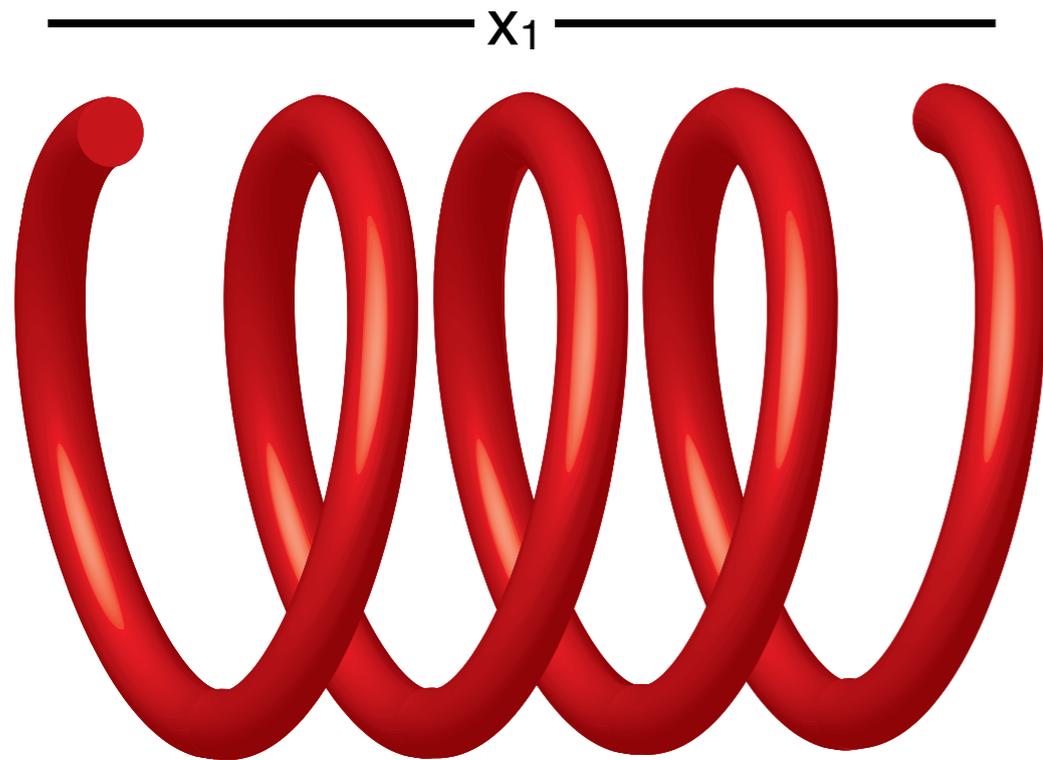
quadprog in MATLAB



Muscle redundancy



Muscle redundancy



$$\Delta x = x_2 - x_1$$

$$F = k\Delta x$$

$$E = \frac{1}{2}k(\Delta x)^2$$

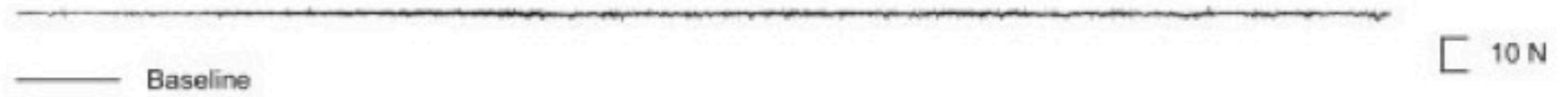
$$E = \frac{1}{2}k\left(\frac{F}{k}\right)^2$$

$$E = \frac{1}{2k}F^2$$

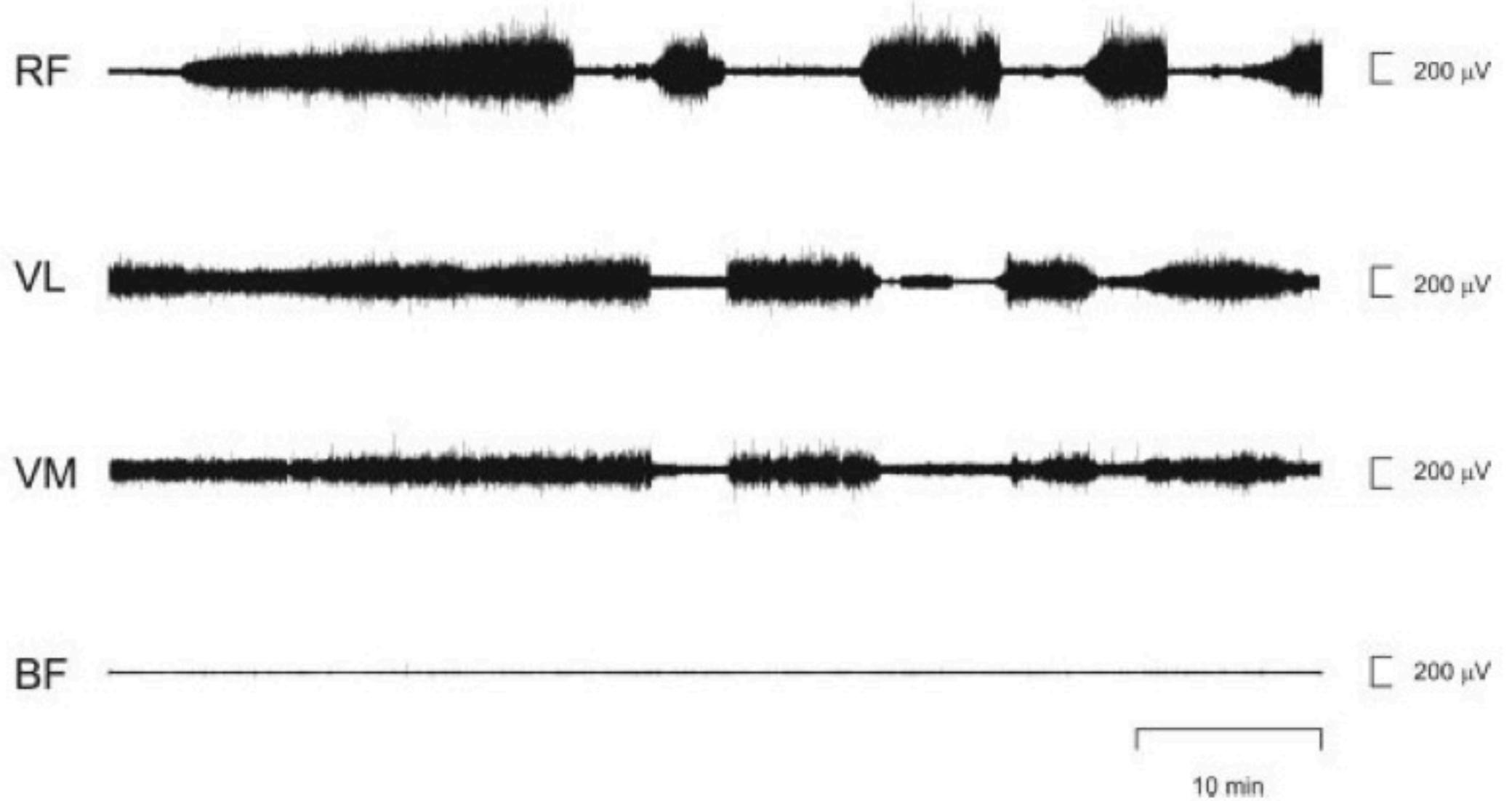
Muscle coordination prediction by Optimization

Muscle redundancy

Force



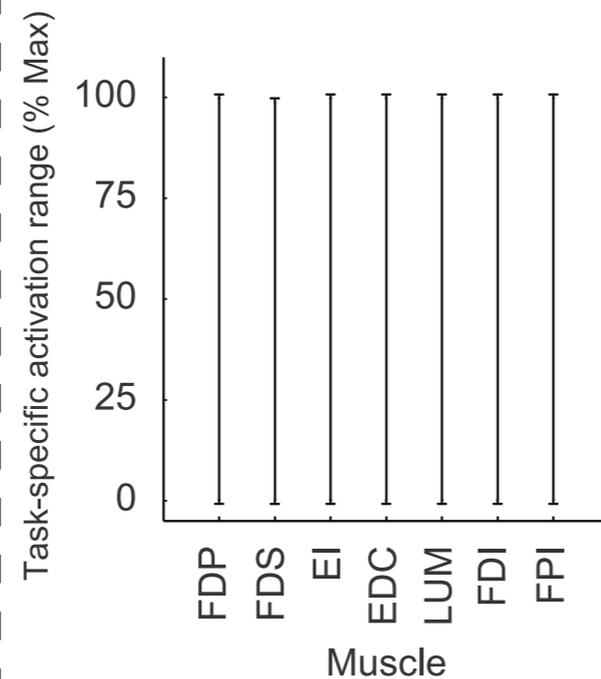
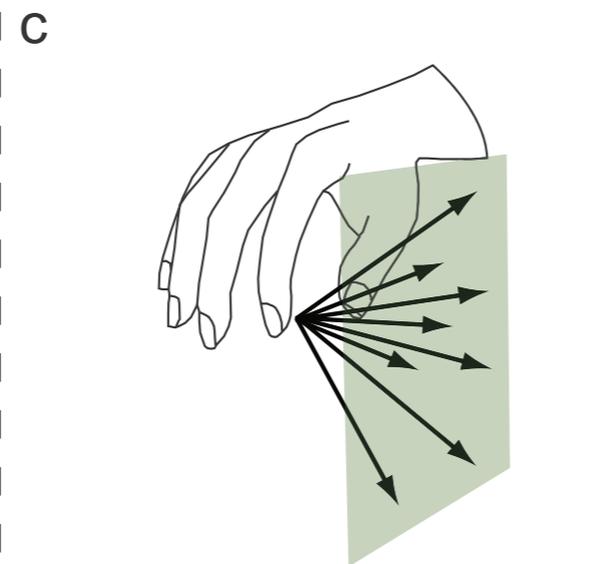
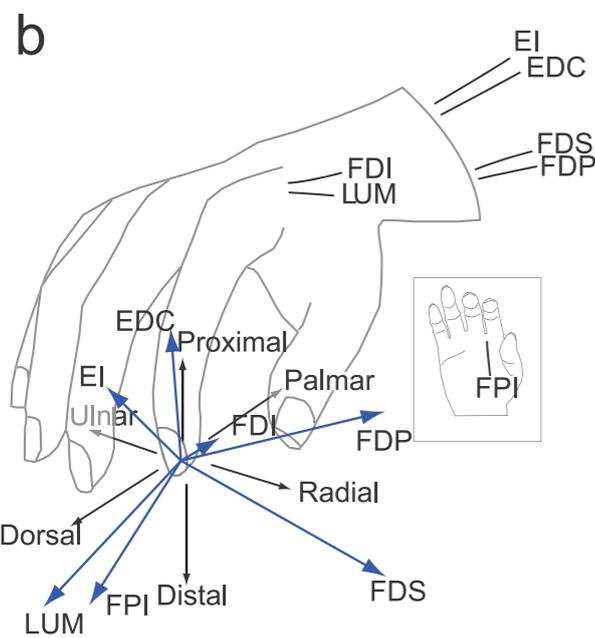
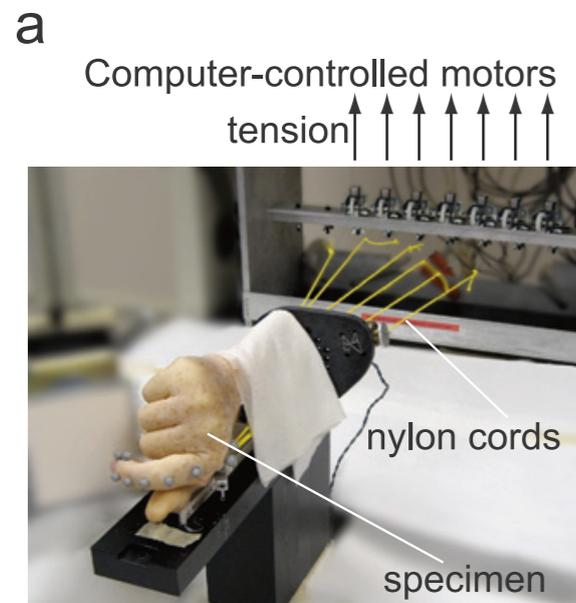
EMG signal



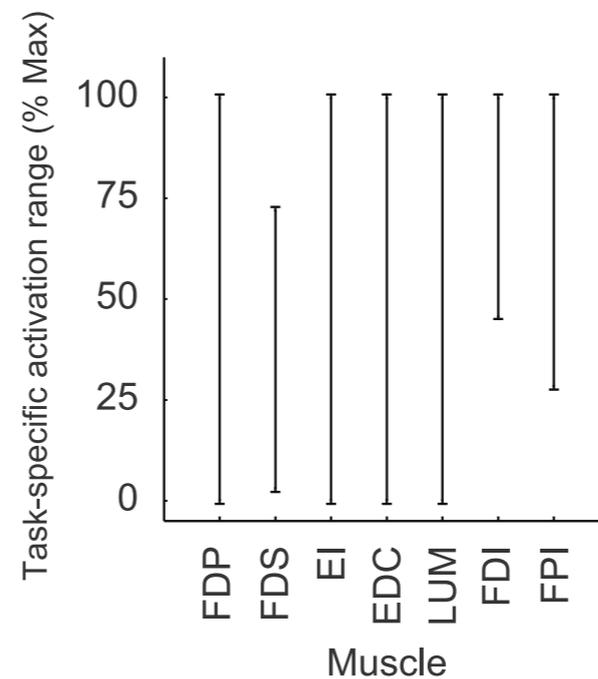
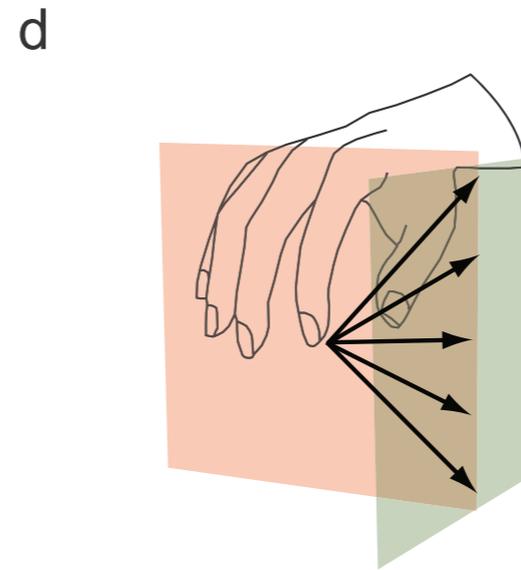
Prediction of muscle switching by dynamic re-optimization

Muscle redundancy

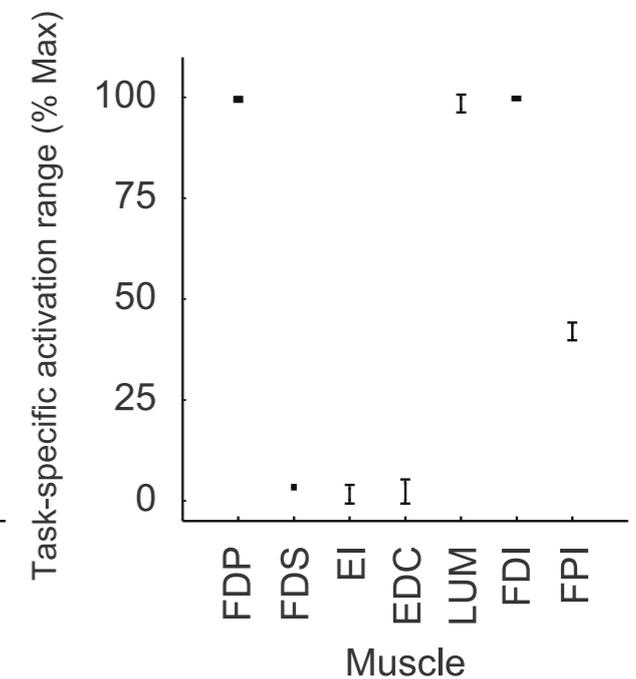
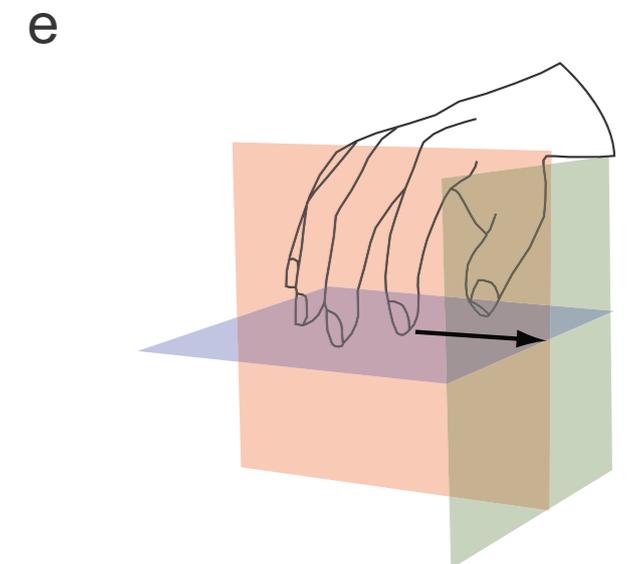
Not all muscles will switch during sustained contraction



Produce 50% maximum radial force

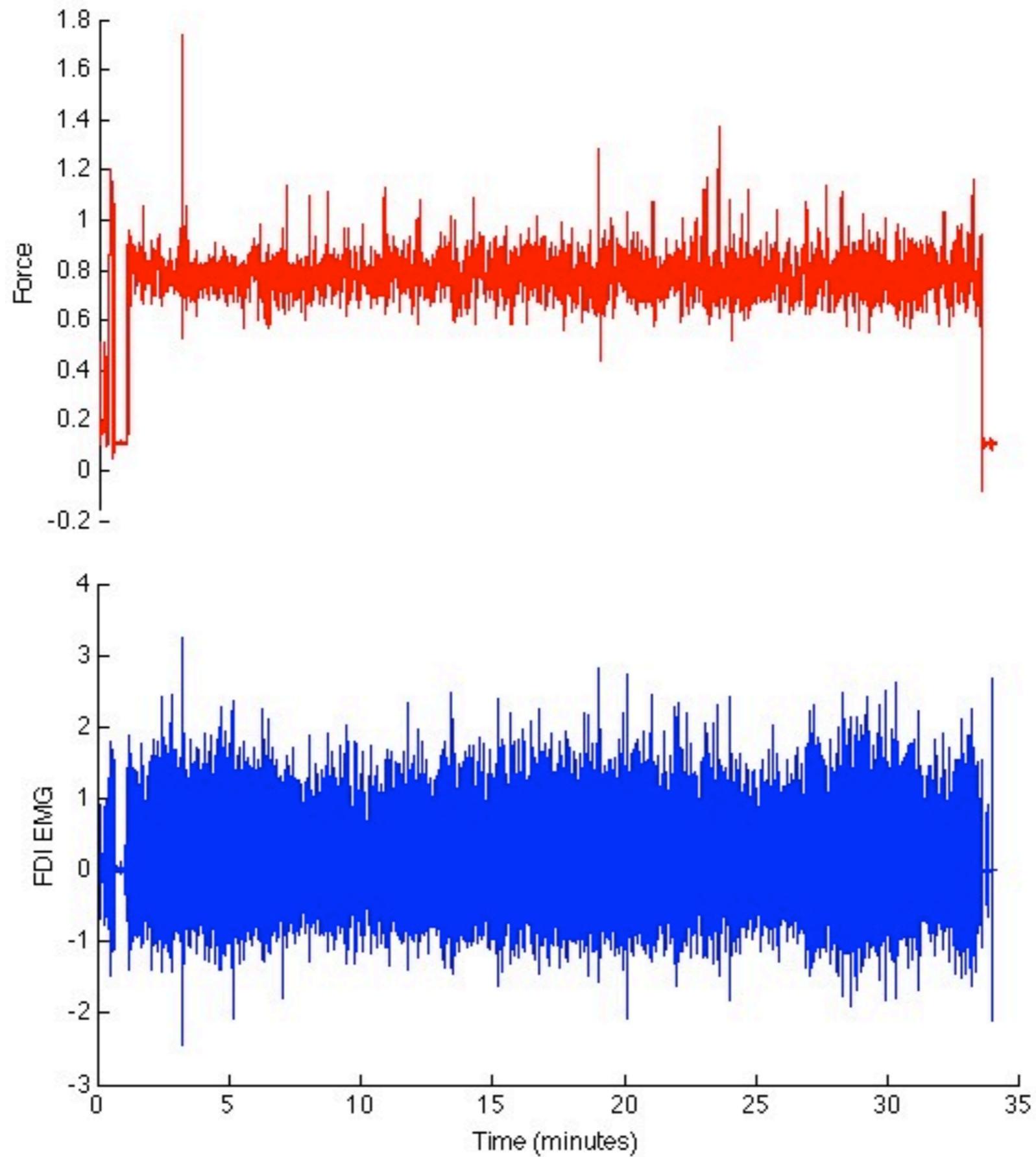


Produce 50% maximum radial force, no dorsal force



Produce 50% maximum radial force, well-directed

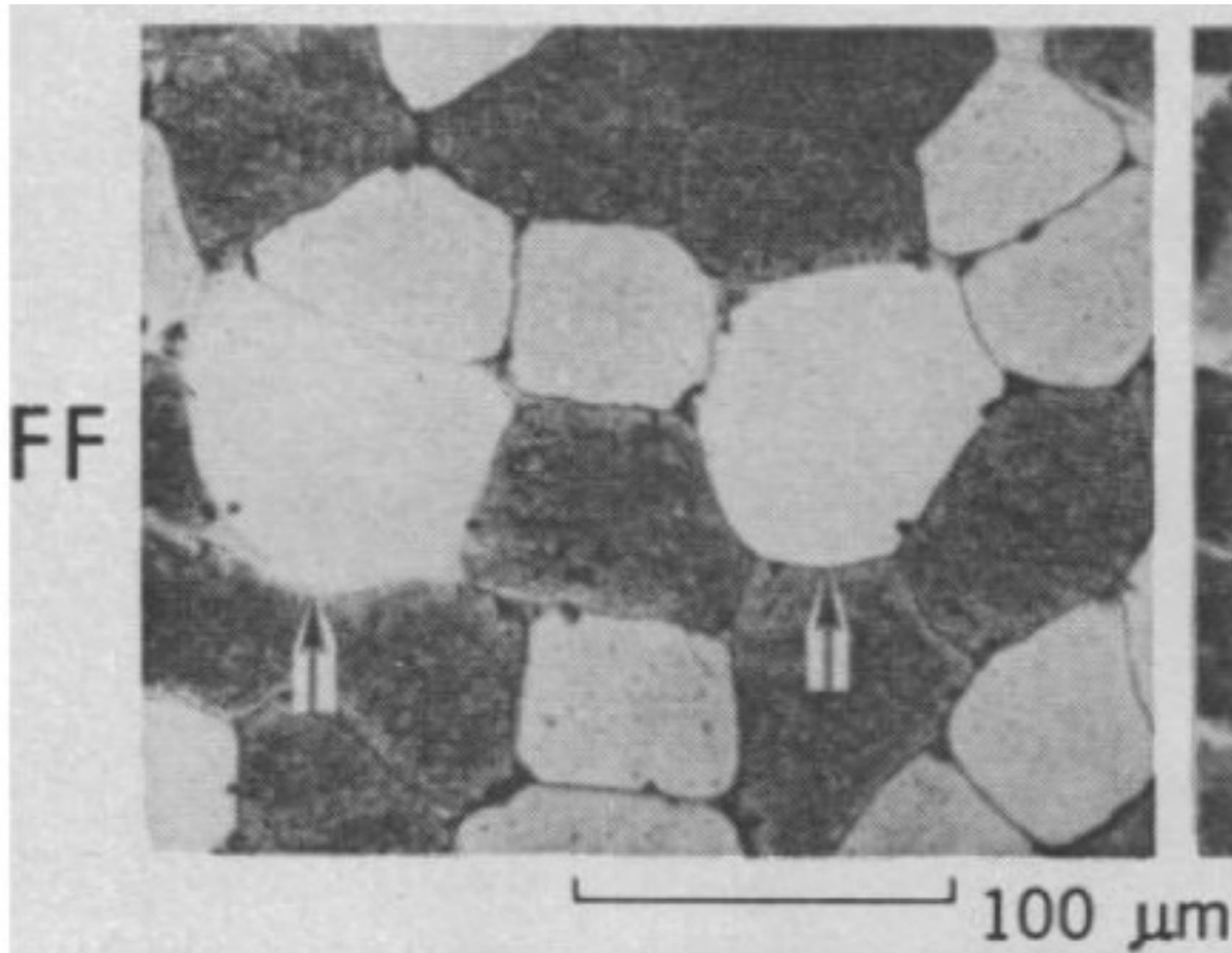
Muscle redundancy



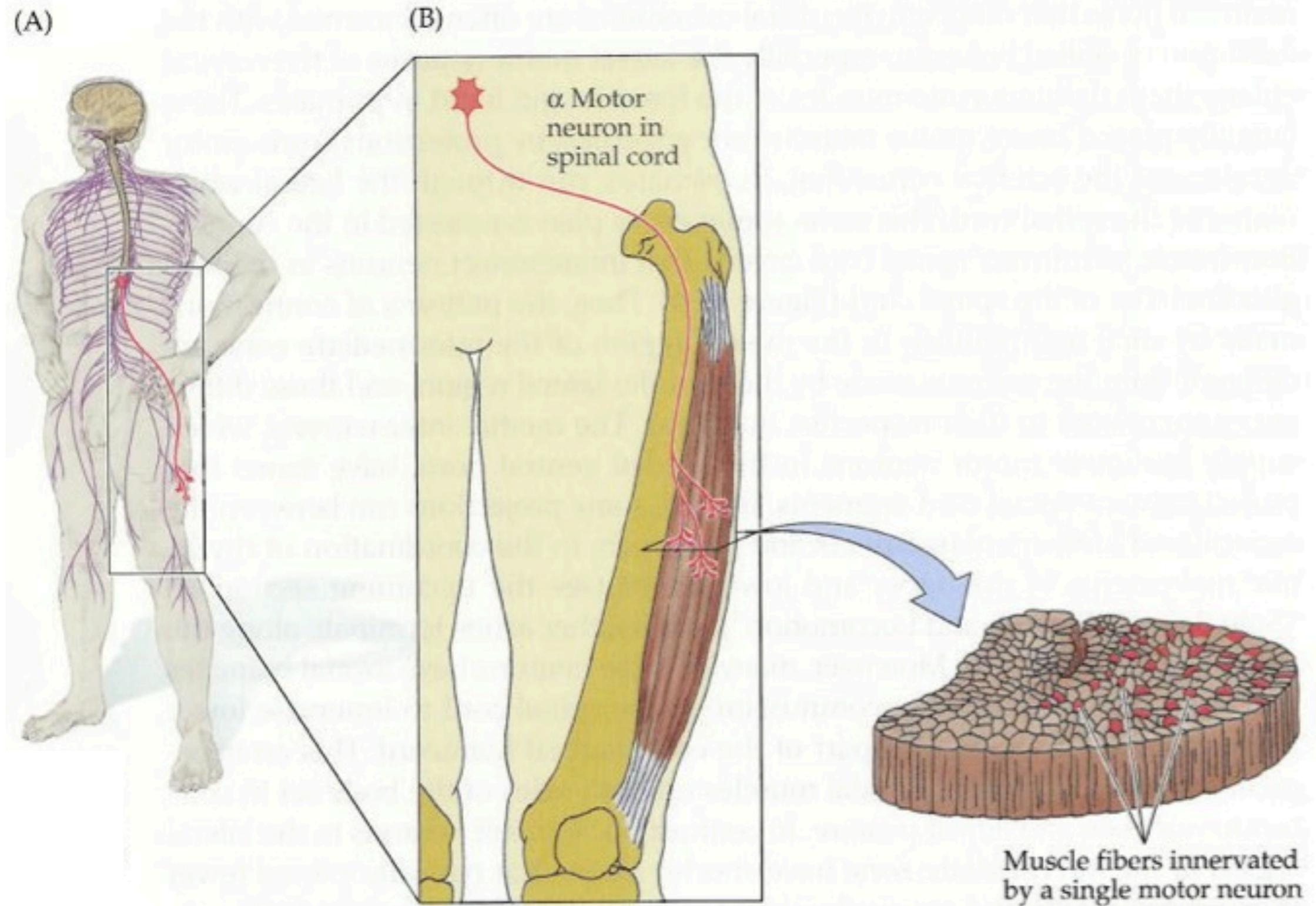
Part 2:
**Peripheral fluctuations from
motor unit redundancy**

Motor unit redundancy

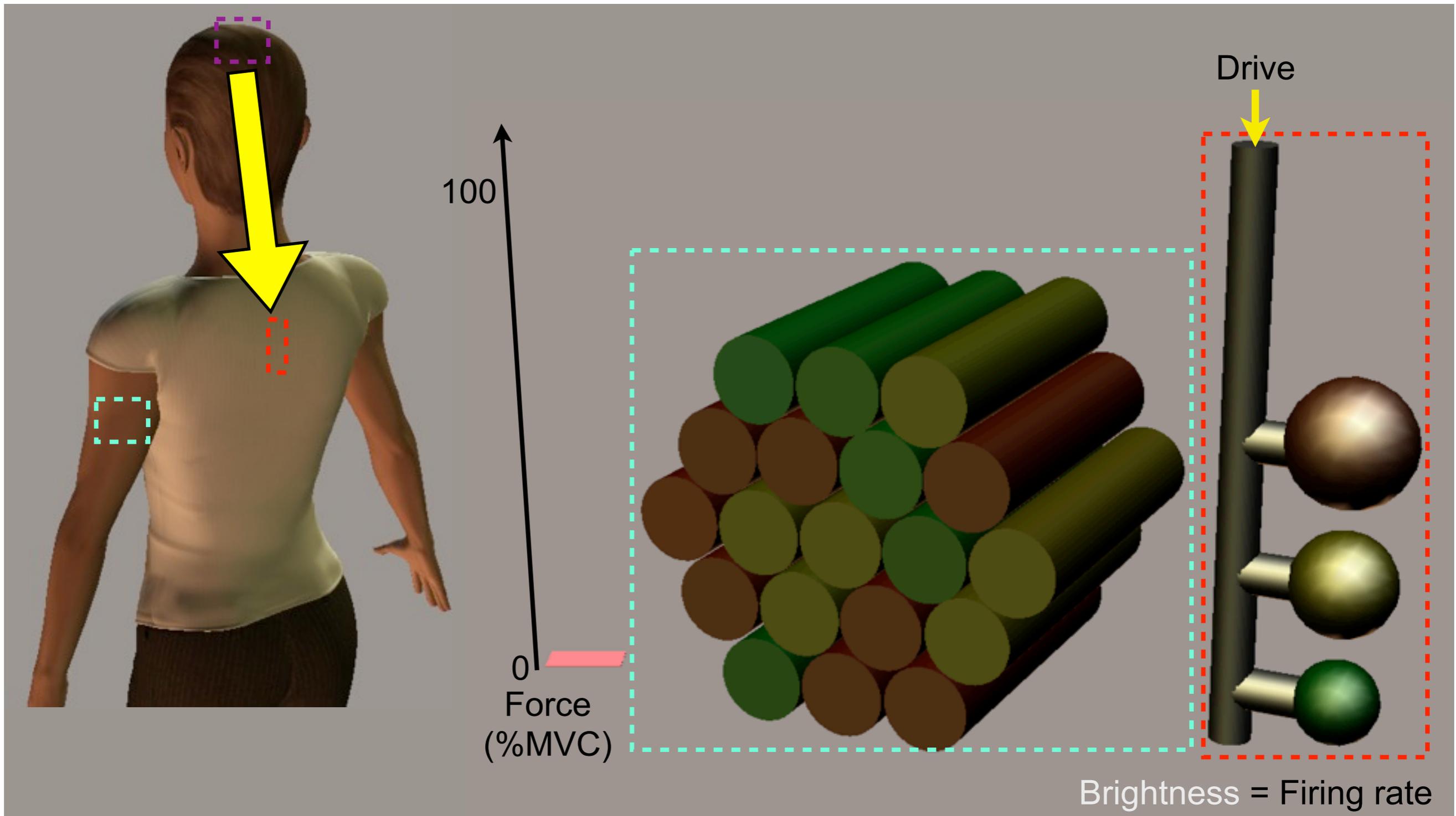
Muscle fiber = muscle cell.
Motor unit = group of muscle fibers.



Motor unit redundancy

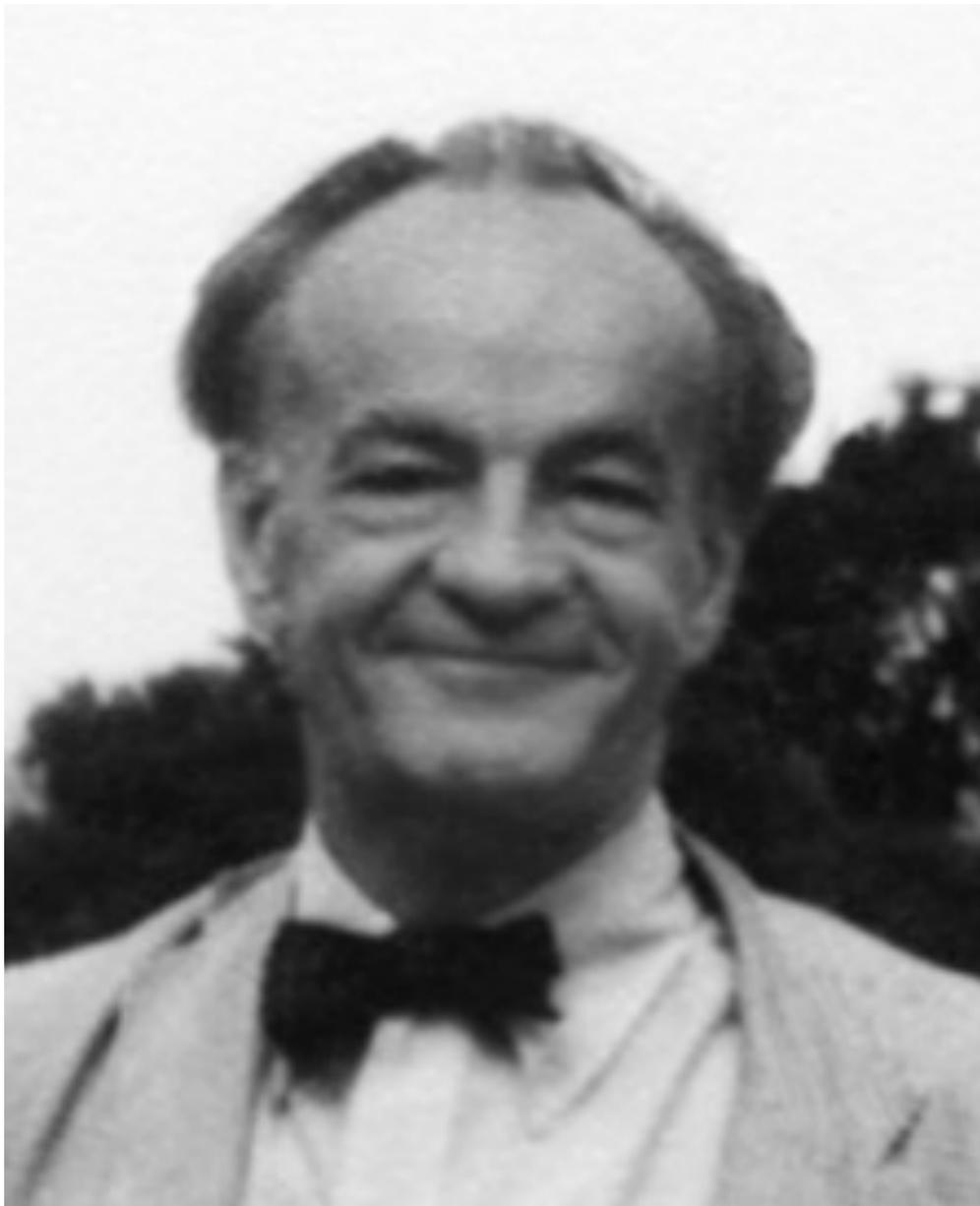


Motor units are sequentially activated

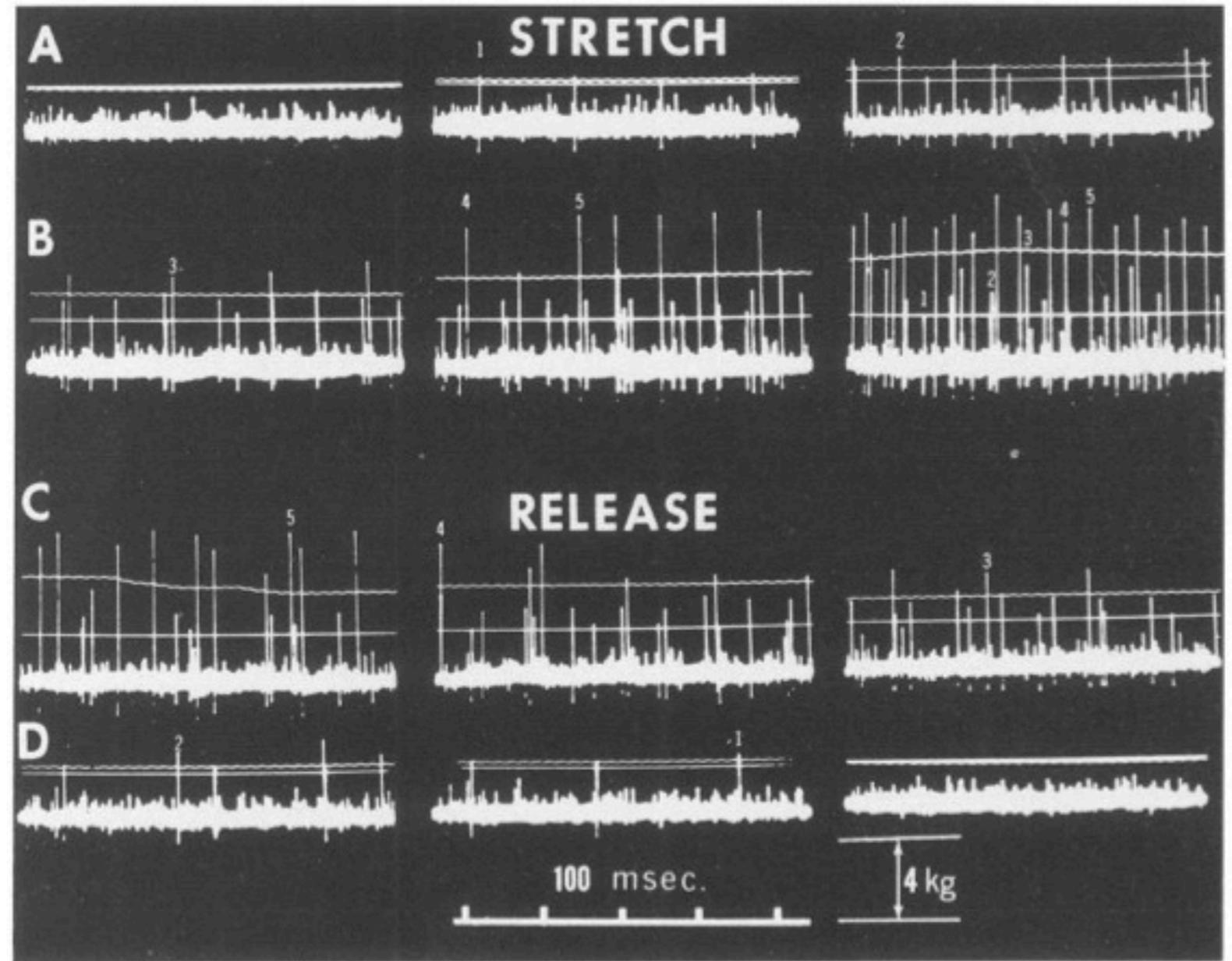


Motor unit redundancy

Elwood Henneman (1915-1996)

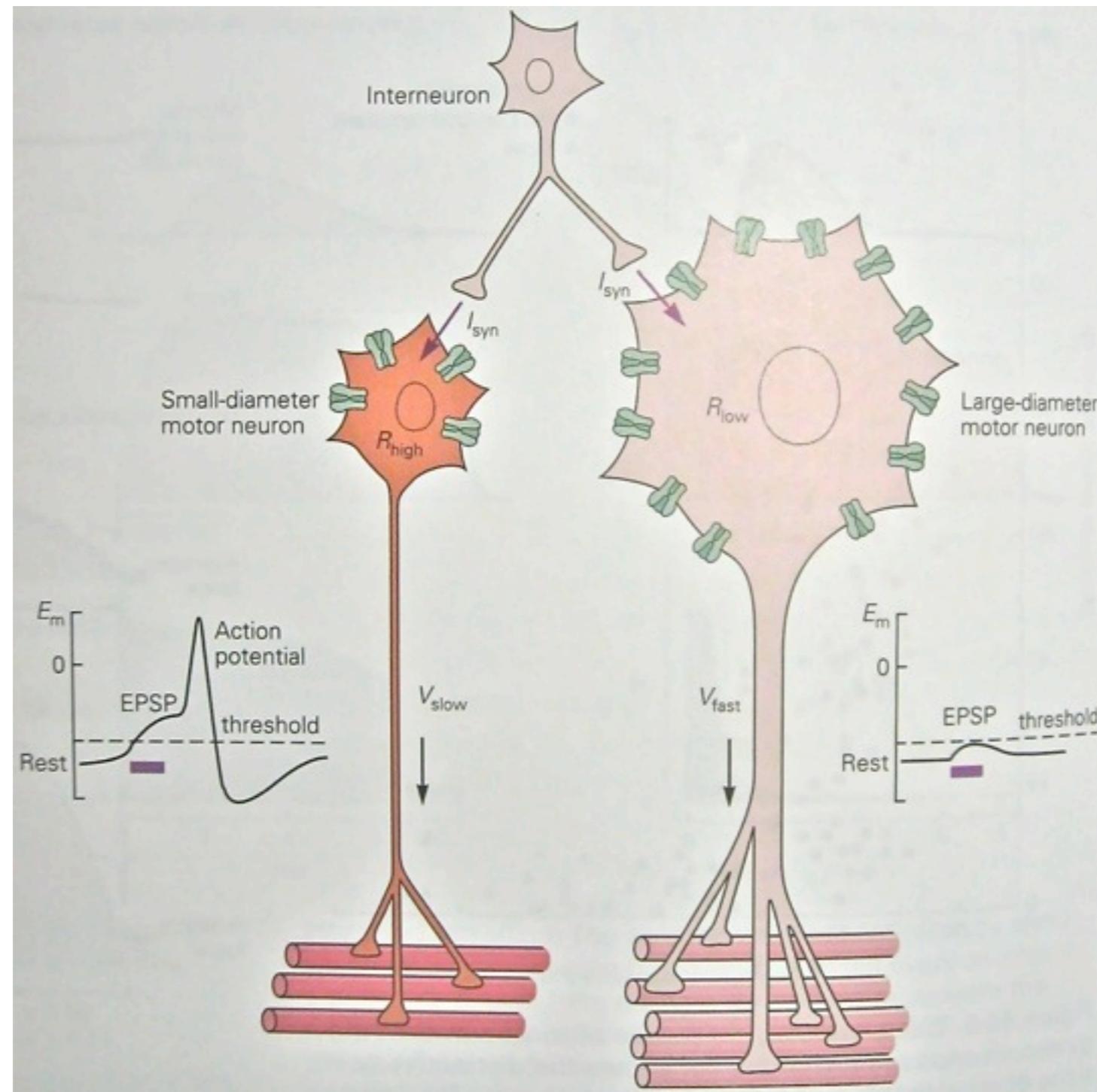


from Mendell, 2005



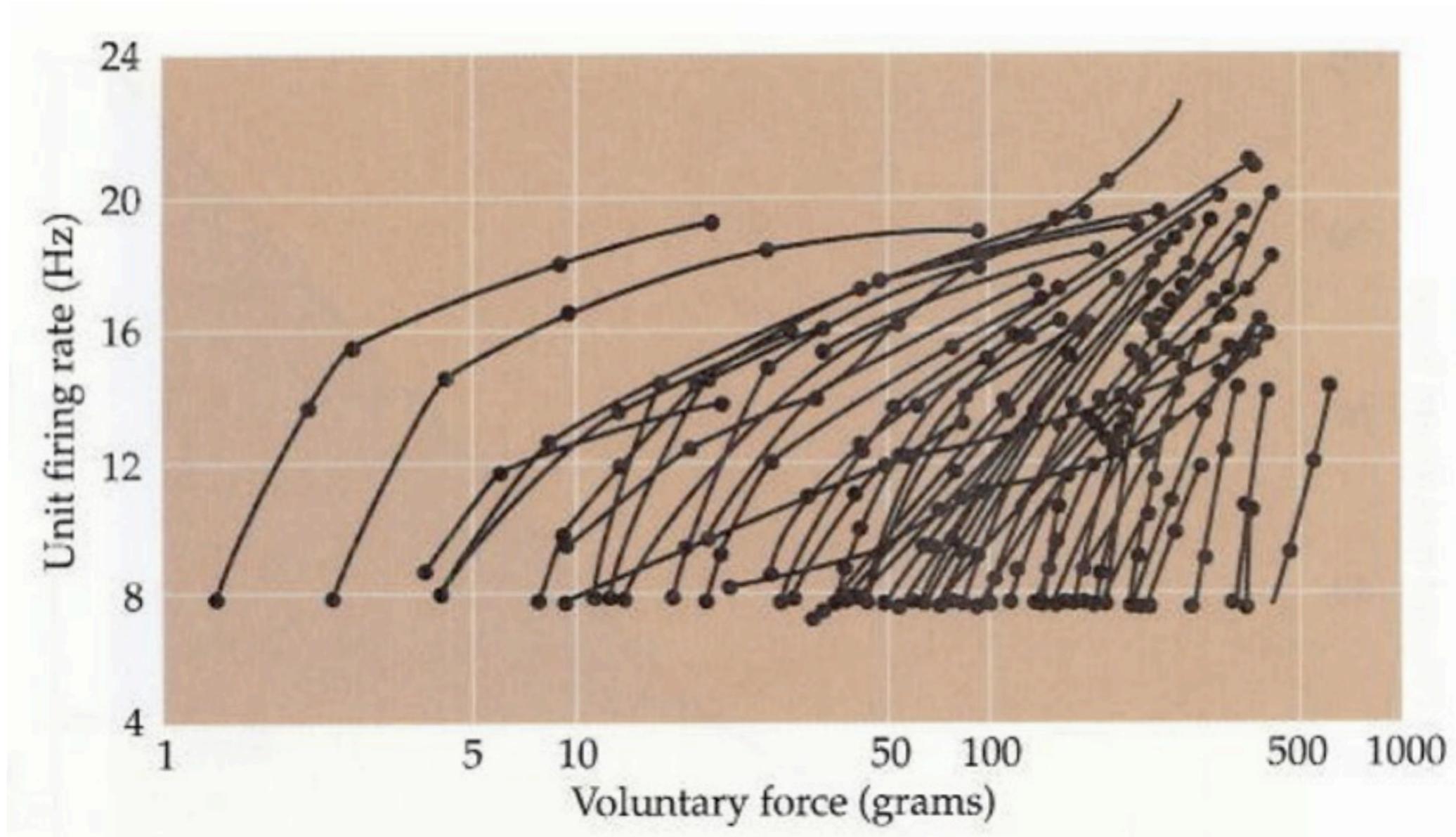
Henneman et al., 1965

Model of motor unit recruitment.



from Kandel, Schwartz, and Jessell, 4th ed.

Motor unit redundancy

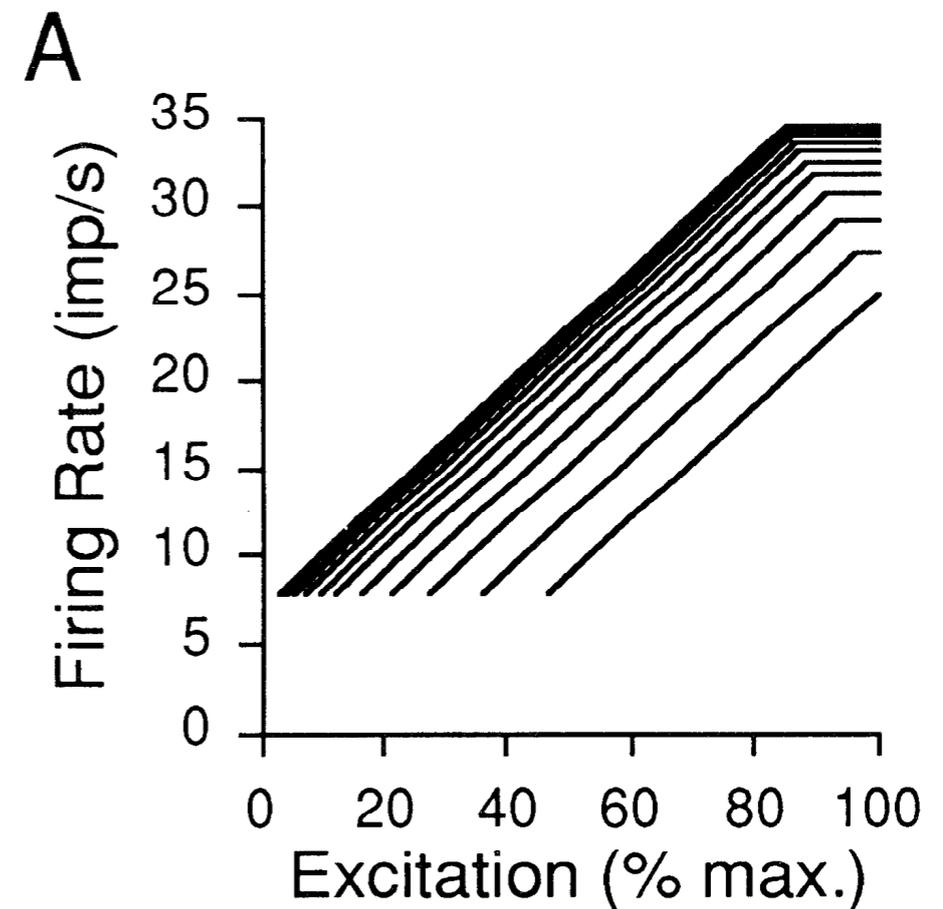
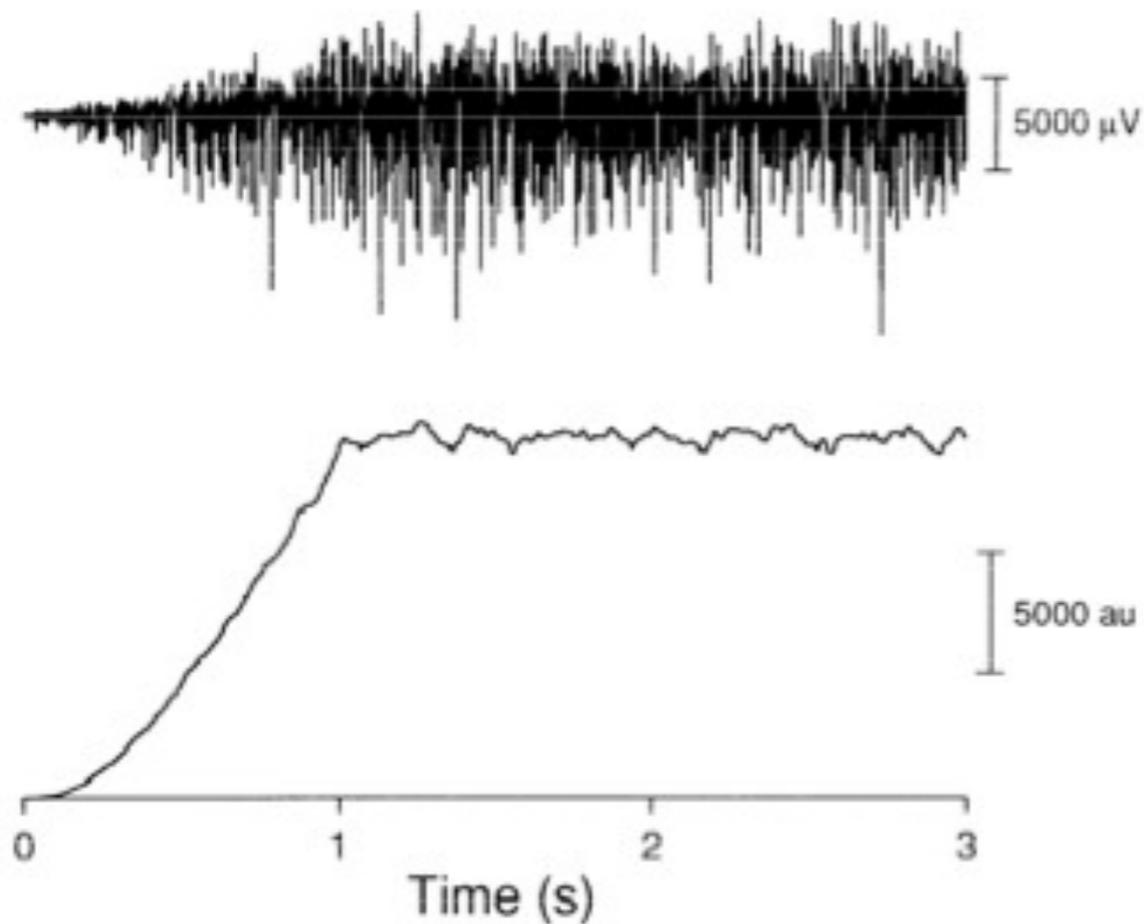


Motor unit redundancy



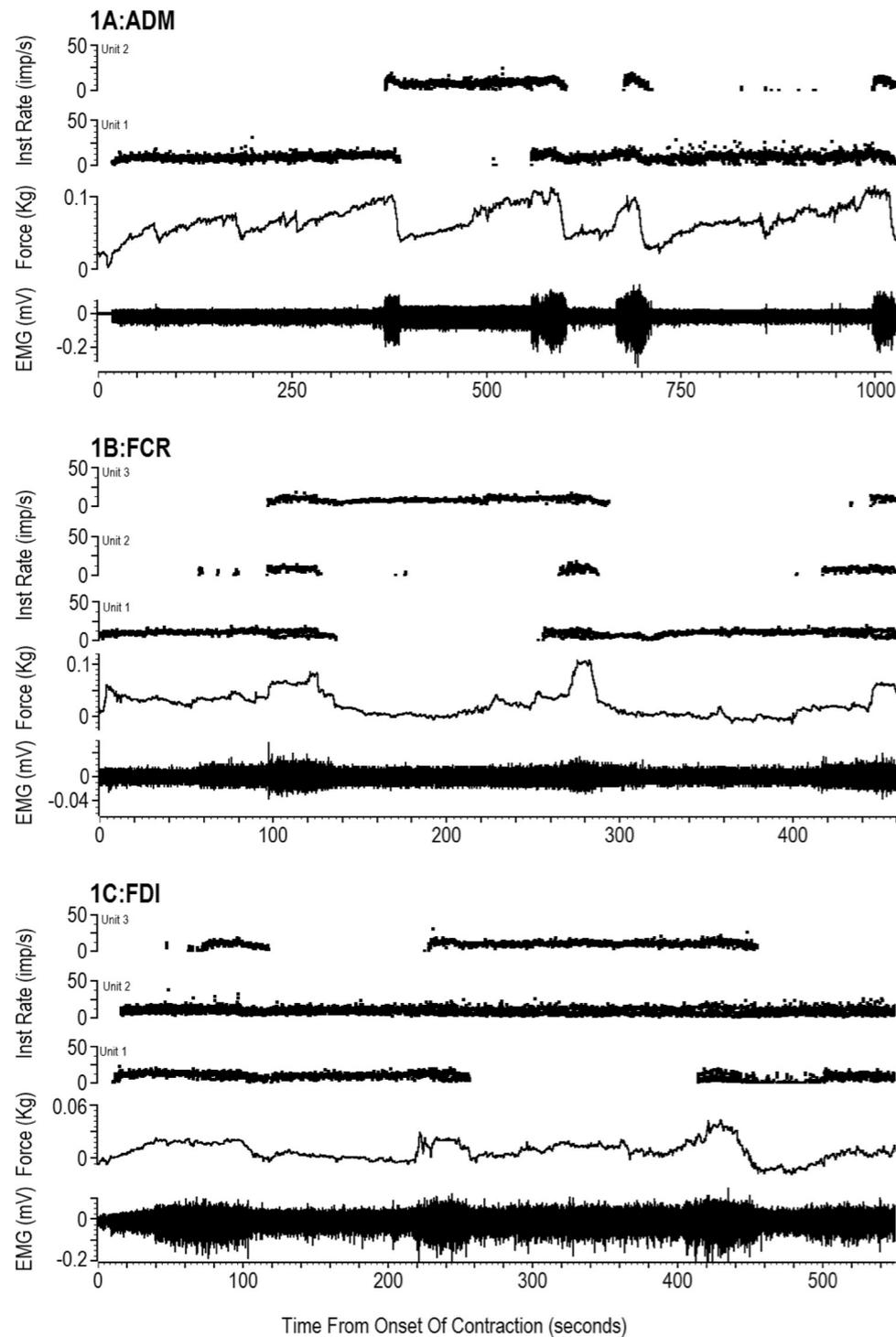
Ordered recruitment is built-in

$$FR_i(t) = g_e \cdot [E(t) - RTE_i] + MFR \quad E(t) \geq RTE_i$$

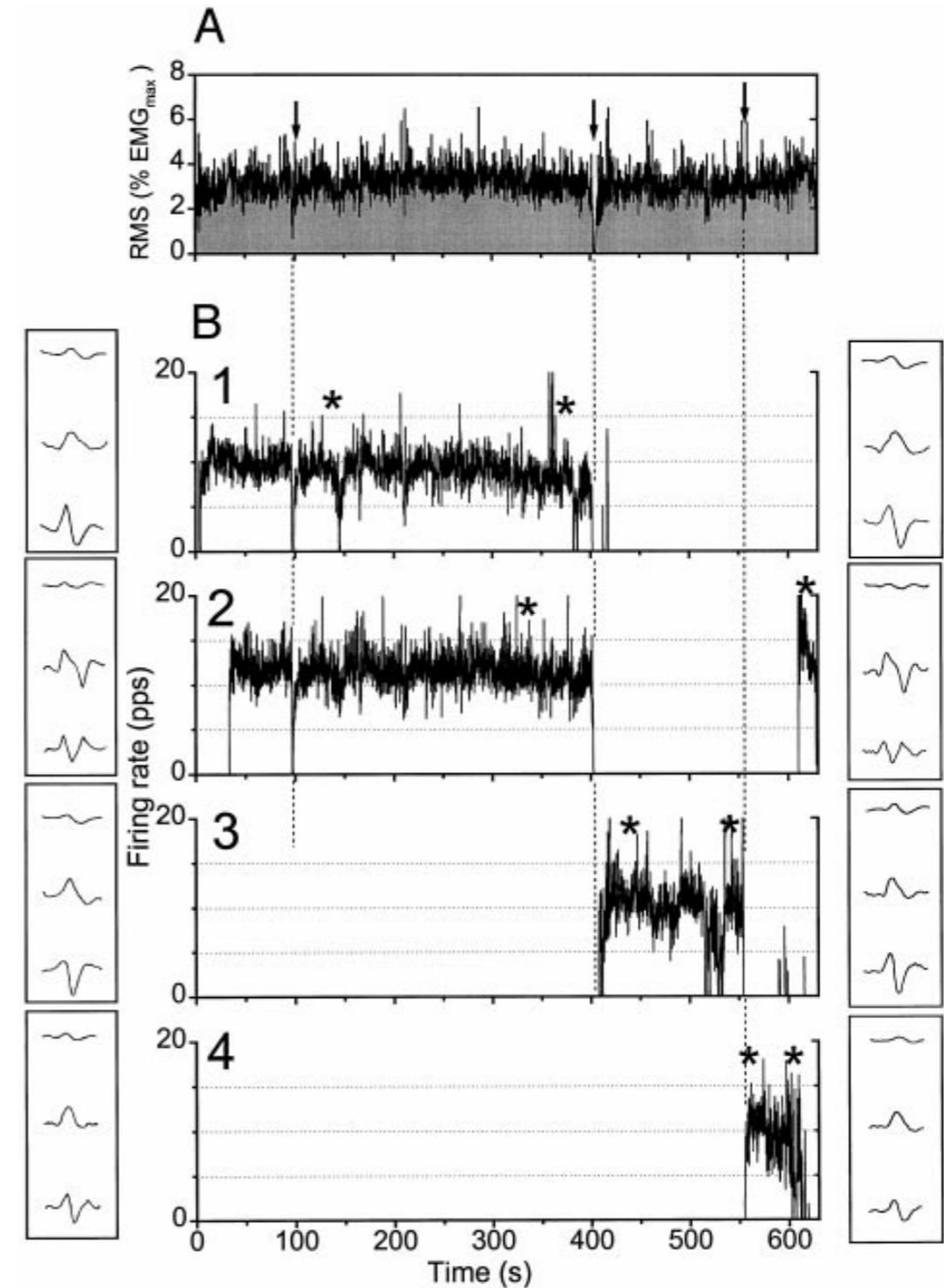


Fuglevand Model of Motor Unit Recruitment

Motor unit trade off during long contractions

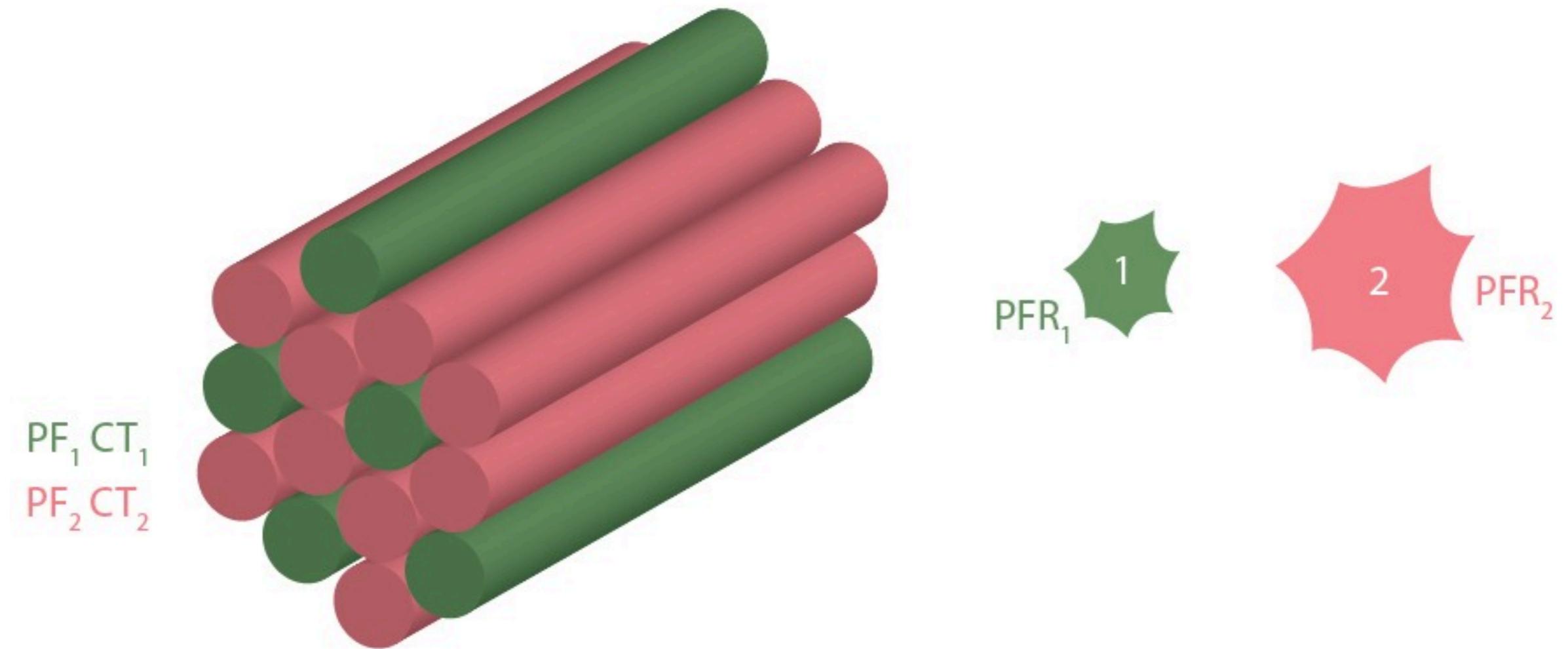


Bawa and Murnaghan, 2009

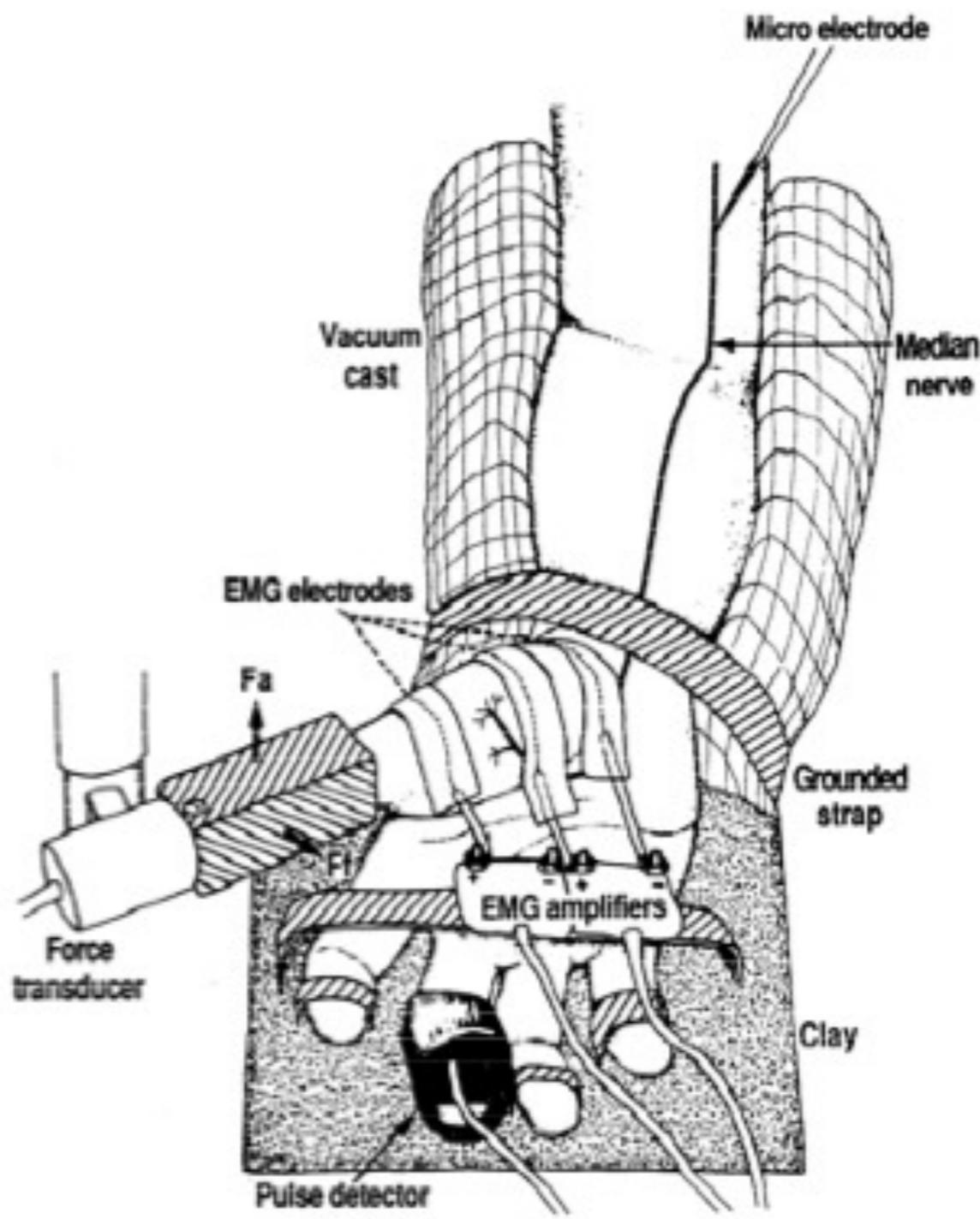


Westgaard and De Luca, 1999

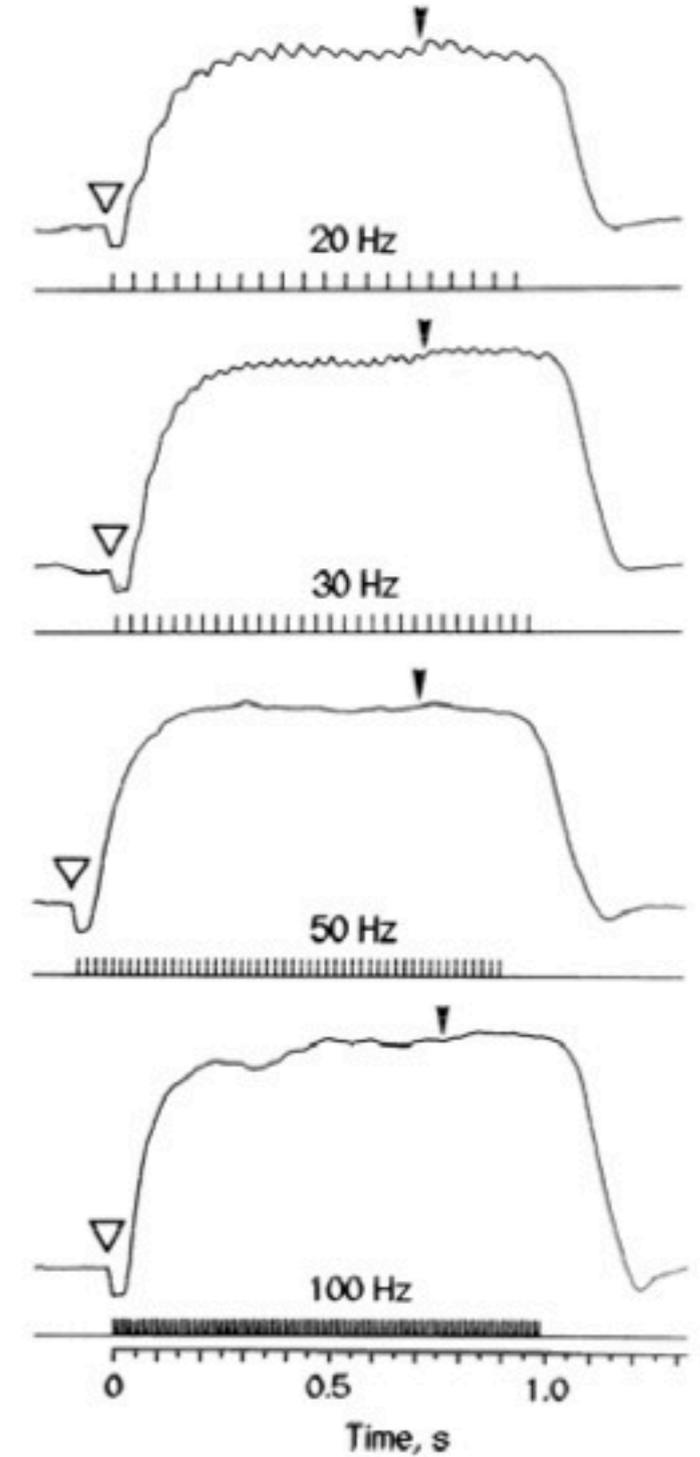
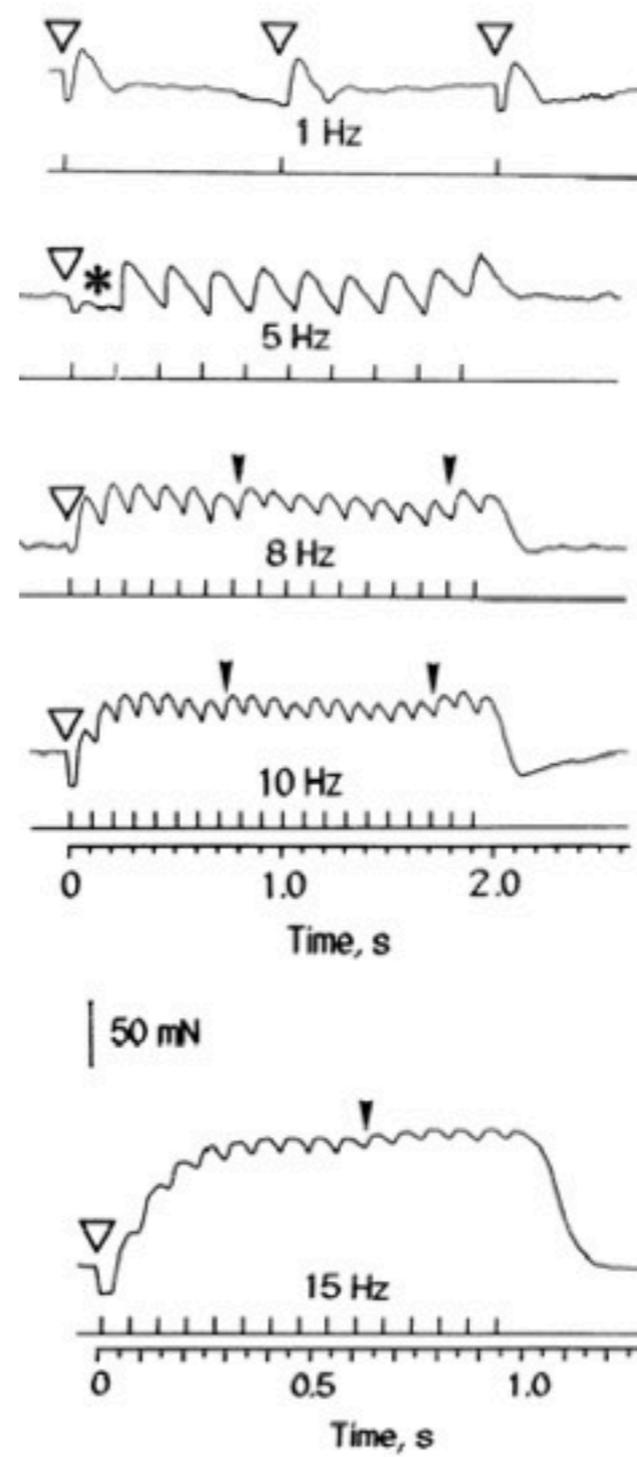
Computationally describing the motor unit pool requires mechanical and neural parameters



Motor unit redundancy

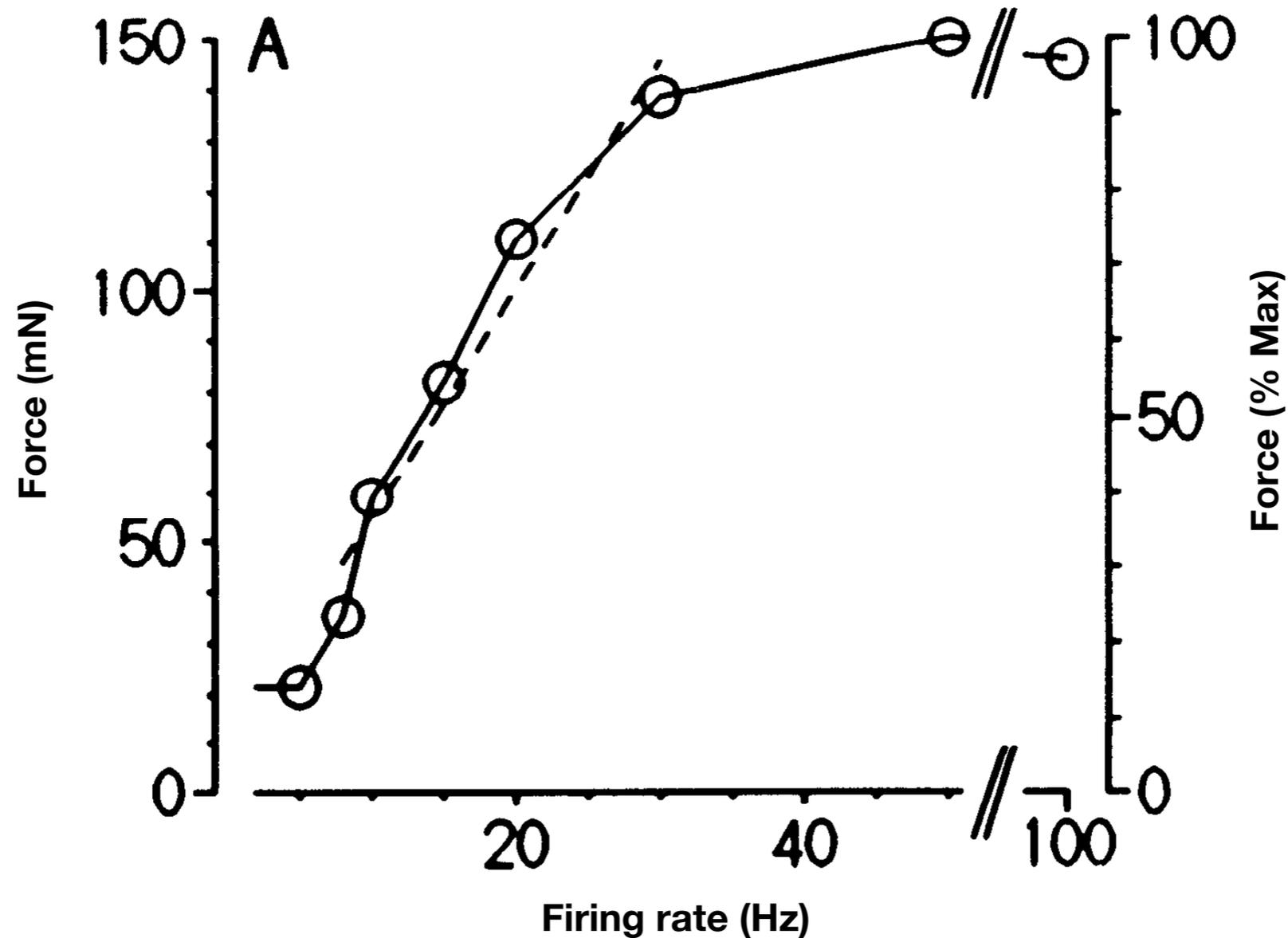


Westling et al. 1990

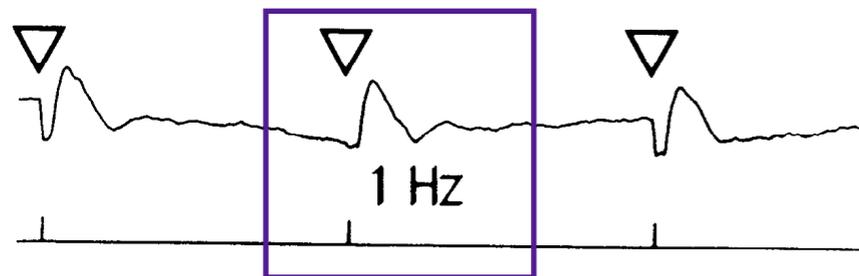


Thomas et al. 1991

Motor unit redundancy



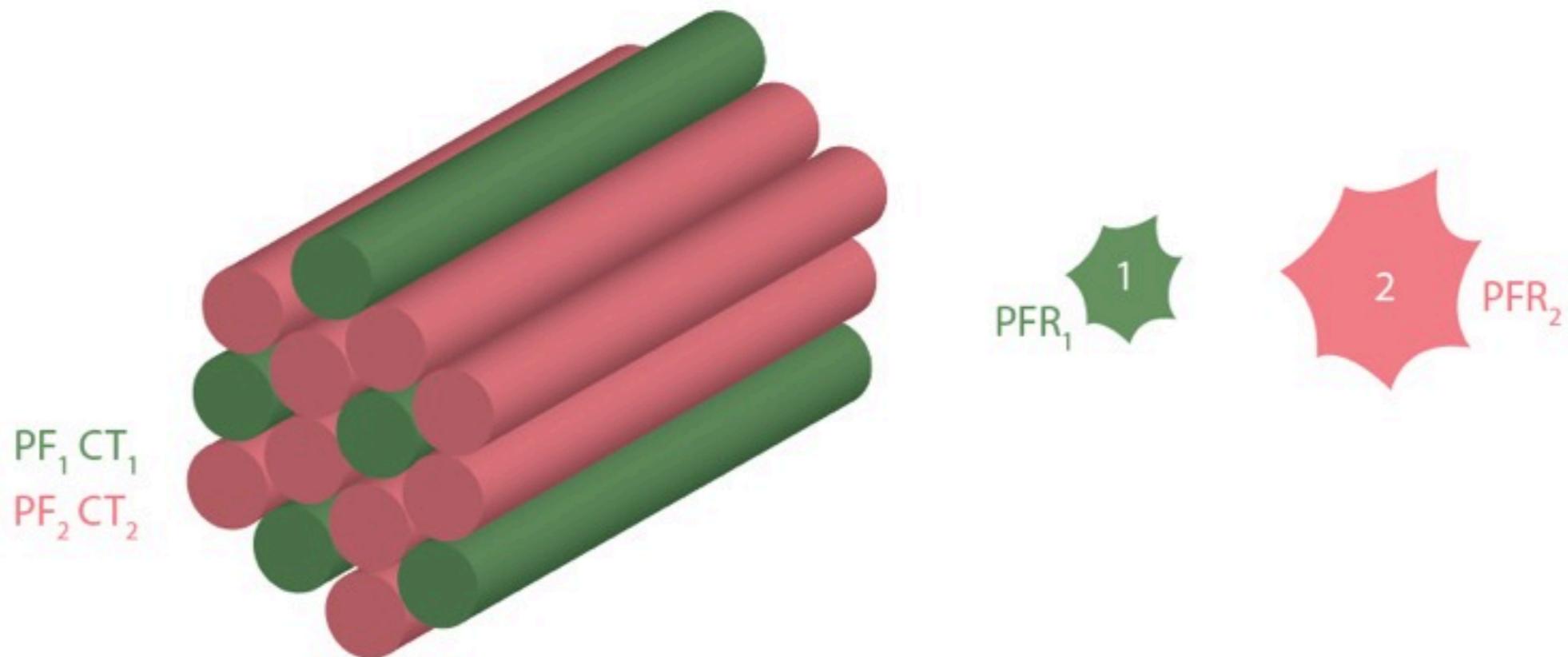
Thomas et al., 1991



$$T(t) = \frac{eP}{C} t e^{-t/C}$$

$$F_{ss} = ePCf$$

Unlike optimizing muscle use,
optimizing motor unit use is MINLP (NP hard)



Minimize Energy Expenditure over variables f and a , subject to

$$eP_1C_1f_1a_1 + eP_2C_2f_2a_2 + \dots + eP_nC_nf_na_n = F_d$$

$$f_i < PFR_i$$

a_i is either 0 or 1

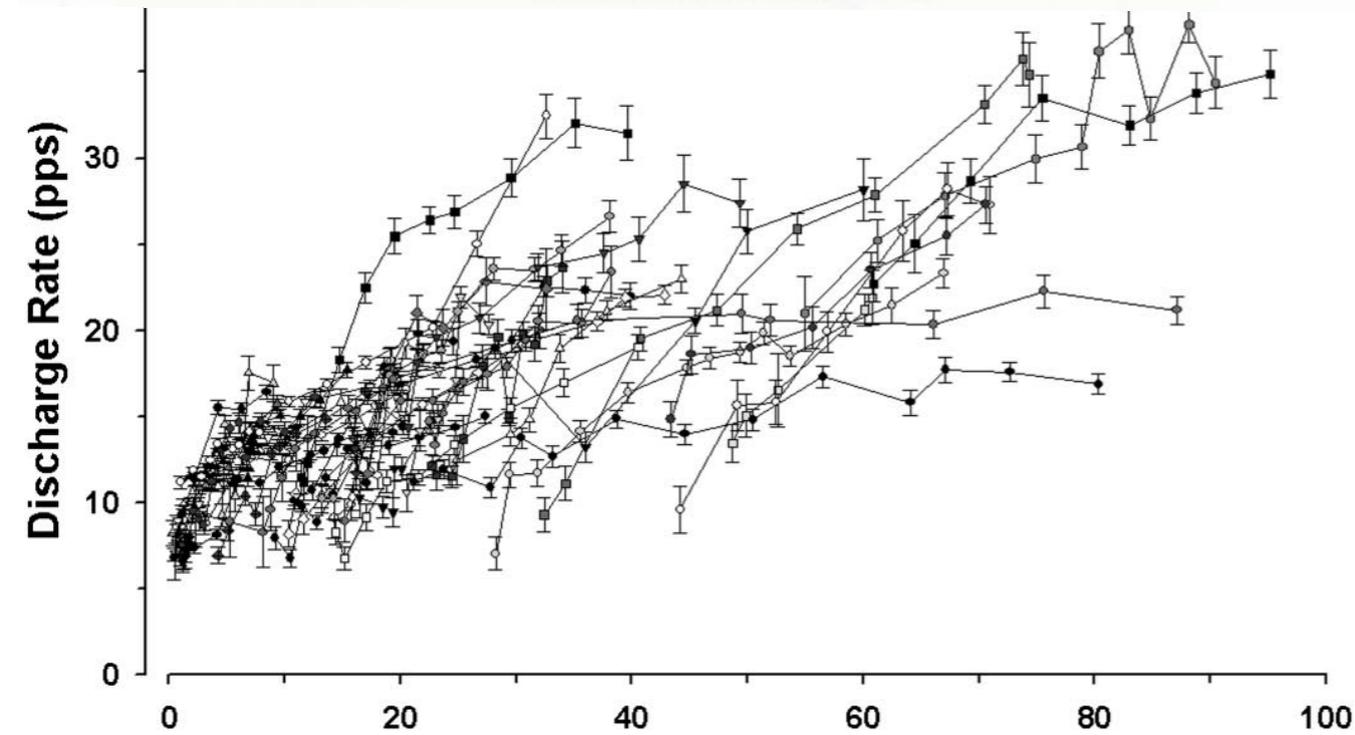
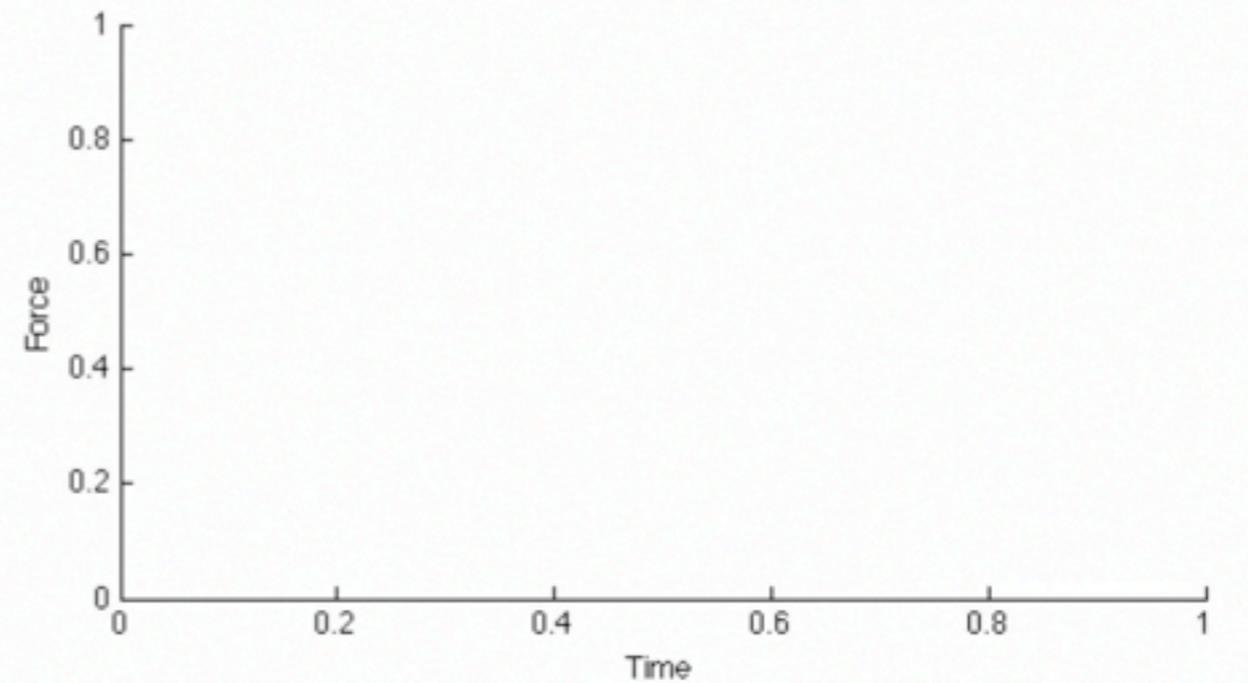
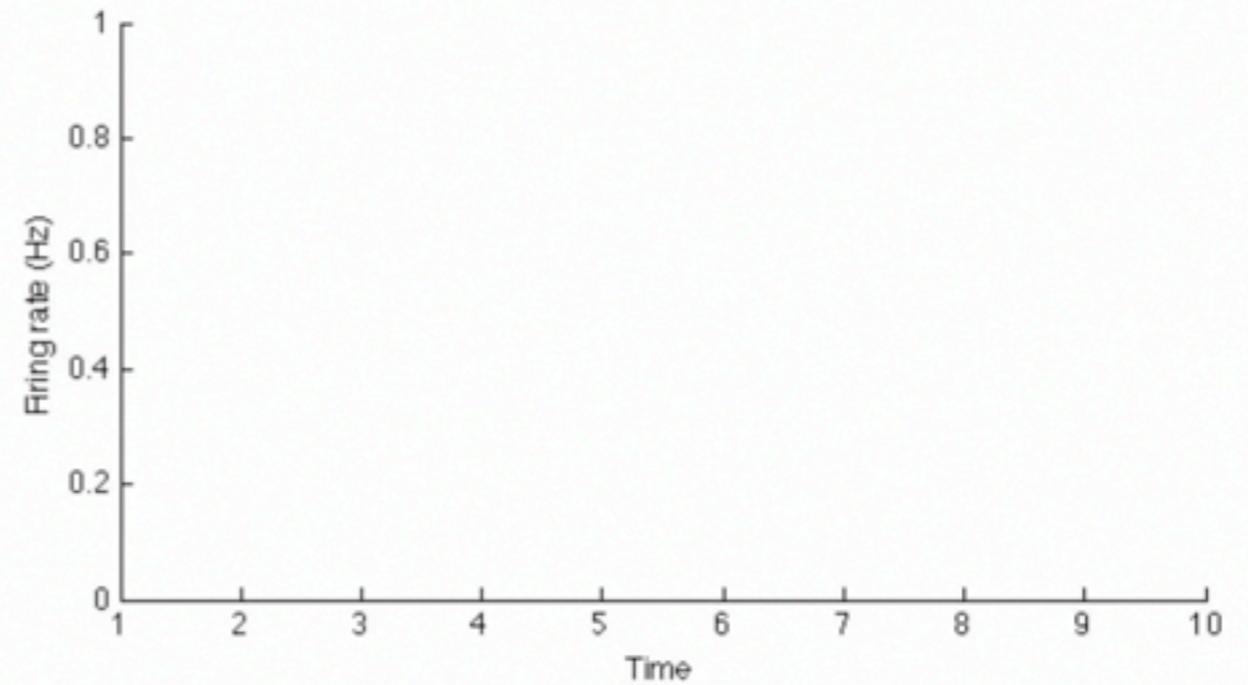
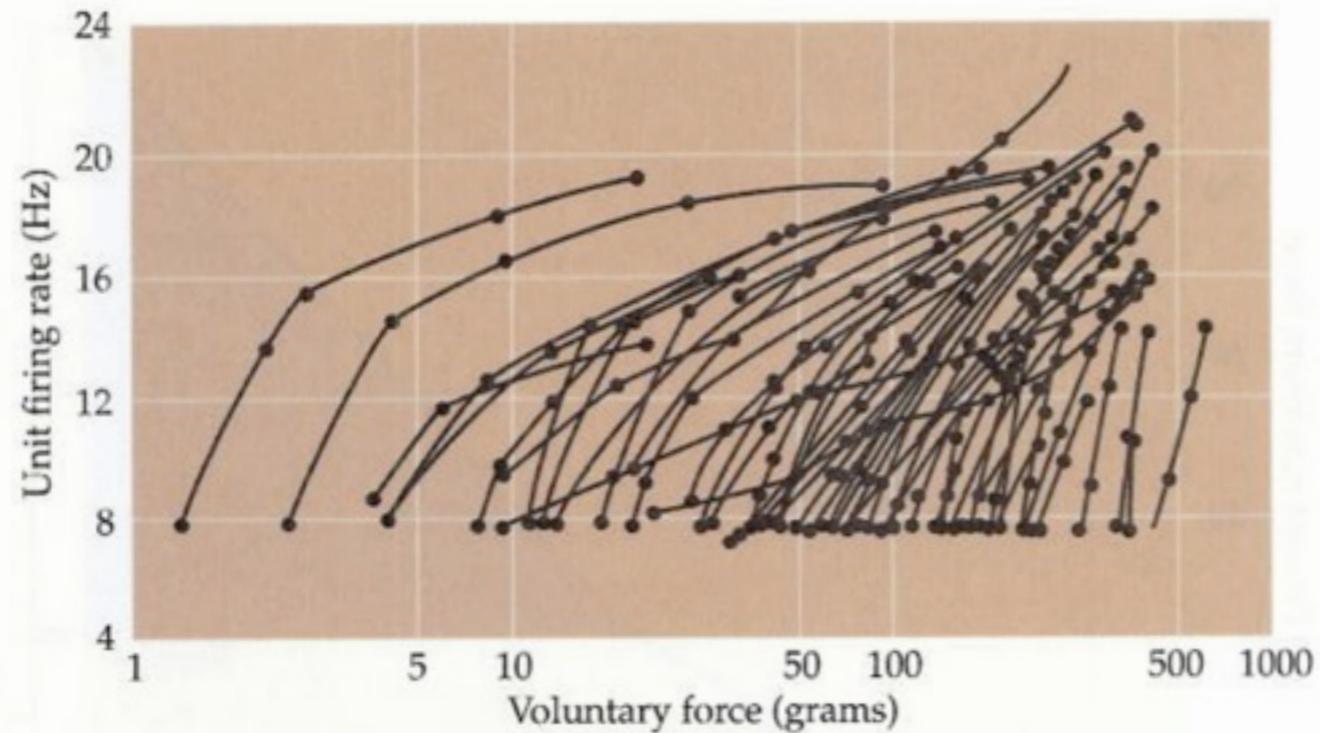
Mixed integer

nonlinear optimization (MINLP)

MINLP Model of Motor Unit Recruitment

Motor unit redundancy

MINLP solution



Monster and Chan, 1977, in Purves et al.

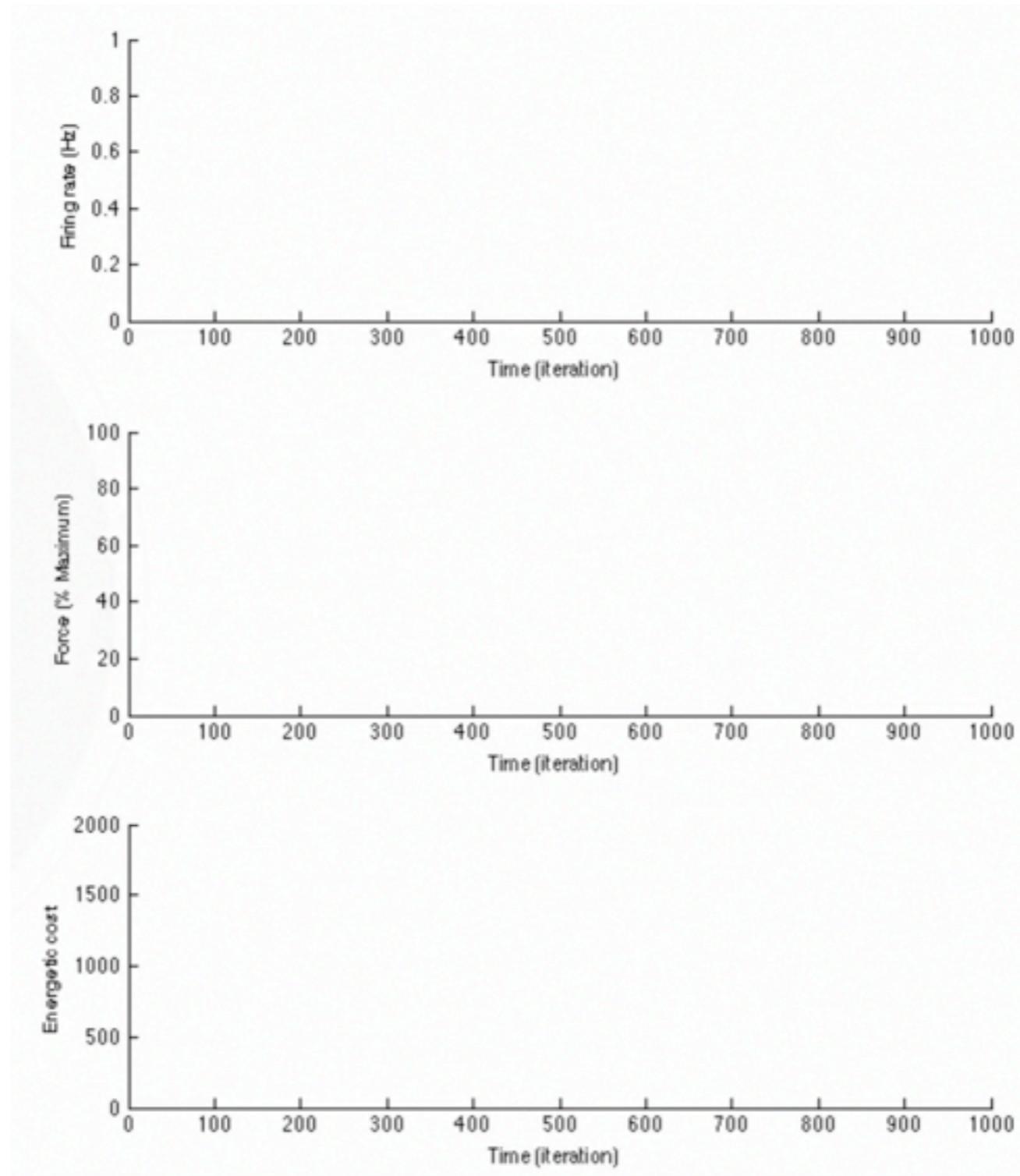
Moritz et al., 2005

Motor unit rotation: depletion recharge model

1. If motor unit active, peak firing rate decays
2. If motor unit is off, peak firing rate recovers
3. When peak firing rate passes a threshold, motor unit is ready to go again

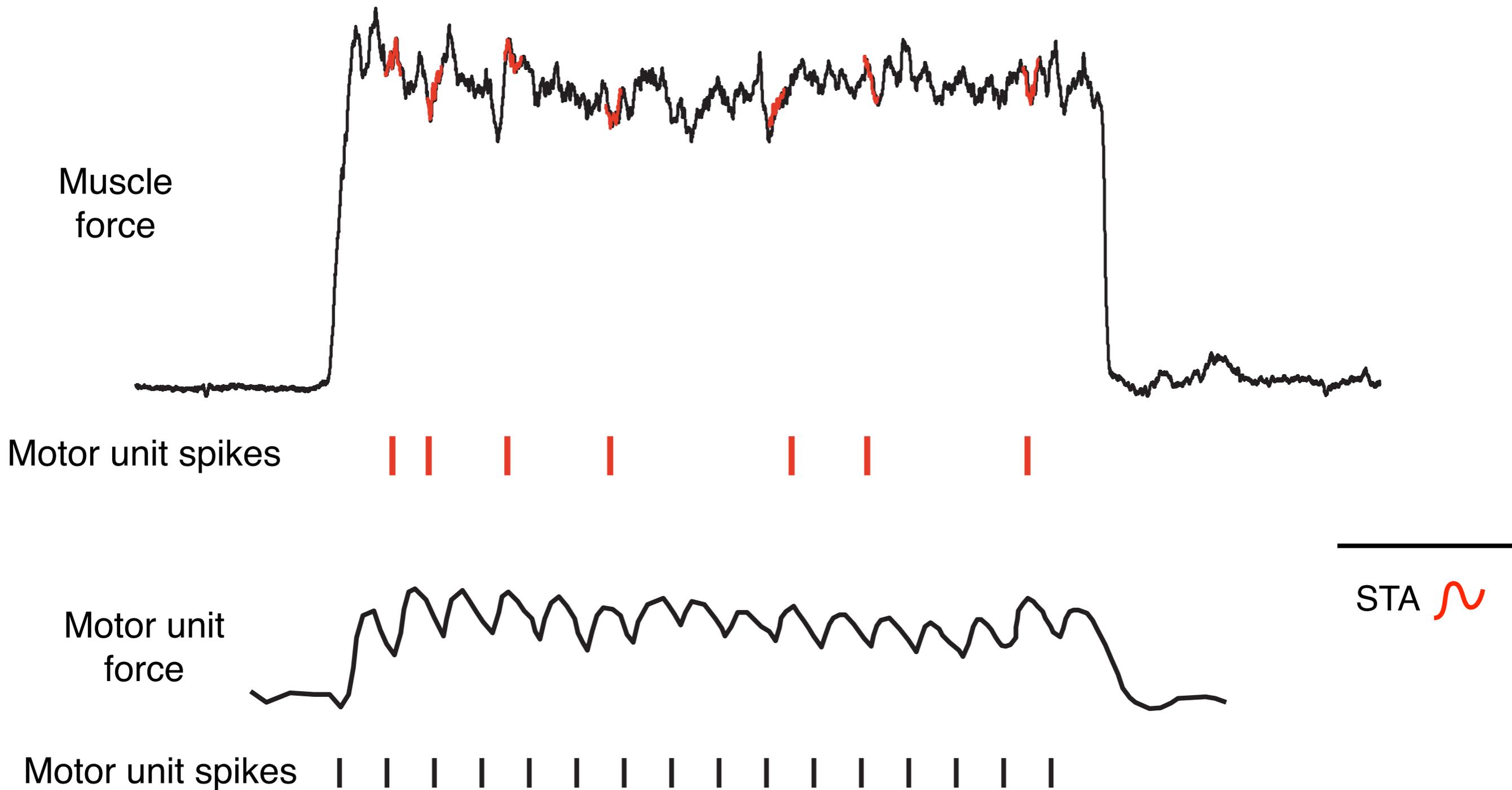
MINLP Model of Motor Unit Rotation

Simulated motor unit rotation: 5% maximum



Motor unit redundancy

Spike triggered averaging: information from “noise”

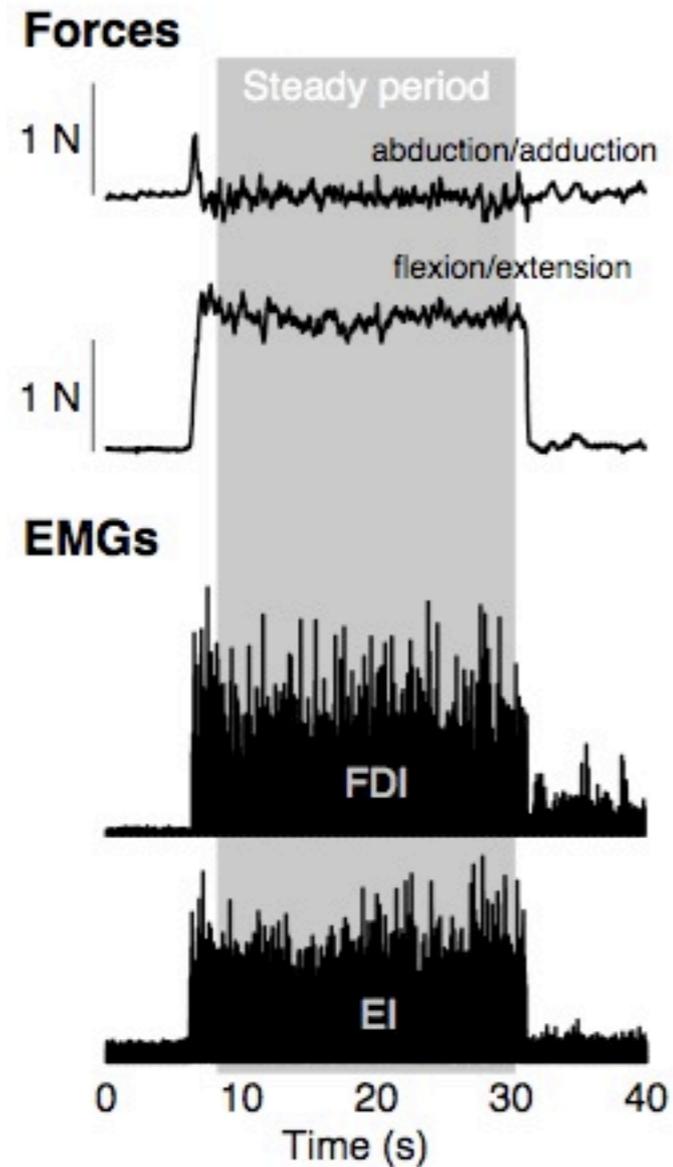


Stein et al., 1972

Kutch et al., 2007

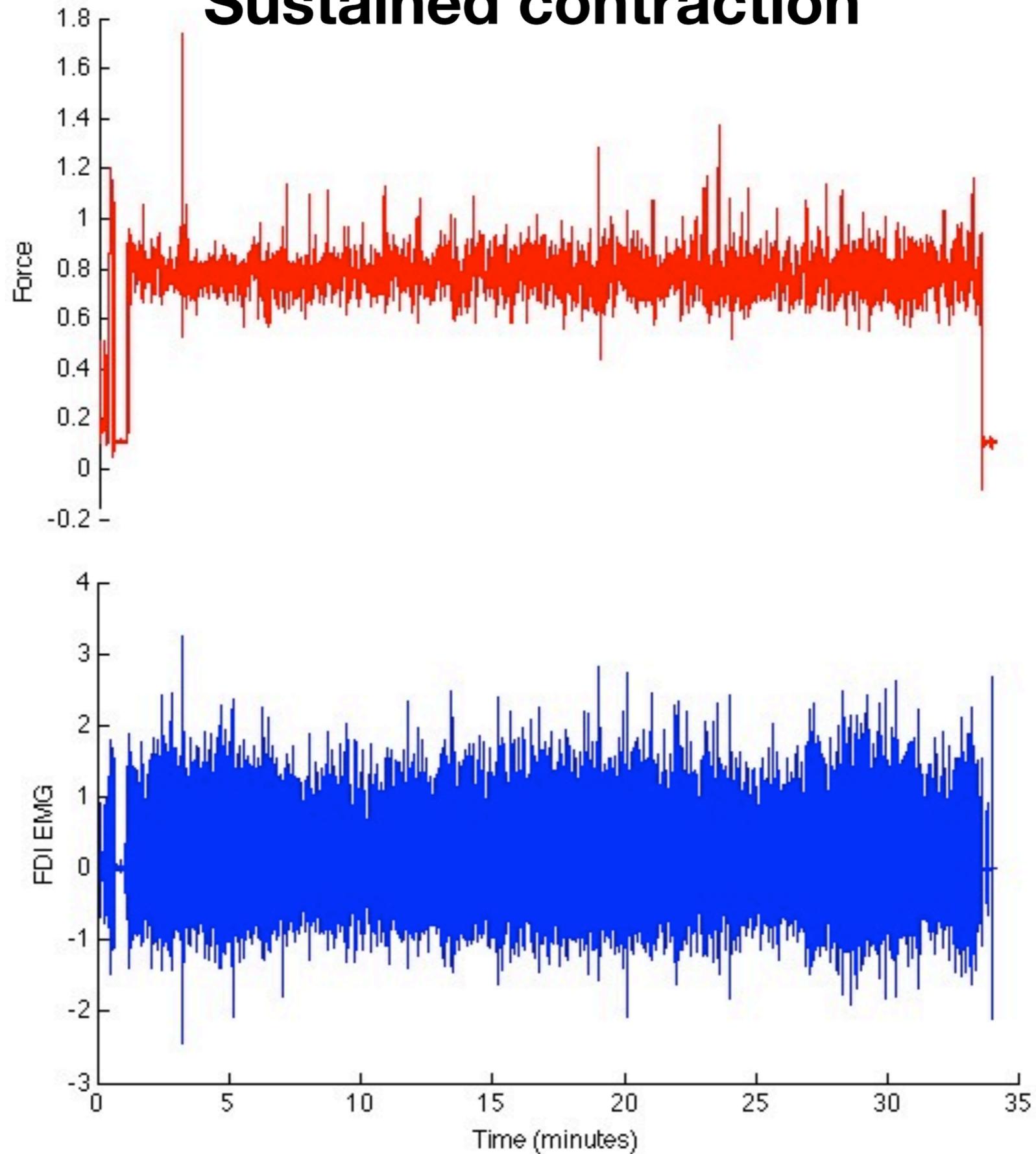
EMG-weighted averaging (EWA)

A. Time domain data



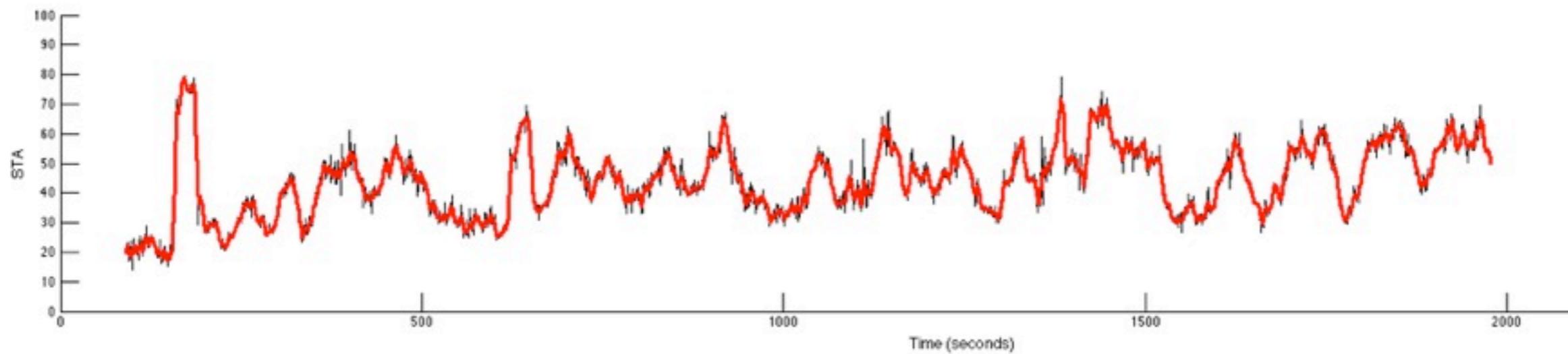
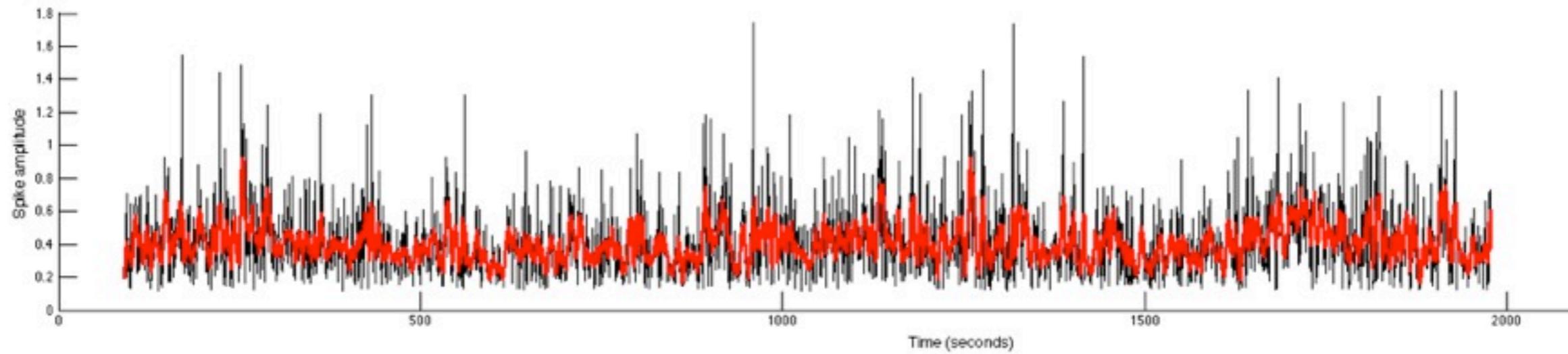
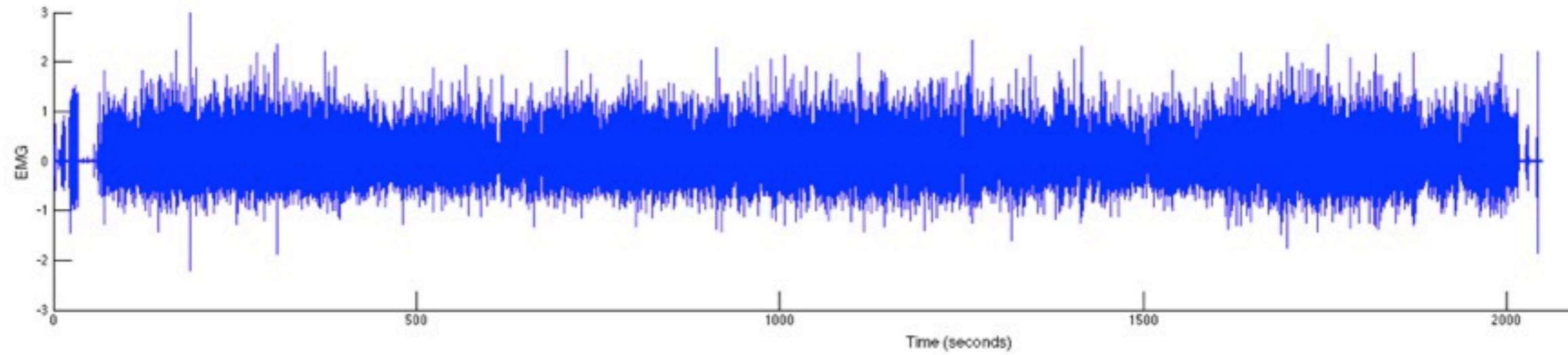
Motor unit redundancy

Sustained contraction



Motor unit redundancy

Evidence of motor unit rotation



Fuglevand Model of Spike-triggered Averaging

- 1. Understanding and better treating chronic pain is essential. Problem of brain-body interaction?**
- 2. Examples of subconscious peripheral activity oscillations from *muscle redundancy***
- 3. Examples of subconscious peripheral activity oscillations from *motor unit redundancy***
- 4. Utility of doing experiments but thinking about them using simple models.**

Thank you